Towards a consistent model of the hot quadruple system HD 93206 = QZ Carinæ: II. N-body model* **

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ABSTRACT

Aims. HD 93206 is a massive early-type stellar system composed of components resolved by direct imaging (Ab, Ad, B, C, D) and a compact subsystem (Aa1, Aa2, Ac1, Ac2). Its geometry was already determined on the basis of extensive photometric, spectroscopic, and interferometric observations. However, the fundamental absolute parameters are still not known precisely enough.

Methods. We use an advanced N-body model to account for all mutual gravitational perturbations among the four close components, and all observational data types, including astrometry, radial velocities, eclipse timing variations, squared visibilities, closure phases, triple products, normalized spectra, and spectral energy distribution (SED). The model has 38 free parameters, grouped into three sets of orbital elements, component masses, and their basic radiative properties (T, log g, v mac).

Results. We revised the fundamental parameters of QZ Car as follows. For a model with the nominal extinction coefficient RV = A V /E(B−V) = 3.1, the best-fit masses are m1 = 26.1 M⊙, m2 = 32.3 M⊙, m3 = 70.3 M⊙, and m4 = 8.8 M⊙, with uncertainties of the order of 2 M⊙, and the system distance d = (2800 ± 100) pc. In an alternative model, we increased the weights of the radial velocity (RV) and transit timing variation (VTT) observations and relaxed the SED constraints, because extinction can be anomalous with RV < 3.4, the distance is smaller; d = (2450 ± 100) pc. This corresponds to the distance of the Collinder 228 cluster. Independently, this is confirmed by dereddening the SED, which is only then consistent with the early-type classification (O9.7Ib for Aa1, O8III for Ac1). Future modelling should also account for an accretion disk around the Ac2 component.


1. Introduction

HD 93206 is a complex system composed of nine components (usually denoted Aa1, Aa2, Ac1, Ac2, Ab, Ad, B, C, D). In the accompanying paper (Mayer et al. 2022) we used several observation-specific models to obtain the fundamental parameters of its subsystems, in particular the eclipsing binary Ac1+Ac2, the spectroscopic binary Aa1+Aa2, and their mutual long-period orbit (Aa1+Aa2)+(Ac1+Ac2). Together, the quadruple subsystem is called the QZ Car variable star. All these models were kinematically; they were based on the two-body problem with the light-time effect and the third light, to account at least for major perturbations.

In this work we focus on the same quadruple subsystem QZ Car, but we use a dynamical N-body model called Xiτau to account for additional perturbations (in particular, all mutual, parametrized, post-Newtonian). Moreover, we account for all observational datasets at the same time, including astrometry, photometry, spectroscopy, and interferometry. This approach allows us to derive robust estimates of fundamental parameters.

* Dedicated to the memory of Dr. Pavel Mayer.
** Based on observations made with ESO Telescopes under programmes 098.D-0706(B), 099.D-0777(B).

1 http://sirrah.troja.mff.cuni.cz/~mira/kitau/
Our model was already used for multiple stellar systems (e.g. \(\xi\) Tau, Nemravová et al. 2016; Brož 2017) and asteroidal moon systems with highly irregular central bodies (e.g. (216), Marchis et al. 2021; Brož et al. 2021a, 2022).

2. Observational datasets

The radial velocity measurements, relative spectroscopy, light curves and corresponding eclipse-time variations (ETVs), and astrometry are already described in Mayer et al. (2022). Here we focus on additional datasets, namely the spectral energy distribution (SED) and interferometry.

2.1. Spectral energy distribution

We used data from Vizier, which includes the standard Johnson system photometry (Ducati 2002), verified by the La Silla and Sutherland photometry (see Mayer et al. 2022), Hipparcos (Anderson & Francis 2012), GAIA3 (Gaia Collaboration 2020), 2MASS (Cutri et al. 2003), WISE (Cutri & et al. 2012), MSX (Egan et al. 2003), and Akari (Ishihara et al. 2010). Altogether, the whole spectral range is 0.35 to 22 \(\mu\)m.

It was necessary to carry out the dereddening of these data. Unfortunately, the classic extinction maps of Green et al. (2019) give unrealistic absorption, and a special treatment is needed for QZ Car, which is too close to the galactic equator. To this end, we used the extinction maps of Lallement et al. (2019). For the assumed distance 2870 pc (Shull & Danforth 2019), the reddening extrapolated from 2100 pc is \(E(B-V) = 0.470 \pm 0.060\) mag, and corresponding absorption \(A_V = 3.1 E(B-V) = 1.46 \pm 0.19\) mag (Fig. 1). Using the standard wavelength dependence of Schlafly & Finkbeiner (2011), we obtained the deredduced fluxes shown in Fig. 2.

Not surprisingly, the corrected fluxes exhibit a power-law slope, which corresponds to the Planck function \((B_\lambda \propto \lambda^{-4}\) for \(\lambda > 0.35\) \(\mu\)m), for the effective temperature \(T \approx 30000\) K. This is in agreement with the early-type spectral classification of QZ Car. Using a significantly smaller distance (e.g. 2000 pc) would result in a SED that does not correspond to early-type stars. We show in Section 3 that this distance and dereddening are indeed reliable. On the other hand, in the far-infrared (\(>2.2\) \(\mu\)m), where absorption is already negligible, a non-negligible excess is present. The monochromatic fluxes are a factor of 5 too large, possibly indicating cold circumstellar matter or blending, neither of which is accounted for in our modelling. Consequently, we should preferably fit the near-ultraviolet to near-infrared (NUV-NIR) spectral range.

2.2. Interferometry

In addition to the Sanchez-Bermudez et al. (2017) astrometric data, for the epochs June 17, 2016, and June 18, 2016, we used interferometric observations with the VLTI/GRAVITY instrument located in the ESO archive for the epochs March 14, 2017 and April 27, 2017. This is an important constraint for the (Ac1+Ac2)+(Aa1+Aa2) orbit. Apart from astrometry, we can directly include squared visibilities \(V^2\), closure phases \(\sigma_{uv}\), and triple product amplitudes \(F_3\) in \(X\) i\(tau\).

We used the Esorex VLTI/GRAVITY pipeline (Freudling et al. 2013; Gravity Collaboration et al. 2017) to reduce the data. We performed the standard visibility calibration, which is substantial (0.2) for baselines \(\geq 4.5 \times 10^3\) cycles per baseline. We used the so-called ‘v-factor’ for the correction of \(V^2\). We did not use data with \(V^2 + \sigma_{uv}^2 > 1.0\). The new \((u,v)\) coverage is shown in Fig. 3. The wide orbit ((Ac1+Ac2)+(Aa1+Aa2)), having the angular separation more than 30 mas, is clearly resolved. On the other hand, angular diameters of individual components (0.015 to 0.08 mas) cannot be resolved. As we discuss in Section 3, there were some problems with the \(F_3\) calibration. Consequently, we also tried to reduce the data without ‘v-factor’.

As a check, we performed astrometry with the Litpro software (Tallon-Bosc et al. 2008). A simplified model of a binary (Aa+Ac) was assumed. We fitted \((u,v)\) coordinates of Aa and the flux ratio \(F_{Aa}/F_{Ac}\); other parameters were kept fixed. Even though there are some systematics, the fit converges without problems and the astrometric uncertainties are comparable to previous measurements (\(\sigma_{uv} \approx 0.010\) mas; Table 1).

We used no light curves in our modelling (only indirectly as ETVs). To our knowledge, there are no sufficiently high signal-to-noise ratio differential interferometric measurements (cf. Sanchez-Bermudez et al. 2017), which would otherwise constrain velocity-dependent visibilities across spectral lines.

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2 In \(X\) i\(tau\), the (Ac1+Ac2) eclipsing binary is located in the centre, hence we use negative signs of \((u,v)\) for the computations.
Table 1. Astrometric positions of component (Ac1+Ac2) with respect to (Aa1+Aa2) from the literature and from new data.

<table>
<thead>
<tr>
<th>time (UTC)</th>
<th>u</th>
<th>v</th>
<th>major mas</th>
<th>minor mas</th>
<th>P.A. deg</th>
<th>$F_{\text{obs}}/F_{\text{syn}}$</th>
<th>Ref.</th>
</tr>
</thead>
<tbody>
<tr>
<td>2012:12:41</td>
<td>13.590</td>
<td>24.538</td>
<td>3.410</td>
<td>4.705</td>
<td>331.020</td>
<td>0.68 ± 0.10</td>
<td>Sana et al. (2014)</td>
</tr>
<tr>
<td>2012:12:449</td>
<td>12.367</td>
<td>22.597</td>
<td>0.540</td>
<td>0.652</td>
<td>331.310</td>
<td>0.37 ± 0.04</td>
<td>Sana et al. (2014)</td>
</tr>
<tr>
<td>2016-01-31:15:25:21</td>
<td>15.940</td>
<td>25.609</td>
<td>0.045</td>
<td>0.054</td>
<td>0</td>
<td>0.74 ± 0.14</td>
<td>Sanchez-Bermudez et al. (2017)</td>
</tr>
<tr>
<td>2017-03-14T03:34:17</td>
<td>16.370</td>
<td>25.672</td>
<td>0.003</td>
<td>0.003</td>
<td>0</td>
<td>0.490 ± 0.001</td>
<td>ESO archive 099.D-0706(B)</td>
</tr>
<tr>
<td>2017-04-27T01:20:12</td>
<td>16.390</td>
<td>25.664</td>
<td>0.003</td>
<td>0.003</td>
<td>0</td>
<td>0.571 ± 0.001</td>
<td>ESO archive 099.D-0777(B)</td>
</tr>
<tr>
<td>2017-04-27T02:08:58</td>
<td>16.402</td>
<td>25.678</td>
<td>0.003</td>
<td>0.003</td>
<td>0</td>
<td>0.573 ± 0.001</td>
<td>ESO archive 099.D-0777(B)</td>
</tr>
</tbody>
</table>

3. Dynamical N-body model

In Xitau the dynamical model contains the following acceleration terms ($\text{Broz}[2017], \text{Broz et al.}[2021a], \text{Broz et al.}[2022]$).

$$f = -\sum_{j=1}^{N} \frac{G m_i}{r_{ij}} r_{ij} + f_{\text{ppm}} + f_{\text{oblat}} + f_{\text{multipole}} + f_{\text{tides}}$$

(1)

Here the terms are mutual gravitational interactions and the parametrized post-Newtonian (PPN); we do not activate oblateness, multipoles, or tides for QZ Car. We exchanged the PPN approximation for that of [Standish & Williams (2006)] which is more accurate. Hereafter, the notation conforms to the actual implementation:

$$f_{\text{ppm}} = \sum_{j=1}^{N} \left[-K_1 (K_2 + K_3 + K_4 + K_5 + K_6 + K_7 + K_8) r_{ij} + K_1 (K_9 + K_{10}) r_{ij} + K_{11} r_{ij}\right].$$

(2)

$$K_1 = \frac{G m_j}{c^2 r_{ij}^3}.$$  

(3)

$$K_2 = -2(\beta + \gamma) \sum_{k \neq i} \frac{G m_k}{r_{ik}}.$$  

(4)

$$K_3 = -(2\beta - 1) \sum_{k \neq i} \frac{G m_k}{r_{jk}}.$$  

(5)

Here $r_{ij}$ denotes the position vector of body $i$, $r_{ij} = r_i - r_j$, $v_i \equiv |r_i|$, $c$ is the speed of light in a vacuum, and $\beta = \gamma = 1$ are the nominal PPN factors.

We perform a numerical integration of orbits with the Bulirsch-Stoer algorithm. It has an adaptive time step, with the relative precision set to $10^{-8}$. The output time step is set to 0.2 d, but all times of observations are also integrated and output precisely. The total number of free parameters is 38 (see Table 2). Observables are derived from coordinates, velocities, radiative quantities, and distance. Synthetic spectra, both relative and absolute, are computed during convergence with Pyterpol (Nemravova et al. 2016) from BSTAR and OSTAR grids (Lanz & Hubeny 2007, 2009).

The observations and our model are compared by means of the $\chi^2$ metric

$$\chi^2 = w_{\text{rot}}^2 r_{\text{rot}}^2 + w_{\text{vis}}^2 r_{\text{vis}}^2 + w_{\text{syn}}^2 r_{\text{syn}}^2 + w_{\text{sed}}^2 r_{\text{sed}}^2 + w_{\text{sky}}^2 r_{\text{sky}}^2,$$

(15)

where the subscripts denote the respective datasets: radial velocity (RV), eclipse or transit timing variation (TTV), squared visibility (VIS), closure phase (CLO), triple product amplitude (T3), synthetic spectrum (SYN), spectral energy distribution (SED), and relative astrometry (SKY2). Recent improvements to our model also include metallicity fitting, a subplex algorithm (i.e. simplex on subspaces; Rowan [1990]), and precise computation of the Roche potential from the volume-equivalent radius for optional light curve computations (using $R(\Omega)$ integrated as in Leahy & Leahy [2015] and inverted to $\Omega(R)$).

As a preparatory task, we computed models with parameters as determined by the observation-specific models (Mayer et al. 2022). However, there were some caveats. First, orbital elements in our N-body model (including periods $P_1$, $P_2$, $P_3$) are only oscillating. When a dynamical model is different, these elements
must be converged again. Whether or not $f_{\text{ppn}}$ is included in the model also affects $\chi^2$; in other words, to obtain accurate values of the parameters it should be included. Moreover, we had to flip the orientation of the system several times to match some of the datasets (TTV, SKY2). Only then did we perform a convergence with the simplex algorithm (Nelder & Mead 1965; e.g. Fig. 4). This was performed multiple times using various initial conditions to avoid a false convergence and to solve some remaining systematics (RV, SYN).

### 3.1. Survey of parameters

In order to understand how individual datasets constrain the model, and to find a global minimum of $\chi^2$, we performed a survey of the parameters. We converged 81 different models. Every convergence was initialized with a different combination of masses $m_1$, $m_2$ (Ac1, Ac2) in the range 15 to 50 $M_\odot$, while $m_3$ (Aa1) was set to $m_{\text{sum}} - m_1 - m_2 - m_4$; nevertheless, all parameters were free during convergence. The maximum number of iterations was set to 1000. To speed up this computation, we used a set of predefined synthetic spectra. We assumed unit weights, with the exception of $w_{\text{vis}} = 0.1$. The radiative parameters of the fourth spectrally undetected component (Aa2) were constrained by Harmanec (1988) parametric relations $m_{\text{syn}}(T_2)$, $\log g(T_2)$ (i.e. assuming it is a normal main-sequence object). The component is too faint to significantly contribute to the total flux; it is not, however, negligible from the dynamical point of view.

The results are shown in Fig. 5. One can clearly see the forbidden regions where no solution can be found ($\chi^2$ remains high). For high $m_1$, $m_2$, this is especially due to the CLO and VIS datasets, which strongly constrain the relative luminosities of the (Ac1+Ac2) and (Aa1+Aa2) components. Moreover, there are strong correlations between parameters: negative for TTV, positive for RV. This is very useful because the best-fit model is just at the intersection. Finally, the $\chi^2$ contribution due to the SED dataset seems to be too flat. The reason is that the distance around 2800 pc corresponds to the SED, and all the models were converged. It does not mean that the SED is unimportant.

### 3.2. Nominal model

The best-fit parameters of our nominal model are listed in Table 2. The observed and synthetic data are compared in Figs. 6 – 14.

First, the eclipse-timing variations (Fig. 6) exhibit much smaller amplitudes compared to those from Mayer et al. (2022) because they are suppressed by the actual motion of the eclipsing binary (Ac1+Ac2). The respective $\chi^2_{\text{vis}}$ contribution is still larger than the number of data points $n_{\text{vis}}$ because the other datasets (RV) have to be fit at the same time; the result is a compromise. Second, the RVs of the eclipsing binary Ac1+Ac2 (Fig. 7) show some systematics related to the Ac1 component at the phases 0.0 and 0.5 (i.e. primary and secondary eclipses) when the lines are blended and the RVs should be close to zero. Additional systematics are present elsewhere, for example between 0.6 and 0.7, which cannot be avoided due to other RV measurements with relatively low RV values. The reason might be hidden in a complex reduction and rectification procedure; one possible solution would be to prefer fitting the synthetic spectra, instead of deriving the RVs (see also Section 3.4). For the Aa2 component, which is relatively faint and fast-rotating, a number of measurements are offset. Because these substantially contribute to $\chi^2_{\text{vis}}$, we decided to remove the RVs of Aa2 in the alternative model (see below).

Third, the RVs of the Aa1 component (Fig. 8) seem to be reliable, because it is relatively bright and slow-rotating. Even so, the Aa1 and Ac1 RVs are both clearly affected by the wide orbit ((Ac1+Ac2)+(Aa1+Aa2)). This was detected in Mayer et al. (2022) as variable $\gamma$ velocities. The fourth component, Aa2, is too faint, but its predicted maximum RV should be of the order of $+300 \text{ km s}^{-1}$.

Astrometry of the wide orbit (Ac+Aa binary; Fig. 9) provides a fundamental angular scale, which together with ETs and RVs constrains the fundamental parameters. Even though there is some tension between periods from RVs and ETs (Mayer et al., 2022), we regard the resulting period $P_3 = (14722 \pm 50)$ d as a reasonable compromise.

The blue part (399–544 nm) of the eight rectified FEROS spectra (with high signal-to-noise ratio) were also fitted (Fig. 10). The $\chi^2_{\text{syn}}$ contribution is still substantial, mostly because the level of continuum was not always correctly determined. The Hα and Hγ lines were removed from the fitting procedure, due to strong emission features; it was impossible to fit them by our model, which does not include any optically thin circumstellar matter (CSM). We can only fit weak emission lines (e.g. Fe III) present in the synthetic spectra of stellar atmospheres. On the other hand, Hδ does have features (asymmetries), which are reasonably fitted, although the depths of synthetic hydrogen lines are not matched precisely, which is again related to the level of the surrounding continuum: for example, between 405.1 to 412.6 nm there is no continuum, as verified by synthetic spectra. Nevertheless, the depths and the features of the He I, C II, O II, Mg II lines are fitted much better. Overall, the determination of the respective RVs is very precise (especially for the Ac1 and Ac2 components) because we fit all the lines at the same time in a process also known as cross-correlation. Our model also naturally couples all the spectra (by the orbits), which avoids line blends.

For the SED (Fig. 11), the fit is acceptable within ±0.2 mag in the NUV–NIR range, which is likely related to the uncertainties of dereddening (see Sect. 2.1). Moreover, 0.15 mag is the depth of the minima. The far-IR range was not fitted; the observed flux exhibits an excess, indicating a presence of the
Fig. 5. Contributions to $\chi^2$ for a set of 81 best-fit models. Individual contributions (datasets) are shown in the panels (from top left): TTV, RV, SKY2, SED, SYN, VIS, CLO, T3. Every convergence was initialized with a different combination of masses $m_1$, $m_2$ (Ac1, Ac2) in the range 15 to 50 $M_\odot$, while $m_3$ (Aa1) was set to $m_{\text{sum}} = m_1 - m_2 - m_3$. All parameters were free during convergence. The axes correspond to the masses $m_1$ and $m_2$; the colours correspond to $\chi^2$ (see also tiny numbers), with adapted colour scales: cyan best fits, blue good fits ($<1.2 \text{ min} \chi^2$), orange poor fits ($\geq 1.2 \text{ min} \chi^2$). The factor was 3.0 for TTV, RV, SKY2. The forbidden regions can be clearly seen (e.g. high $m_1$, $m_2$ especially due to CLO), as well as correlations between the parameters (TTV $-$, RV $+$). The weighted very best fit for all the datasets is denoted by the red circle.
CSM. Nevertheless, the SED (together with the mass, RV, angular scale) determines the distance around 2800 pc.

A comparison of interferometric observations and our model is straightforward for the squared visibilities $V^2$ (Fig. 12). The sinusoidal dependence on the baseline $B/\lambda$ essentially corresponds to a wide binary ($(A_{c1}+A_{c2})+(A_{a1}+A_{a2})$). The scatter of the observed $V^2$ is related to the Poisson noise; our synthetic $V^2$ are smooth. Because $V^2$ values can be very close to 1 (for a binary), it is important to include the observed values that are slightly higher or lower than 1 because only then will the mean value be close to 1. The corresponding precision of astrometry, when all VLT/GRAVITY measurements are compressed to (u, v) coordinates, is of the order of 0.010 mas = 10 $\mu$as.

The same is true for the closure phases arg $T_1$ (Fig. 13). As in Sanchez-Bermudez et al. (2017), the dependence on $B/\lambda$ is similar to that of a binary.

On contrary, the triple product amplitude (Fig. 14) exhibits some systematics, especially at long baselines ($B/\lambda > 4 \times 10^7$ cycles per baseline); the observed values are often close to or even exceed 1, which seems to be a calibration problem. Nevertheless, the positions of the maxima and minima of $|T_3|$ as a function of $B/\lambda$ are fitted perfectly, hence we retained the dataset in the nominal model (and we removed it in the alternative model; see Sect. 3.3).

3.3. Alternative model

Alternative models are useful for determining the true uncertainties of parameters. With this goal in mind, we modified a number of things, in particular the RVs of the Ac2 component were not used because they did not seem reliable. Instead, the Ac2 component was again constrained according to Harmanec (1988). In the case of the Ac1 RVs, we removed the outliers identified in the nominal model.

Similarly, $|T_3|$ was not used because it exhibited systematics at long baselines, while $V^2$ at the same baselines was fitted precisely. Outliers were also removed from the VIS, CLO, and T3 datasets, as they often occur at the beginning of the burst. We thus assumed they were caused by a temporarily incorrect set-up.

The weights were set to extreme values, to enforce the fitting of datasets with a small number of points: $w_{rv} = 100$, $w_{3}\sigma = 1000$, $w_{vis} = 0.1$, $w_{db} = 0.1$, $w_{sinc} = 0.1$, $w_{sky2} = 1000.0$. On the contrary, we relaxed the SED constraint by using $w_{sed} = 1$

The results are summarized in Table 3 and the figures can be found in Appendix A. The major differences between the models can be summarized as follows. Using $w_{trim} = 1$, means forcing the Ac2 component to be on the main sequence. Since we needed a substantial mass ratio to explain the RVs of Ac1, the temperature of Ac2 increases (and its radius decreases). Putting
log $g_1 \leq 3.5$, would the precession rate $\dot{\omega}$ increase, hence $\chi^2_{	ext{res}}$ as well as $\chi^2_{\text{S}}$. Interestingly, the difference appears to be of the same order as the systematics of RVs mentioned in Section 3.2. Nevertheless, the precession is not as substantial; the observed RV curves do not exhibit a clear temporal trend, but rather a scatter (Mayer et al. 2022), and thus all the parameters (except $P_1$) remain the same, within the uncertainties.

4. Discussion

Compared to previous works on QZ Car (Walker et al. 2017, Blackford et al. 2020), our new model indicates a higher total mass (137 vs. 112 $M_\odot$) and a different distribution of masses within the binaries Aa1+Aa2 and Ac1+Ac2, preferring the mass ratios Aa1/Aa2 = 8 and Ac1/Ac2 close to 1, respectively.

Given the photo-spectro-interferometric distance of (2800 ± 100) pc for the nominal model, QZ Car is likely related to the Carina Nebula (NGC 3372). However, when cluster distances were determined from the Gaia early Data Release 3 parallaxes (Shull et al. 2021, Göppl & Preibisch 2022), they turned out to be systematically smaller, possibly due to anomalous extinction, with $R_V \equiv A_V/E(B-V) = 3.2$ to 4.0. For Collider 228, the median distance is 2470 pc and the angular size about 14′, which corresponds to the tangential size of only 10 pc. The radial size is not well constrained by parallaxes. This revised distance is in agreement with our alternative model of QZ Car.

Massive multiple stars in this region may shed light on possible progenitors of the η Carinae event (Weigelt et al. 2016), which was suggested to be caused by mass transfer in triple systems, eventually leading to an explosive merger (Smith et al. 2018). Notably, the QZ Car quadruple system includes the eclipsing mass-transferring binary Ac1→Ac2, which will evolve substantially. According to our model, the mass ratio Ac2/Ac1 is relatively close to 1, which means that we are observing this binary at almost its closest distance. If, for example, the final mass of Ac1 decreases to 5 $M_\odot$, the angular momentum conservation implies the final separation (as well as the envelope extent of Ac1) of 1000 $R_\odot$ (i.e. substantially less than the pericentre of (Aa1+Ac2)+(Ac1+Ac2) binary, $a_3(1 - e_3) = 6300 R_\odot$). This does not lead to an imminent instability. It is still unclear, what has been (and shall be) the role of loosely bound companions, Ab, Ad, B, C, D, imaged around QZ Car (Rainot et al. 2020) because we still lack their proper motions.

5. Conclusions

Using the Mayer et al. (2022) observation-specific models as initial conditions for convergence, we constructed a robust N-body model of the QZ Car quadruple system, fitting all three orbits and the stellar–radiative parameters at the same time. Because we used all types of observations, which are in a sense orthogonal, the model is well-behaved and does not exhibit strong correlations (or drifts). Independent constraints for individual parameters were only used when needed (e.g. for the luminosity–radius of the Aa2 component, which is too faint to be directly observable in the flux).

Our preferred model is the nominal one (see Table 2): the best-fit masses are $m_1 = 26.1 M_\odot$, $m_2 = 32.3 M_\odot$, $m_3 = 70.5 M_\odot$, $m_4 = 137 M_\odot$.

Interestingly, the Aa1 component seems to be extremely massive (up to 70 $M_\odot$), especially compared to the Aa2 component (less than 10 $M_\odot$). This may be also related to a (putative) past mass transfer Aa2 → Aa1.
Fig. 10. Comparison of the rectified observed FEROS spectra (blue) with the synthetic spectra computed by our N-body model (orange). Residuals are also plotted (red). They are substantial for the $H\delta$ line (see circles), where the continuum level is uncertain (between 405.1 and 412.6 nm). Nevertheless, most line features (including splits, blends, weak lines close to the continuum) are present in both observed and synthetic spectra, resulting in reliable RVs of individual stellar components (especially Ac1, Aa1; cf. Fig. 15).

Fig. 11. Comparison of the dereddened (blue) and the synthetic SED (red). The NUV–NIR region is reasonably described by our N-body model, although there is a substantial excess of the observed flux in the far-infrared region. This is possibly related to non-thermal processes in stellar atmospheres or to the presence of circumstellar matter, which is not included in our N-body model.

and $m_4 = 8.8 M_\odot$, with uncertainties of the order of 2 $M_\odot$, and the distance $d = (2800 \pm 100)$ pc. The alternative model, with the Ac2 component forced to be on the main sequence, exhibits some systematic differences, especially for the SED, which can be attributed to anomalous extinction with $R_V \sim 3.4$. We used it to determine the realistic uncertainties of parameters.

There are still some poorly constrained parameters, in particular the mutual inclinations of the orbits, because the longitude of nodes $\Omega_1$ is not constrained by eclipses. For simplicity, we assumed a co-planarity, but observations with the VLTI/GRAVITY instrument covering both short periods ($P_1, P_2$) could be used to constrain it; the astrometric uncertainties related to the Aa1 component are of the same order as the photocentre motions related to the eclipsing binary Ac1+Ac2.

As a future work we suggest including the observed light curve and strong emission lines (especially $H\alpha$ and $H\beta$) in the model. However, this is generally difficult, given the possible presence of both optically thick and optically thin circumstellar matter (CSM). An appropriate treatment of the radiation transfer in the CSM is needed for this purpose (e.g. Brož et al. 2021b). Moreover, a presence of oscillatory signals in the TESS light curve also requires substantial model improvements (e.g. Conroy et al. 2020).

Acknowledgements. M.B., Ph.D., and M.W. were supported by the Czech Science Foundation grant 19-01995S. We thank an anonymous referee for comments. We thank Michael Shull for a discussion about anomalous extinction.

References
Ducati, J. R. 2002, VizieR Online Data Catalog.
Gaia Collaboration. 2020, VizieR Online Data Catalog, I/350.
Fig. 12. Squared visibilities $V^2$ for VLTI/GRAVITY observations (March 14, 2017 and April 27, 2017; blue), synthetic $V^2$ (orange), and residuals (red). The sinusoidal dependence on the baseline $B/\lambda$ essentially corresponds to a wide binary ($(A_{c1}+A_{c2})+(A_{a1}+A_{a2})$). Disks of individual stellar components cannot be resolved (at 0.08 mas, which correspond to a drop in $V^2$ of only 0.01 at the longest baseline).

Fig. 13. Same as Fig. 12 but for the closure phase $\arg T_3$. Again, the dependence on $B/\lambda$ is similar to that of a binary.

Harmanec, P. 1988, Bulletin of the Astronomical Institutes of Czechoslovakia, 39, 329
Lainey, V. 2016, Celestial Mechanics and Dynamical Astronomy, 126, 145

Fig. 14. Same as Fig. 12 but for the triple product amplitude $|T_3|$. The observed values are often close to or even exceed 1, which indicates a possible calibration problem at long baselines ($B/\lambda > 4 \times 10^7$ cycles per baseline); synthetic values are always $< 1$. The positions of maxima and minima of $|T_3|B/\lambda$ are fitted perfectly.

Leahy, D. A. & Leahy, J. C. 2015, Computational Astrophysics and Cosmology, 2, 4
Fig. 15. Synthetic spectra of individual components (Ac1, Ac2, Aa1, Aa2) weighted by their luminosities to show their contributions to the total spectrum. For comparison, the observed spectrum is plotted (error bars). The region of the He I 5016 and 5047 lines is plotted. The Ac2 component is fast-rotating and has broad lines; the Aa2 component is not luminous and its contribution is negligible.

Fig. A.1. Same as Fig. 6 but for the alternative model.

Fig. A.2. Same as Fig. 7 but for the alternative model.

Fig. A.3. Same as Fig. 8 but for the alternative model.

Fig. A.4. Same as Fig. 9 but for the alternative model.

Appendix A: Figures for the alternative model

For comparison, we show the corresponding figures for the alternative model (Fig. A.1 to Fig. A.8). Generally, they are similar to those of the nominal model, but they demonstrate how weights and additional constraints (for components Ac2 and Aa2) can change the best-fit solution.
Fig. A.5. Same as Fig. 10 but for the alternative model.

Fig. A.6. Same as Fig. 11 but for the alternative model.

Fig. A.7. Same as Fig. 12 but for the alternative model.

Fig. A.8. Same as Fig. 13 but for the alternative model.
### Table 2. Best-fit parameters for the nominal (Sect. 3.2) and alternative (Sect. 3.3) models.

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### Notes. The notation is as follows: 1. Ac1, 2. Ac2, 3. Aa1, 4. Aa2. The orbital elements are oscillating for the epoch $T₀ = 2453738.819100$, where $m₁$ denotes the mass of body 1 (and so on for bodies 2, 3, 4); $P₁$ is the orbital period of the orbit $(1+2)$, log $e₁$ logarithm of eccentricity, $i₁$ inclination, $Ω₁$ longitude of node, $σ₁$ longitude of pericentre, $λ₁$ true longitude (and so on for orbits $(3+4)$, $(1+2)+(3+4)$); $T₁$ is the effective temperature of body 1, log $g₁$ logarithm of gravity, $v_{rot₁}$ rotational velocity, $γ$ systemic velocity, $dₚc$ distance; $n$ denotes the number of observations (RV, TTV, VIS, CLO, T₃, SYN, SED, SKY₂); $χ²$ is simply unreduced $χ²$. The nominal and alternative models use different weights (cf. §). Parameters flagged with † were derived from $T₁$ according to Harmanec (1988); those flagged with ‡ were fixed. The angular orbital elements are expressed in the standard stellar reference frame; the (Ac1+Ac2) eclipsing binary is located in the centre.
Table 3. Derived parameters for the nominal and alternative models.

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Notes. $a$ denotes the semi-major axis, $e$ the eccentricity, $R$ the radius, and $L$ the relative luminosity in $V$ band.