Possible systematics in the VLBI catalogs as seen from *Gaia*

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ABSTRACT

Aims. In order to investigate the systematic errors in the very long baseline interferometry (VLBI) positions of extragalactic sources (quasars) and the global differences between *Gaia* and VLBI catalogs, we use the first data release of *Gaia* (*Gaia* DR1) quasar positions as the reference and study the positional offsets of the second realization of the International Celestial Reference Frame (ICRF2) and the Goddard VLBI solution 2016a (gsf2016a) catalogs.

Methods. We select a sample of 1032 common sources among three catalogs and adopt two methods to represent the systematics: considering the differential orientation (offset) and declination bias; analyzing with the vector spherical harmonics (VSH) functions.

Results. Between two VLBI catalogs and *Gaia* DR1, we find that: i) the estimated orientation is consistent with the alignment accuracy of *Gaia* DR1 to ICRF, of ~ 0.1 mas, but the southern and northern hemispheres show opposite orientations; ii) the declination bias in the southern hemisphere between *Gaia* DR1 and ICRF2 is estimated to be $+152 \mu\text{as}$, much larger than that between *Gaia* DR1 and gsf2016a which is $+34 \mu\text{as}$. Between two VLBI catalogs, we find that: i) the rotation component shows that ICRF2 and gsf2016a are generally consistent within $30 \mu\text{as}$; ii) the glide component and quadrupole component report two declination-dependent offsets: dipolar deformation of $\sim +50 \mu\text{as}$ along the Z-axis, and quadrupolar deformation of $\sim -50 \mu\text{as}$ that would induce a pattern of $\sin 2\delta$.

Conclusions. The significant declination bias between *Gaia* DR1 and ICRF2 catalogs reported in previous studies is possibly attributed to the systematic errors of ICRF2 in the southern hemisphere. The global differences between ICRF2 and gsf2016a catalogs imply that possible, mainly declination-dependent systematics exist in the VLBI positions and need further investigations in the future *Gaia* data release and the next generation of ICRF.

Key words. astrometry – reference systems – catalogs

1. Introduction

The International Celestial Reference Frame (ICRF) has been serving as the basic position reference for nearly three decades as it provides a very precise position observed by the very long baseline interferometry (VLBI) technique. The first generation of ICRF (ICRF1) was proposed in 1998 (Ma et al. 1998). With significant improvements, the second generation of ICRF (ICRF2; Fey et al. 2015) has been adopted since 2009 and now is widely used in astrometry and geodesy. The positional noise floor of ICRF2 is about 40 micro-arcseconds (μas) and the directional stability of the frame axes is at the level of $10 \mu\text{as}$. The next generation of ICRF (ICRF3) is expected to be published in 2018 (Jacobs et al. 2014).

The monitoring and maintenance of the ICRF have been undertaken in previous works, for example, Gontier et al. (2001), Feissel-Vernier et al. (2006), Sokolova & Malkin (2007), Lambert (2014). These works usually involve comparison of the radio source positions provided in the regular VLBI solutions from different International VLBI Service (IVS) analysis centers. Lambert (2013) assessed the axis stability of ICRF2 to be of $20 \mu\text{as}$ and reported that there has been no noticeable deformation in ICRF2 since 2009. Similar results are presented in Lambert (2014) showing that almost all catalogs from different IVS analysis centers are consistent with respect to ICRF2 within

$20 \mu\text{as}$, except some catalogs showing significant orientation angles of $\sim 40 \mu\text{as}$. These works showed that the VLBI catalogs were generally consistent within several tens of μas .

In principle, the mutual comparison of VLBI solutions can only offer an internal check because these solutions are usually obtained at the same period, based on almost the same data and similar astrometric and geophysical models, thus cannot be rigorously considered independent. The more reasonable way is to adopt another catalog as the reference that is fully independent of VLBI observations and provide positions for sufficient radio sources with accuracy better than or at least comparable to VLBI. However, almost all the astrometric catalogs could not satisfy the requirements, until the *Gaia* mission published its first data release (*Gaia* DR1; Gaia Collaboration 2016a), which provides positions for about 135 000 known quasars.

The comparison in Mignard et al. (2016) showed large residuals and a declination bias ~ 0.1 mas between the *Gaia* DR1 and ICRF2 catalogs. The authors mentioned that the latter is likely due to the (ecliptic) north-south asymmetry of the systematics of *Gaia* observations. Considering that the ICRF2 catalog created in 2009 is already outdated for current VLBI observations (Malkin 2016), it is natural to include a new VLBI catalog to replace the ICRF2 catalog. Mignard & Klioner (2017) presented results showing that *Gaia* DR1 positions had less scattered residuals with respect to gsf2016a than to ICRF2 and showed no bias

in the declination or right ascension relative to the VLBI catalog at XKa bands, which confirmed the quality of the *Gaia* DR1 catalog. The authors, therefore, concluded that large residuals between *Gaia* DR1 and ICRF2 catalogs reported in Mignard et al. (2016) were mainly attributed to systematics in ICRF2. Jacobs (2017) also compared the *Gaia* DR1 quasar positions with the VLBI positions obtained from VLBI observations at different wavelengths, that is, SX, K, and XKa bands. The authors reported that with respect to *Gaia* DR1, VLBI positions showed a smaller scatter and lower percentage outliers at higher radio frequency, which again confirmed the quality of the *Gaia* DR1 and implied possible systematics in the ICRF2. Generally, the comparisons between the *Gaia* DR1 and VLBI catalogs revealed some possible systematics in the ICRF2 catalog, which are not found in previous works based on the mutual comparison of VLBI catalogs. This motivates us to perform further investigations on this problem.

In this work, we aim to study systematics in the VLBI catalogs and the global differences between *Gaia* and VLBI quasar positions. Three catalogs are used for comparison: the *Gaia* DR1 auxiliary quasar solution, the ICRF2 catalog, and the gsf2016a serving as the prototype of ICRF3. In contrast to previous works where the ICRF2 was used as the reference catalog, we use the *Gaia* DR1 quasar positions as the reference.

2. Dataset

Gsf2016a is a VLBI solution based on all available dual band VLBI observations at 8.4 GHz and 2.2 GHz from 1979.08.03 to 2016.08.22, except these of the VLBA Calibrator Surveys (VCS)¹. As a result, this solution does not contain most of the VCS-only sources that are usually observed in only one session. Gsf2016a provides global source positions of 1895 sources and mean positions of 39 ICRF2 “special handling sources”, the latter being known as unstable sources. To avoid the effect of variations of individual source positions due to the intrinsic source-structure changes such as jets, we only used 1895 sources whose positions were estimated as global parameters in the VLBI solutions. For the *Gaia* DR1 auxiliary quasar solution, there are only 2191 ICRF2 source counterparts in the optical band. We selected a sample consisting of all 1032 common sources among these three catalogs and five groups are investigated for comparison: all the 1032 sources denoted as “All”; 563 sources in the northern hemisphere and 469 in the south, denoted as “North” and “South”, respectively; 262 sources among the 295 ICRF2 defining sources and 770 non-defining sources, denoted as “Defining” and “Non-def”, respectively. The median positional errors of the sample in *Gaia* DR1, ICRF2, and gsf2016a are 590 μ as, 134 μ as, and 62 μ as for the right ascension component ($\alpha \cdot \cos \delta$); 528 μ as, 200 μ as, and 88 μ as for the declination component.

Figure 1 plots the positions for all 1032 sources used in this work. Some sparse regions can be seen between -60° and -30° , leading to an uneven sky distribution. Figure 2 shows the zonal mean of positional differences of ICRF2 and gsf2016a catalogs with respect to the *Gaia* DR1. Large mean offsets in the VLBI and *Gaia* positions (up to 5 mas) are clearly visible, which again motivates us to carry out further analyses.

Fig. 1. Distribution of 1032 quasars used in this work, including 262 ICRF2 defining sources (blue solid circles) and 770 non-defining sources (red crosses).

3. Representations of the systematics

The global difference between radio source positions in two catalogs can be written as a coordinate transformation; the most commonly used one considers a simple orientation:

$$\Delta\alpha^* = -A_1 \cos \alpha \sin \delta - A_2 \sin \alpha \sin \delta + A_3 \cos \delta,$$

$$\Delta\delta = +A_1 \sin \alpha - A_2 \cos \alpha, \quad (1)$$

where $\Delta\alpha^* = \Delta\alpha \cos \delta$; A_1 , A_2 , and A_3 are orientation angles around the X, Y, and Z axes, respectively. This transformation is usually used to align the reference frames, for example, to align the *Gaia* DR1 reference frame to ICRF2 (Lindgren et al. 2016), or to assess the stability of reference frame axes (e.g., Lambert 2013). If we consider a possible declination bias as done, for instance, in Feissel-Vernier et al. (2006), an additional term d_z (known as equatorial tilt) should be added to Eq. (1):

$$\Delta\alpha^* = -A_1 \cos \alpha \sin \delta - A_2 \sin \alpha \sin \delta + A_3 \cos \delta,$$

$$\Delta\delta = +A_1 \sin \alpha - A_2 \cos \alpha + d_z. \quad (2)$$

Here we used this term d_z to check if there is an overall declination offset between *Gaia* DR1 and VLBI positions as mentioned in Mignard et al. (2016) and figure out the cause.

A more general way to represent the global difference between catalogs is to use the vector spherical harmonics (VSH; Mignard & Klioner 2012). Mignard & Klioner (2012) provided detailed mathematical descriptions and practical examples for the VSH analysis. This method is similar to the Fourier expansions which help us to see more details as the highest degree $l_{\max}$ increases. Nevertheless, the VSH analysis of higher orders adds more parameters to estimate, and hence would make the estimation biased for a small sample. Also, there is no physical interpretation available for terms with $l_{\max} > 2$. Hence only the first two degrees VSH functions were considered in this work. For the first degree, the magnetic (or toroidal) and electric (or spheroidal) harmonics can be denoted as a rotation vector $\mathbf{R} = (R_1, R_2, R_3)^T$ and a glide vector $\mathbf{G} = (G_1, G_2, G_3)^T$, respectively, and the induced vector field can be described as follows:

$$\Delta\alpha^* = -R_1 \cos \alpha \sin \delta - R_2 \sin \alpha \sin \delta + R_3 \cos \delta$$

$$-G_1 \sin \alpha + G_2 \cos \alpha,$$

$$\Delta\delta = +R_1 \sin \alpha - R_2 \cos \alpha$$

$$-G_1 \cos \alpha \sin \delta - G_2 \sin \alpha \sin \delta + G_3 \cos \delta. \quad (3)$$

¹ Detailed descriptions of gsf2016a can be found at <http://gemini.gsfc.nasa.gov/solutions/2016a/2016a.html>

Fig. 2. Mean differences between *Gaia* DR1 and VLBI positions calculated in each cell of $10^\circ \times 10^\circ$. To obtain a better visual effect, the sources with position difference larger than 5 mas are not plotted. The blue line indicates the Galactic plane and two red crosses indicate directions of the Galactic center and the anti-Galactic center.

The rotation vector $\mathbf{R}$ is equivalent to orientation angles in Eqs. (1) and (2). For the second degree, the quadrupolar vector field can be described as follows (Titov & Lambert 2013):

$$\begin{aligned}
 \Delta\alpha^* = & +M_{2,0} \sin 2\delta \\
 & - \cos 2\delta (M_{2,1}^{\text{Re}} \cos \alpha - M_{2,1}^{\text{Im}} \sin \alpha) \\
 & + \sin \delta (E_{2,1}^{\text{Re}} \sin \alpha + E_{2,1}^{\text{Im}} \cos \alpha) \\
 & - \sin 2\delta (M_{2,2}^{\text{Re}} \cos 2\alpha - M_{2,2}^{\text{Im}} \sin 2\alpha) \\
 & - 2 \cos \delta (E_{2,2}^{\text{Re}} \sin 2\alpha + E_{2,2}^{\text{Im}} \cos 2\alpha), \\
 \Delta\delta = & +E_{2,0} \sin 2\delta \\
 & - \sin \delta (M_{2,1}^{\text{Re}} \sin \alpha + M_{2,1}^{\text{Im}} \cos \alpha) \\
 & - \cos 2\delta (E_{2,1}^{\text{Re}} \cos \alpha - E_{2,1}^{\text{Im}} \sin \alpha) \\
 & + 2 \cos \delta (M_{2,2}^{\text{Re}} \sin 2\alpha + M_{2,2}^{\text{Im}} \cos 2\alpha) \\
 & - \sin 2\delta (E_{2,2}^{\text{Re}} \cos 2\alpha - E_{2,2}^{\text{Im}} \sin 2\alpha),
 \end{aligned} \tag{4}$$

where E and M stand for the VSH functions of electric and magnetic types, respectively.

In the following analysis, all of the unknowns were estimated by the weighted least squares method. Except for the formal errors of source positions, the covariance information between right ascension and declination of each source was also considered. The data were weighted using the approach introduced in Mignard et al. (2016, see Eq. (4) and Appendix B), that is, the covariance matrix between $\Delta\alpha^*$ and $\Delta\delta$ in the least squares fitting is given by

$$\Sigma = \begin{bmatrix} \sigma_{\alpha^*,G}^2 + \sigma_{\alpha^*,V}^2 & c_G + c_V \\ c_G + c_V & \sigma_{\delta,G}^2 + \sigma_{\delta,V}^2 \end{bmatrix}, \tag{5}$$

where $\sigma_{\alpha^*,G}$ and $\sigma_{\delta,G}$ are the formal errors of right ascension and declination in the *Gaia* DR1 catalog; $\sigma_{\alpha^*,V}$ and $\sigma_{\delta,V}$ are the formal errors of right ascension and declination given in VLBI catalogs; and c_G and c_V are the covariances between right ascension and declination of each source given in *Gaia* DR1 and VLBI catalogs, respectively. The 3-sigma principle was adopted to remove the outliers.

Table 1. Differential orientation between *Gaia* DR1 and VLBI catalogs. A_{tot} is obtained by $A_{\text{tot}} = \sqrt{A_1^2 + A_2^2 + A_3^2}$.

Group	A_1 (μas)	A_2 (μas)	A_3 (μas)	A_{tot} (μas)
ICRF2 – <i>Gaia</i> DR1				
All	-85 ± 18	-17 ± 16	$+8 \pm 18$	87 ± 18
North	-180 ± 23	-69 ± 21	-76 ± 25	207 ± 23
South	$+79 \pm 29$	$+59 \pm 25$	$+113 \pm 28$	150 ± 28
Defining	-30 ± 29	-41 ± 25	$+35 \pm 32$	62 ± 28
Non-def	-123 ± 24	-3 ± 21	-8 ± 23	123 ± 24
gsf2016a – <i>Gaia</i> DR1				
All	-75 ± 16	$+5 \pm 14$	$+21 \pm 17$	78 ± 16
North	-162 ± 21	-74 ± 19	-58 ± 23	188 ± 21
South	$+66 \pm 26$	$+111 \pm 22$	$+117 \pm 26$	174 ± 24
Defining	-24 ± 27	-29 ± 23	$+39 \pm 30$	54 ± 28
Non-def	-106 ± 21	$+25 \pm 18$	$+8 \pm 21$	109 ± 21

4. Investigating the systematics

4.1. Consideration of the differential orientation.

The differential orientations between *Gaia* DR1 and VLBI catalogs are presented in Table 1. Referring to *Gaia* DR1, the ICRF2 catalog showed a total orientation of $62 \sim 207 \mu\text{as}$; for gsf2016a it was from $54 \mu\text{as}$ to $188 \mu\text{as}$. This result is quite normal since the *Gaia* DR1 reference frame is aligned to the ICRF with an accuracy of about 0.1 mas at the epoch J2015.0 (Lindgren et al. 2016). Comparing the three orientation angles of the ICRF2 catalog (upper part) with those of gsf2016a (lower part), the differences never exceed $20 \mu\text{as}$, except for A_2 of the group “South” which is about $50 \mu\text{as}$. This result is consistent with that in Lambert (2013) and Lambert (2014), that is, the axis stability of ICRF2 is on the order of $20 \mu\text{as}$. Comparing the results of different groups in the same catalog, however, some inconsistencies are presented. For the ICRF2 catalog, the relative orientation angles for groups “North” and “South” have opposite signs, as found in Liu et al. (2017). Using the new gsf2016a data, we attained similar results, indicating that there are possible zonal deformations between VLBI and *Gaia* DR1 catalogs.

When we considered the additional declination bias dz , the orientation angles A_1 and A_2 changed slightly, in the same order as their uncertainties, and A_3 remained almost unchanged

Table 2. Differential orientation and declination bias between *Gaia* DR1 and VLBI catalogs.

Group	A_1 (μ as)	A_2 (μ as)	A_3 (μ as)	dz (μ as)	A_{tot} (μ as)
ICRF2 – <i>Gaia</i> DR1					
All	-98 ± 18	-32 ± 16	$+8 \pm 18$	$+120 \pm 14$	103 ± 18
North	-189 ± 23	-107 ± 22	-76 ± 25	$+119 \pm 19$	229 ± 23
South	$+59 \pm 29$	$+82 \pm 25$	$+113 \pm 28$	$+152 \pm 22$	152 ± 27
Defining	-41 ± 29	-54 ± 25	$+35 \pm 32$	$+78 \pm 22$	78 ± 28
Non-def	-134 ± 24	-15 ± 21	-8 ± 23	$+148 \pm 18$	135 ± 24
gsf2016a – <i>Gaia</i> DR1					
All	-81 ± 16	$+0 \pm 14$	$+21 \pm 17$	$+46 \pm 12$	84 ± 17
North	-169 ± 22	-104 ± 20	-58 ± 23	$+87 \pm 17$	207 ± 21
South	$+61 \pm 26$	$+116 \pm 22$	$+117 \pm 26$	$+34 \pm 19$	176 ± 24
Defining	-24 ± 27	-29 ± 23	$+39 \pm 30$	$+0 \pm 21$	54 ± 28
Non-def	-113 ± 21	$+17 \pm 18$	$+8 \pm 21$	$+73 \pm 16$	115 ± 21

Notes. A_{tot} is obtained in the same way as in Table 1.

Table 3. Correlation coefficients of parameters in the solution of group “All” for “ICRF2 – *Gaia* DR1” in Table 2.

	A_1	A_2	A_3	dz
A_1	+1.0	+0.1	-0.2	-0.1
A_2		+1.0	-0.1	-0.1
A_3			+1.0	+0.0
dz				+1.0

Notes. Other solutions in Table 2 showed similar correlations. The correlation coefficient of parameters (A_1 , A_2 , and A_3) in the solutions in Table 1 was also similar to that presented in this table.

for both ICRF2 and gsf2016a catalogs (Table 2) compared with Table 1. This means that estimating dz did not significantly affect the estimation of orientation angles. Table 3 shows that the correlation coefficients between dz and three orientation angles in the solutions in Table 2 never exceed 0.3. From the column dz in Table 2, one can clearly find a significant bias in both ICRF2 and gsf2016a catalogs. The bias was estimated to be of $78 \sim 152 \mu$ as between ICRF2 and *Gaia* DR1 catalogs, which agrees with the declination bias of about -0.1 mas as reported in Mignard et al. (2016) and later confirmed in our previous work (Liu et al. 2017). For gsf2016a, dz was estimated to be smaller in comparison, strictly beneath 100μ as for all five groups, especially for the “Defining” group which yielded zero bias.

Then we compared the bias dz obtained from the ICRF2 catalog with that from gsf2016a. Taking gsf2016a minus ICRF2 in sense, the differences were $-74 \pm 18 \mu$ as for “All” group; $-32 \pm 25 \mu$ as and $-118 \pm 29 \mu$ as for “North” and “South” group, respectively; and $-78 \pm 30 \mu$ as and $-75 \pm 24 \mu$ as for “Defining” and “Non-def”, respectively. The groups “All”, “Defining”, and “Non-def” gave consistent results: there was a relative declination offset of 70μ as between gsf2016a and ICRF2 catalogs. Comparing directly the declination of the two catalogs for the 290 common ICRF2 defining sources, a clear offset can be seen in Fig. 3, mostly in the southern hemisphere. The declination offset between gsf2016a and ICRF2 catalogs is obviously beyond the precision of ICRF2, which was not found in the previous works. A lot of effort has been made to strengthen the southern hemisphere after the adoption of ICRF2 (Jacobs et al. 2014), therefore we can reasonably consider gsf2016a as an improved

Fig. 3. Declination differences between gsf2016a and ICRF2 catalogs for 290 common ICRF2 defining sources, in the sense of ICRF2 minus gsf2016a. A clear positive offset can be seen from the south side of the equator.

catalog compared to ICRF2 in the southern hemisphere. As a result, the declination offset between gsf2016a and ICRF2 catalogs should reflect the systematic errors of ICRF2 in the southern hemisphere. We thus concluded that the declination offset of about 0.1 mas between *Gaia* DR1 and ICRF2 positions would be mostly coming from the position errors of ICRF2 catalog rather than *Gaia* DR1. Furthermore, the pattern in Fig. 3 is more similar to $\sin 2\delta$ than linear or a bias. In the following section, we also use the VSH tools to directly investigate this pattern.

4.2. Analysis with the VSH tools.

As stated in Mignard & Klioner (2012), the implementation of VSH functions requires the orthogonality conditions to be satisfied, which means that the sample should distribute uniformly on the celestial sphere. Therefore, the groups “North” and “South” which only contain radio sources in the half-sky were not analyzed with this method.

Table 4 reports the rotation component in the VSH analysis of the positional offsets among the *Gaia* DR1, ICRF2, and gsf2016a catalogs. For the first-degree VSH analysis ($l_{\text{max}} = 1$), the rotation components of the ICRF2 and gsf2016a catalogs with respect to the *Gaia* DR1 were consistent within their formal

Table 4. Rotation component of VSH analysis of *Gaia* DR1 and VLBI positional offsets.

Group	$l_{\max}$	R_1 (μas)	R_2 (μas)	R_3 (μas)	R (μas)	Apex ($^\circ$)
ICRF2 – <i>Gaia</i> DR1						
All	1	-81 ± 18	-19 ± 16	$+16 \pm 19$	85 ± 18	$(193 \pm 11, +11 \pm 13)$
	2	-30 ± 22	-71 ± 22	$+23 \pm 19$	80 ± 22	$(247 \pm 17, +17 \pm 14)$
Defining	1	-46 ± 29	-60 ± 25	$+59 \pm 32$	97 ± 29	$(232 \pm 21, +38 \pm 18)$
	2	-9 ± 34	-115 ± 33	$+28 \pm 33$	119 ± 33	$(265 \pm 17, +14 \pm 16)$
Non-def	1	-100 ± 25	$+36 \pm 22$	-9 ± 23	107 ± 24	$(160 \pm 12, -5 \pm 13)$
	2	-96 ± 31	$+15 \pm 30$	$+8 \pm 25$	98 ± 31	$(171 \pm 18, +5 \pm 15)$
gsf2016a – <i>Gaia</i> DR1						
All	1	-69 ± 17	$+8 \pm 14$	$+26 \pm 17$	74 ± 17	$(173 \pm 12, +21 \pm 14)$
	2	-13 ± 20	-59 ± 19	$+37 \pm 18$	71 ± 19	$(257 \pm 19, +31 \pm 15)$
Defining	1	-34 ± 27	-32 ± 23	$+56 \pm 31$	73 ± 29	$(223 \pm 31, +50 \pm 22)$
	2	$+7 \pm 32$	-111 ± 31	$+23 \pm 32$	114 ± 31	$(274 \pm 16, +12 \pm 16)$
Non-def	1	-84 ± 22	$+59 \pm 19$	$+5 \pm 21$	103 ± 21	$(145 \pm 11, +3 \pm 12)$
	2	-84 ± 27	$+31 \pm 26$	$+30 \pm 23$	95 ± 27	$(159 \pm 17, +19 \pm 14)$
ICRF2 – gsf2016a						
All	1	$+0 \pm 4$	-23 ± 4	$+0 \pm 3$	23 ± 4	$(269 \pm 10, -1 \pm 8)$
	2	$+0 \pm 5$	-20 ± 5	$+0 \pm 3$	20 ± 5	$(270 \pm 14, -1 \pm 10)$
Defining	1	-1 ± 5	-20 ± 5	-3 ± 4	20 ± 5	$(267 \pm 14, -10 \pm 12)$
	2	$+1 \pm 6$	-18 ± 6	-5 ± 4	18 ± 6	$(276 \pm 20, -16 \pm 14)$
Non-def	1	-6 ± 6	-26 ± 6	$+6 \pm 5$	28 ± 6	$(257 \pm 14, +12 \pm 11)$
	2	-3 ± 8	-32 ± 8	$+9 \pm 5$	33 ± 8	$(263 \pm 16, +16 \pm 11)$

Table 5. Glide component of VSH analysis for the *Gaia* DR1 and VLBI positional offsets.

Group	$l_{\max}$	G_1 (μas)	G_2 (μas)	G_3 (μas)	G (μas)	Apex ($^\circ$)
ICRF2 – <i>Gaia</i> DR1						
All	1	-104 ± 18	$+153 \pm 18$	$+172 \pm 17$	254 ± 17	$(124 \pm 6, +43 \pm 4)$
	2	-64 ± 21	$+90 \pm 22$	$+176 \pm 18$	209 ± 19	$(125 \pm 11, +58 \pm 6)$
Defining	1	$+51 \pm 28$	$+152 \pm 28$	$+106 \pm 27$	192 ± 28	$(71 \pm 10, +33 \pm 8)$
	2	$+65 \pm 32$	$+57 \pm 35$	$+96 \pm 29$	129 ± 31	$(41 \pm 23, +48 \pm 14)$
Non-def	1	-219 ± 24	$+140 \pm 23$	$+208 \pm 21$	334 ± 23	$(148 \pm 5, +39 \pm 4)$
	2	-208 ± 31	$+140 \pm 30$	$+237 \pm 24$	346 ± 27	$(146 \pm 7, +43 \pm 5)$
gsf2016a – <i>Gaia</i> DR1						
All	1	-112 ± 16	$+140 \pm 16$	$+81 \pm 15$	197 ± 16	$(129 \pm 5, +24 \pm 5)$
	2	-64 ± 19	$+77 \pm 20$	$+85 \pm 16$	132 ± 18	$(130 \pm 11, +40 \pm 8)$
Defining	1	$+54 \pm 27$	$+136 \pm 27$	$+13 \pm 26$	147 ± 27	$(68 \pm 11, +5 \pm 10)$
	2	$+47 \pm 30$	$+37 \pm 33$	$+11 \pm 28$	61 ± 31	$(38 \pm 31, +11 \pm 26)$
Non-def	1	-226 ± 21	$+126 \pm 21$	$+110 \pm 19$	281 ± 21	$(151 \pm 5, +23 \pm 4)$
	2	-182 ± 27	$+113 \pm 27$	$+142 \pm 20$	257 ± 26	$(148 \pm 7, +33 \pm 5)$
ICRF2 – gsf2016a						
All	1	$+10 \pm 3$	$+21 \pm 3$	$+59 \pm 3$	64 ± 3	$(63 \pm 9, +68 \pm 3)$
	2	$+14 \pm 4$	$+19 \pm 4$	$+74 \pm 4$	78 ± 4	$(54 \pm 11, +72 \pm 3)$
Defining	1	$+13 \pm 4$	$+24 \pm 4$	$+57 \pm 4$	64 ± 4	$(60 \pm 10, +64 \pm 4)$
	2	$+18 \pm 5$	$+26 \pm 6$	$+69 \pm 5$	76 ± 5	$(55 \pm 11, +65 \pm 4)$
Non-def	1	$+8 \pm 6$	$+16 \pm 6$	$+52 \pm 6$	55 ± 6	$(63 \pm 20, +71 \pm 6)$
	2	$+4 \pm 7$	$+21 \pm 7$	$+64 \pm 7$	67 ± 7	$(79 \pm 21, +71 \pm 7)$

errors. Comparing directly the positions between the ICRF2 and gsf2016a catalogs, we found the largest component of rotation vector R_2 to be $20 \sim 30 \mu\text{as}$. This result is similar to those of Tables 1 and 2, indicating that the ICRF2 and gsf2016a are consistent within several tens of μas when considering only the rotation vector.

Table 5 reports the glide component in the VSH analysis of the positional offsets among the *Gaia* DR1, ICRF2, and gsf2016a catalogs. For $l_{\max} = 1$, the glide component was on the order of $100 \mu\text{as}$ both for ICRF2 and gsf2016a catalogs referring to *Gaia* DR1, slightly larger than that in Mignard et al. (2016). Theoretically, part of the observed glide component between

Fig. 4. Declination residuals for 290 ICRF2 defining sources after the adjustment of the first-degree VSH functions based on the solution of the group “Defining”, in sense of ICRF2 minus gsf2016a. The large positive offsets in the southern hemisphere in Fig. 3 are reduced but still show a $\sin 2\delta$ -like pattern.

Gaia DR1 and VLBI catalogs is supposed to be the accumulative Galactic aberration effect over the J 2000.0 ~ J 2015.0 period caused by the Solar acceleration relative to the Galactic Center (see, e.g., Malkin 2016). The Galactic aberration would induce a dipolar proper motion for quasars and cause a time-dependent orientation between ICRF and *Gaia* reference frames. Assuming the Galactic aberration constant to be $5 \mu\text{as yr}^{-1}$, the amplitude of the glide induced by the Galactic aberration is supposed to be of $75 \mu\text{as}$ and pointed to the anti-Galactic center (we take VLBI minus *Gaia* in sense). The obtained glide, however, was 2–4 times as large and the direction of glide vector was far away from the Galactic center and anti-Galactic center (last column in Table 5). Moreover, the glide obtained from different groups in the same catalog did not give consistent results in terms of the amplitude and the direction. Consequently, the obtained glide vector was interpreted as the dipolar deformation between *Gaia* and VLBI positions.

The positional offset between ICRF2 and gsf2016a catalogs showed a glide larger than $50 \mu\text{as}$, mainly directed along the Z-axis. Since G_3 only appears in the expression of $\Delta\delta$ (Eq. (3)), it can therefore only partly explain the declination bias of $\sim 100 \mu\text{as}$ seen in Fig. 3. Figure 4 shows the declination residuals for 290 common ICRF2 defining sources after the adjustment of parameters in the first-degree VSH fitting using the “Defining” group. One can see that large positive offsets in the southern hemisphere in Fig. 3 are reduced, but still a pattern that looks like a $\sin 2\delta$ can be found.

The analysis of the first-two-degree VSH ($l_{\text{max}} = 2$) gave relatively consistent rotation and glide vectors with that of $l_{\text{max}} = 1$ regarding their formal errors. Between *Gaia* DR1 and two VLBI catalogs, the quadrupole terms gave the consistent result and were estimated to be of the same order as rotation and glide, that is, of $\sim 100 \mu\text{as}$. Based on the same catalogs, different groups gave inconsistent results, especially for the “Defining” group which showed a quadrupole component $M_{2,1}^{\text{Im}}$ as large as $\sim 300 \mu\text{as}$. Figure 5 plots the residual of adjustment of the parameters in the VSH analysis of $l_{\text{max}} = 2$ using the “All” group. The pre-fit weighted rms of $\Delta\alpha^*$ and $\Delta\delta$ are $1365 \mu\text{as}$ and $1588 \mu\text{as}$ for ICRF2 minus *Gaia* DR1; and $1522 \mu\text{as}$ and $2148 \mu\text{as}$ for gsf2016a minus *Gaia* DR1. Performing the VSH analysis of the first degree, the post-fit weighted rms of $\Delta\alpha^*$ and $\Delta\delta$ are $1357 \mu\text{as}$ and $1578 \mu\text{as}$ for ICRF2 minus *Gaia* DR1; and

$1516 \mu\text{as}$ and $2145 \mu\text{as}$ for gsf2016a minus *Gaia* DR1. After the VSH analysis of the first two degrees, the post-fit weighted rms of $\Delta\alpha^*$ and $\Delta\delta$ are $1355 \mu\text{as}$ and $1574 \mu\text{as}$ for ICRF2 minus *Gaia* DR1; and $1514 \mu\text{as}$ and $2140 \mu\text{as}$ for gsf2016a minus *Gaia* DR1. As a result, the VSH fittings improved the positional offset between *Gaia* DR1 and VLBI catalogs; however, this improvement is insignificant compared to the positional offset.

Between ICRF2 and gsf2016a catalogs, we found a significant quadrupole term $E_{2,0}$ relative to the formal error, which would cause a pattern of $\sin 2\delta$ in the declination offset. Figure 6 plots the declination residuals for 290 common ICRF2 defining sources after the adjustment of parameters in the first-two-degree VSH fitting using the “Defining” group. We found that the patterns seen in Fig. 3 were clearly removed. The weighted rms of declination offsets in Figs. 3, 4, and 6 are $101 \mu\text{as}$, $64 \mu\text{as}$, and $64 \mu\text{as}$, respectively. We, therefore, concluded that there are two, mainly deformation terms of $\sim 50 \mu\text{as}$ between ICRF2 and gsf2016a, leading to the declination offsets between these two VLBI catalogs.

Table 6 displays the correlation coefficients between parameters in the VSH fittings, from which one could find several correlation coefficients larger than 0.4, for example, between G_2 and $M_{2,1}^{\text{Re}}$. This indicates that estimating quadrupole terms would affect the determination of rotation and glide components; although the estimated rotation and glide are roughly consistent for $l_{\text{max}} = 1$ and $l_{\text{max}} = 2$. Comparing Eq. (3) with Eq. (4), we can easily find that G_2 and $M_{2,1}^{\text{Re}}$ have the same coefficient ($-\cos \alpha \sin \delta$) in the declination component. Things are similar between G_1 and $M_{2,1}^{\text{Im}}$, R_1 and $E_{2,1}^{\text{Im}}$, and R_2 and $E_{2,1}^{\text{Re}}$. Probably, these similarities in coefficients (elements of the Jacobian matrix) make the simultaneous estimation of these parameters more sensitive to the number of sources and their distribution in the sky. We thus used all 2191 common sources between ICRF2 and *Gaia* DR1 and performed the VSH fittings. The results were consistent with those in Tables 4, 5 and 7 but the correlation coefficient between G_2 and $M_{2,1}^{\text{Re}}$ reduced down to 0.5, although it still showed a strong correlation. These strong correlations, therefore, are possibly because the sample did not distribute uniformly in the sky (some sparse areas can be seen in Fig. 2). In this case, the requirement of orthogonality conditions for VSH analysis was not satisfied.

5. Concluding remarks

We analyzed the global position difference between ICRF2 and gsf2016a catalogs referring to the *Gaia* DR1 auxiliary solution. Some inconsistencies between ICRF2 and gsf2016a catalogs are found, together with possible deformations taking place between *Gaia* DR1 and the two VLBI catalogs.

The orientation angles of ICRF2 and gsf2016a catalogs relative to *Gaia* DR1 agree well with the claimed alignment accuracy of *Gaia* DR1 reference frame to ICRF2. The opposite orientation between the groups “North” and “South”, presented both in ICRF2 and gsf2016a catalogs, indicates possible deformations taking place between VLBI and *Gaia* DR1 catalogs. If we consider that the *Gaia* DR1 represents a rigid frame due to the well-designed principle of *Gaia* astrometric observations, there would be possible North-South deformations in the VLBI catalogs. The declination bias of ~ 0.1 mas between *Gaia* DR1 and ICRF2 reported in Mignard et al. (2016) is found to be most probably caused by the source position errors in the southern hemisphere of ICRF2. Direct comparison of ICRF2 and gsf2016a

Fig. 5. Residual plot after adjustment of the first two-degree VSH for the group “All”. *Top left*: the right ascension component of “ICRF2 – *Gaia* DR1”. *Top right*: the declination component of “ICRF2 – *Gaia* DR1”. *Bottom left*: the right ascension component of “gsf2016a – *Gaia* DR1”. *Bottom right*: the declination component of “gsf2016a – *Gaia* DR1”. Symbols show defining sources as blue circles and non-defining sources as red crosses.

Fig. 6. Declination residuals for 290 ICRF2 defining sources after the adjustment of the first two-degree VSH functions based on the solution of the group “Defining”, in sense of ICRF2 minus gsf2016a. The patterns seen in Fig. 3 are clearly removed.

declinations reveals some declination-dependent patterns; however, these patterns are not like a bias or linear.

The VSH analysis indicates that there are some other systematics between *Gaia* DR1 and the two VLBI catalogs, causing a dipolar deformation on the order of $100 \mu\text{as}$. Besides, the positional offsets of ICRF2 defining sources yield a large quadrupole term of $300 \mu\text{as}$, which is significant regarding the accuracy of *Gaia* DR1 and VLBI catalogs and thus requires a careful check. The VSH analysis of the positional offsets between ICRF2 and gsf2016a gives an interesting result. On

the one hand, the rotation component shows that these two VLBI catalogs are generally consistent within $30 \mu\text{as}$. On the other hand, the glide component and quadrupole component report two declination-dependent deformations in the declination offsets: dipolar deformation along the Z-axis, and quadrupolar deformation that would induce a pattern of $\sin 2\delta$. These two declination-dependent systematics are not found in previous works and should be explained clearly in ICRF3.

We note that the *Gaia* DR1 is the early stage of the whole *Gaia* mission and there are several shortcomings (Gaia Collaboration 2016b; Lindegren et al. 2016). As a result, using *Gaia* DR1 quasar positions as the reference would introduce some systematics in the final results. Furthermore, the uncertainties given in gsf2016a are the formal errors in the VLBI solution rather than the inflated error as in ICRF2, which means that the positional uncertainty in gsf2016a is underestimated. In view of future *Gaia* data releases and the next generation of ICRF, the global difference between *Gaia* and VLBI positions, as well as their own systematics, will be seen more clearly.

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Table 6. Correlation coefficients of parameters in the solution of group “All” for “ICRF2 – *Gaia* DR1” in Table 6.

	G_1	G_2	G_3	R_1	R_2	R_3	$E_{2,2}^{\text{Re}}$	$E_{2,2}^{\text{Im}}$	$E_{2,1}^{\text{Re}}$	$E_{2,1}^{\text{Im}}$	$E_{2,0}$	$M_{2,2}^{\text{Re}}$	$M_{2,2}^{\text{Im}}$	$M_{2,1}^{\text{Re}}$	$M_{2,1}^{\text{Im}}$	$M_{2,0}$
G_1	+1.0	−0.3	+0.0	−0.0	+0.3	−0.0	+0.0	+0.0	+0.2	+0.2	−0.0	−0.0	−0.1	−0.4	+0.5	−0.0
G_2		+1.0	+0.0	−0.3	+0.0	−0.0	+0.0	−0.0	−0.2	−0.1	−0.0	+0.0	−0.0	+0.6	−0.4	+0.1
G_3			+1.0	+0.0	+0.0	+0.0	+0.0	−0.0	−0.0	−0.0	−0.3	−0.0	−0.1	−0.0	+0.0	−0.0
R_1				+1.0	−0.3	−0.0	−0.0	−0.0	+0.4	−0.4	−0.0	−0.0	−0.0	−0.2	−0.2	+0.0
R_2					+1.0	+0.0	−0.0	+0.0	−0.4	+0.5	+0.1	+0.0	−0.0	+0.2	+0.2	+0.0
R_3						+1.0	−0.1	−0.0	+0.0	−0.0	−0.0	+0.0	−0.0	+0.0	+0.0	+0.3
$E_{2,2}^{\text{Re}}$							+1.0	+0.0	−0.0	+0.1	−0.0	−0.0	+0.0	−0.0	−0.1	−0.1
$E_{2,2}^{\text{Im}}$								+1.0	+0.0	+0.0	−0.0	−0.0	+0.0	−0.0	−0.0	−0.0
$E_{2,1}^{\text{Re}}$									+1.0	−0.2	−0.1	+0.0	+0.1	−0.2	+0.0	−0.0
$E_{2,1}^{\text{Im}}$										+1.0	+0.1	−0.0	+0.0	+0.0	+0.2	+0.0
$E_{2,0}$											+1.0	+0.1	+0.1	−0.0	−0.0	−0.0
$M_{2,2}^{\text{Re}}$												+1.0	+0.0	+0.0	+0.0	−0.0
$M_{2,2}^{\text{Im}}$													+1.0	+0.0	−0.0	−0.0
$M_{2,1}^{\text{Re}}$														+1.0	−0.2	+0.1
$M_{2,1}^{\text{Im}}$															+1.0	−0.1
$M_{2,0}$																+1.0

Notes. Other solutions in Table 6 showed similar correlations. The correlation of parameters (rotation and glide components) in the solutions in Tables 4 and 5 was also similar to that presented in this table.

Table 7. Quadrupole terms of VSH analysis of *Gaia* DR1 and VLBI positional offsets.

Group	$E_{2,2}^{\text{Re}}$ (μas)	$E_{2,2}^{\text{Im}}$ (μas)	$E_{2,1}^{\text{Re}}$ (μas)	$E_{2,1}^{\text{Im}}$ (μas)	$E_{2,0}$ (μas)	$M_{2,2}^{\text{Re}}$ (μas)	$M_{2,2}^{\text{Im}}$ (μas)	$M_{2,1}^{\text{Re}}$ (μas)	$M_{2,1}^{\text{Im}}$ (μas)	$M_{2,0}$ (μas)
ICRF2 – <i>Gaia</i> DR1										
All	$+24 \pm 12$	$+20 \pm 11$	-96 ± 27	$+56 \pm 27$	-17 ± 21	$+39 \pm 11$	-41 ± 12	-58 ± 28	$+86 \pm 27$	-93 ± 21
Defining	$+24 \pm 22$	$+41 \pm 19$	-85 ± 42	$+24 \pm 41$	$+86 \pm 33$	$+59 \pm 17$	-63 ± 19	-19 ± 44	$+302 \pm 43$	-34 ± 33
Non-def	$+16 \pm 15$	$+3 \pm 15$	-101 ± 37	$+7 \pm 38$	-96 ± 27	$+13 \pm 14$	-30 ± 15	-46 ± 38	-129 ± 37	-109 ± 27
gsf2016a – <i>Gaia</i> DR1										
All	$+30 \pm 11$	$+17 \pm 11$	-100 ± 25	$+78 \pm 24$	$+36 \pm 18$	$+40 \pm 9$	-53 ± 10	-85 ± 26	$+90 \pm 25$	-70 ± 19
Defining	$+35 \pm 21$	$+48 \pm 18$	-130 ± 39	$+30 \pm 38$	$+162 \pm 31$	$+66 \pm 16$	-56 ± 18	-16 ± 41	$+301 \pm 40$	-19 ± 31
Non-def	$+21 \pm 14$	-2 ± 13	-58 ± 33	$+30 \pm 33$	-51 ± 24	$+11 \pm 12$	-52 ± 13	-96 ± 34	-111 ± 34	-84 ± 25
ICRF2 – gsf2016a										
All	$+1 \pm 2$	$+1 \pm 2$	$+0 \pm 5$	-6 ± 5	-49 ± 4	$+0 \pm 2$	$+1 \pm 2$	$+0 \pm 5$	$+8 \pm 5$	$+0 \pm 4$
Defining	$+4 \pm 2$	-1 ± 2	$+7 \pm 7$	$+7 \pm 7$	-52 ± 5	$+0 \pm 3$	$+2 \pm 3$	$+7 \pm 7$	$+5 \pm 7$	$+7 \pm 5$
Non-def	$+1 \pm 3$	$+2 \pm 3$	-22 ± 9	-17 ± 10	-29 ± 8	$+0 \pm 4$	$+6 \pm 4$	$+12 \pm 9$	$+8 \pm 9$	-9 ± 6

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