Line-of-sight geometrical and instrumental resolution effects on intensity perturbations by sausage modes

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ABSTRACT

Context. Diagnostics of magnetohydrodynamic (MHD) waves in the solar atmosphere is a topic that often encounters interpretation problems, partly because of the high complexity of the solar atmospheric medium. Forward modelling can significantly guide interpretation, bridging the gap between numerical simulations and observations, and increasing the reliability of mode identification for applying MHD seismology.

Aims. We determine the characteristics of the fast MHD sausage mode in the corona on the modulation of observable quantities, such as line intensity and spectral line broadening. Effects of the line-of-sight angle and of spatial, temporal, and spectral resolutions are considered.

Methods. We take a cylindrical tube that simulates a loop in a low-\(\beta\) coronal environment with an optically thin background and let it oscillate with the fast sausage mode. A parametric study is performed.

Results. Longitudinal structuring of the intensity modulation is obtained and set by the nodal structure of the radial velocity. The modulation is strongly dependent on the contribution function of the spectral line. Under the assumption of equilibrium ionisation, the intensity variation can be very low (\(\leq 4\%\) for Fe \(^{17}\)I) or significant (35\% for Fe \(^{21}\)II). Most of this variation disappears when considering the radiative relaxation times of the ions, due to the fast timescales of the sausage mode in the corona. Regardless of the ionisation state of the plasma, the variation in spectral line broadening can be significant, even for low intensity modulation. The nature of this broadening is not thermal but is mostly turbulent. This places spectrometers in clear advantage over imaging instruments for the detection of the sausage mode. The modulation of all quantities can considerably decrease with the line-of-sight angle with respect to the perpendicular to the tube axis. The spatial and temporal resolution are the main factors affecting modulation, erasing longitudinal structuring when these are on the order of the mode’s wavelength or the mode’s period, placing high constraints on instrumentation. Significant variability in all quantities can still be obtained when viewing at an angle of up to 30°, with pixel size resolutions up to one-third of the mode’s wavelength, or temporal resolution of one fifth of the mode’s period. Modulation is only weakly dependent on spectral resolution due to the mode’s inherent symmetry.

Key words. magnetohydrodynamics (MHD) – Sun: corona – Sun: oscillations

1. Introduction

During the past decade solar physics has witnessed a boom in observational reports on wave-like behaviour in all layers of the solar atmosphere (see the recent review by De Moortel & Nakariakov 2012). This is due, on the one hand, to the advances in imaging and spectroscopic instruments, allowing higher spatial, temporal, and spectral resolutions, which have allowed proper visualization of magnetohydrodynamic (MHD) waves with a rather wide range of properties in terms of amplitudes, periods, and speeds. On the other hand, theoretical progress points to the strong potential of waves for explaining the heating demands of the chromosphere and the corona on the observed spatial and time scales, as well as the important role they can play for the indirect estimation of local physical parameters of the plasma (MHD seismology, Roberts et al. 1984; Uchida 1970; Aschwanden 2004; Taroyan & Erdélyi 2009). This of course applies to all physical parameters dictating the behaviour of these waves: the magnetic field strength (Nakariakov et al. 1999; Pascoe et al. 2007b), the magnetic field geometry (Verth & Erdélyi 2008; Ruderman et al. 2008; Van Doorsselaere et al. 2009), the density inhomogeneity (Aschwanden et al. 2003; Goossens et al. 2002, 2008; Arregui et al. 2007), the temperature structure, the response of the plasma to energy injection (polytropic index, Van Doorsselaere et al. 2011b), the plasma \(\beta\) parameter (Van Doorsselaere et al. 2011a), and the transport coefficients (Nakariakov & Verwichte 2005a). Therefore, much emphasis has been put on searching for all kinds of MHD waves, each contributing in a more or less specific way to the measurement of a specific quantity.

The fast MHD sausage mode (\(m = 0\) mode), which we consider in this study, is compressible, characterised by axisymmetric radial displacements of the plasma, having magnetic pressure and gas pressure acting in phase as restoring forces. Thus, this mode does not perturb the main axis of loops but its cross-section, producing intensity variations and spectral line broadening.

The MHD fast sausage mode was first described analytically by Rosenberg (1970), Zaitsev & Stepanov (1975), Roberts et al. (1984), and Cally (1986). Most observations of oscillatory phenomena interpreted as sausage modes have been made in events associated to solar flares, observed with radiometers in the microwave range. These have been most frequently reported using the Nobeyama Radioheliograph (NoRH, Nakajima et al. 1994), with a cadence of 0.1 s and a spatial resolution of 5′′–10′′ observing in microwave frequencies of 17 GHz and 34 GHz.
Imaging Assembly of SDO (Su et al. 2012) and with SECIS meter of Hinode (Kitagawa et al. 2010), with the Atmospheric also exist in extreme ultraviolet (EUV) lines with the EIS spectrometer of Hinode (Kitagawa et al. 2010), with the Atmospheric Imaging Assembly of SDO (Su et al. 2012) and with SECIS (Williams et al. 2002, 2001). Similarly, few reports also exist in cooler (chromospheric and photospheric) lines with ARIES (Srivastava et al. 2008), with the Solar Optical Telescope of Hinode (Fujimura & Tsuchida 2009), and with the ROSA instrument (Morton et al. 2011; Jess et al. 2012; Morton et al. 2012). Most observations of fast sausage modes are linked to quasi-periodic pulsations (QPPs) commonly observed during solar flares in microwave and soft and hard X-ray ranges (Nakariakov & Verwichte 2005b; De Moortel & Nakariakov 2012, for reviews on the subject). As shown by Mossessian & Fleishman (2012), not only can the sausage mode but also the kink and the torsional Alfvén mode lead to modulation of the source parameters (e.g. energetic electron distribution, magnetic field strength, and column thickness along the line-of-sight) resulting in gyrosynchrotron radiation. Nakariakov et al. (2003) show that the period of the sausage mode in the corona is mostly determined by the length of the hosting structure and the external Alfvén speed, thus leading to very short periods. They further show that non-lyeak sausage modes occur in sufficiently thick and dense loops, thus greatly constraining their existence in the solar atmosphere (Nakariakov et al. 2012). It is therefore not surprising that most of the reported sausage modes in the literature come from observations with high cadence instruments, mostly radiometers, and are mostly associated with flaring loops, where densities are high. However, by performing 2D MHD simulations, Pascoe et al. (2007b) have investigated the existence of sausage modes in long coronal loops with weak density contrast by extending the wave numbers into the leaky regime. In flaring conditions, they found sausage modes with periods from 5 s to 60 s of detectable quality in loops of length up to 60 Mm, thus supporting the interpretation from observations of QPPs. In this regime the period of the sausage mode is determined by the length of the loop and the external Alfvén speed, therefore providing a seismological way to measure the latter and the external magnetic field. Very few reports exist, however, of sausage modes in long coronal (non-flaring) loops, a fact that may be linked either to MHD radiation (leaky modes), leading to a poor quality factor for such modes, or to the lack of adequate temporal and spatial resolutions.

In a 3D MHD model De Moortel & Pascoe (2012) analyse the effects of line-of-sight integration on energy budget estimates in multi-stranded coronal loops subject to propagating kink modes. The modes strongly couple to azimuthal Alfvén waves, to which all energy is eventually transferred, resulting in kinetic energy estimates from Doppler shifts one to two orders of magnitude lower than the true wave energy. This suggests that most of the energy could be observed in spectral line broadening.

Cooper et al. (2003a,b) used a 2D model to investigate analytically the modulation of intensity from propagating kink and sausage modes based on variation in the angle between the line-of-sight and the emitting structure. They furthermore consider the effect of curvature and apply the results to explain propagating intensity perturbations along a loop observed with SECIS (Williams et al. 2001, 2002).

Gruszczycki et al. (2012) have performed 3D numerical simulations of (trapped and leaky) sausage modes oscillating in a cylinder, and study the resulting modulation of the intensity along a ray perpendicular to the axis of the cylinder. They consider the variation in the pixel size, thus simulating different spatial resolution during observations, and find that intensity variation essentially disappears for resolutions close to the mode’s wavelength.

These previous works calculate the intensity by integrating the density squared along the line-of-sight, and therefore ignore the radiative response of the plasma and effects from instrumental resolution. Based on numerical simulations, synthetic observations of TRACE channels and Hinode/EIS by De Moortel & Bradshaw (2008) illustrate the ill-posed intensity inversion problem, which can even alter the period of oscillations. Similarly, synthetic observations of AIA channels of SDO by Martínez-Sykora et al. (2011) show that a significant contribution to the emerging intensity can come from non-dominant ions of a specific channel. These results imply that not only density but also ionisation balance and emissivity need to be taken into account for forward modelling intensities.

The application of MHD seismology strongly relies on the capacity to pinpoint the nature of the wave in observations. However, as analytical, numerical, and observational studies show, mode identification is far from a trivial matter. In this work we choose a simple approach to characterise the observable properties of the MHD fast sausage mode in the corona. This approach can be used as a platform for constructing more complex models or can help understand more complex numerical results, such as those coming from 3D numerical simulations. We assume that we have a cylindrical structure in a low-β coronal environment, which offers significant density contrast with the ambient plasma, and hosts the fast sausage mode. By synthesising the emerging intensity in specific coronal lines using the CHIANTI atomic database (Dere et al. 1997, 2009), we investigate the effects from varying line-of-sight angles, as well as effects from spatial, temporal, and wavelength resolutions on the modulation of observable quantities. By doing so we are able to predict the detectability of this mode with current instruments, as well as incoming instruments in the near future.

The paper is structured as follows. In Sect. 2 we describe the different models we considered, and in Sect. 3 we present the results from two different point of views: that of imaging instruments, and that of instruments with spectrometric capabilities. In Sect. 4 we discuss the results and conclude in Sect. 5.

2. Models

2.1. Variation in thermodynamic quantities

In the forward modelling approach, the task of identifying MHD modes in the solar corona starts by implementing these modes in realistic numerical simulations. For the latter, it is necessary first to identify the theoretical observational signatures from such modes, free of non-linear effects. In this work we take such an approach and consider the simplest model of an axisymmetric plasma cylinder of radius $R$ embedded in a low-β coronal environment, oscillating with the sausage mode, i.e. the axisymmetric $m = 0$ mode described in Edwin & Roberts (1983). In this study we ignore the effects of gravity, field-line curvature, and twist. The variation in the thermodynamic quantities is found by
We have perturbed mass density, gas pressure, and magnetic field; and choose our base model to be similar to the simulation model are variations on a "base model". For comparison purposes we with the sausage mode. All the models considered in this work quantities we produce a 3D data cube of a cylinder oscillating around 350 km s\(^{-1}\) and 900 km s\(^{-1}\), respectively. The plasma \(\beta\) parameter is at all times lower than 0.3. The internal and external temperature for the unperturbed cylinder are set in this model to 1.05 \(\times 10^5\) K and 2.4 \(\times 10^5\) K. For a further analogy with Gruszecki et al. (2012), we choose the wavenumber in the base model as \(KR = 2.24\), where \(R = 1\) Mm denotes the radius of the cylinder. This results in a wavelength of \(\approx 2.8\) Mm. The amplitude \(A\) of the standing mode (see Eq. (7)) is chosen so as to generate velocity perturbations in agreement with typical values deduced from spectral line broadening in the corona (Chae et al. 1998; Peter 2010). Accordingly, we choose \(A = 0.011\) (similar to the value used in Gruszecki et al. 2012).

Typical sizes for plasma inhomogeneities in the corona are still not well known. This has led to several debates concerning the concept of loops as monolithic or rather multi-stranded structures in the corona. Currently, state-of-the-art coronal imaging devices such as SDO/AIA with instrumental point spread functions (PSF) in the range 1–1.2 Mm are providing increasing observational evidence for a family of structures with sizes not resolved by the telescopes (Brooks et al. 2012). Higher resolution imaging can be achieved with chromospheric instruments through tracing coronal rain in loops, which has provided evidence of strand-like structures of a few hundred km (Antolin & Rouppe van der Voort 2012). While these works reveal subarcsecond density structure providing support for multi-stranded loop models, it is reasonable to think that the collection of strands composing the loop (defining the main waveguide) is actually much larger and behave collectively, agreeing with our choice of 1 Mm for the radius of our loop. Such families of neighbour strands traced by coronal rain indeed have several Mm in diameters, as seen in Antolin & Verwichte (2011) or Antolin & Rouppe van der Voort (2012). Furthermore, it has been shown that the characteristics of a sausage mode are rather insensitive to the presence of cross-sectional inhomogeneities in loops (Pascoe et al. 2007a, 2009).

Numerically, our numerical model consists of a 204 \(\times 204 \times N_i\) grid. The parameter \(N_i\) denotes the number of points in the \(z\) direction and is chosen so that the different line-of-sight rays for the intensity calculation (explained in Sect. 2.3) traverse the same cross-sectional area in the model. In the base model, three wavelengths are enough, leading to \(N_z = 342\) points. The spatial resolution in \(x, y,\) and \(z\) axes is the same: about 25 km. The fast sausage mode in the corona produces very low cross-sectional area variation, which for some of the considered models leads to very low intensity variations. To correctly calculate the variations in those models we have also considered a numerical model with ten times the resolution in each direction. Correspondingly, all results related to intensity modulation are obtained with the high-resolution models. All other results do not vary significantly between the low and high spatial resolution models.

Figure 1 shows a snapshot of our base model, representing a cut along the middle axis of the cylinder. The sausage mode creates in-phase perturbations between the density and the magnetic field, and anti-phase perturbations between the density and the radius. Furthermore, the radial and longitudinal velocities are \(\pi/4\) out of phase with the density. The snapshot in Fig. 1 is taken at a time of one-third of the period \(P\), which, in this model, corresponds to \(P \approx 4.6\) s. Positive velocity values

2.2. Base model

Once we know the analytical solution for the thermodynamic quantities we produce a 3D data cube of a cylinder oscillating with the sausage mode. All the models considered in this work are variations on a “base model”. For comparison purposes we choose our base model to be similar to the simulation model by Gruszecki et al. (2012). Accordingly, we take a discontinuous density profile with a mass density contrast \(\rho_i/\rho_o = 5\) and a magnetic field ratio \(B_i/B_o = 0.89\) between the interior and the exterior of the unperturbed cylinder. Correspondingly, the Alfven speeds inside and outside the cylinder oscillate around 350 km s\(^{-1}\) and 900 km s\(^{-1}\), respectively. The plasma \(\beta\) parameter is at all times lower than 0.3. The internal and external temperature for the unperturbed cylinder are set in this model to 1.05 \(\times 10^5\) K and 2.4 \(\times 10^5\) K. For a further analogy with Gruszecki et al. (2012), we choose the wavenumber in the base model as \(KR = 2.24\), where \(R = 1\) Mm denotes the radius of the cylinder. This results in a wavelength of \(\approx 2.8\) Mm. The amplitude \(A\) of the standing mode (see Eq. (7)) is chosen so as to generate velocity perturbations in agreement with typical values deduced from spectral line broadening in the corona (Chae et al. 1998; Peter 2010). Accordingly, we choose \(A = 0.011\) (similar to the value used in Gruszecki et al. 2012).

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correspond to outflow towards the axis of the cylinder. From Fig. 1 it can be noticed that the perturbation of longitudinal velocity is about one order of magnitude less than the radial perturbation. They have maximum values of about 19 km s\(^{-1}\) and 3.4 km s\(^{-1}\), respectively. At the location of an anti-node of the radial velocity, density oscillates about 7% around a mean value of 4.9 \times 10^{-12} \text{ kg m}^{-3}, and temperature oscillates about 5% around a mean value of 1.048 \times 10^6 \text{ K}.

2.3. Calculation of synthetic spectra

To calculate synthetic spectra, we choose different viewing angles on the structure, simulating different line-of-sight configurations. Denoting by \(\theta\) the angle between the line-of-sight and the perpendicular to the axis of the cylinder, we consider the cases: \(\theta = 0^\circ, 30^\circ, 45^\circ, 60^\circ\), shown in Fig. 1. For each line-of-sight, we define rays 1 and 2 as two particular rays crossing the cylinder at a node and an anti-node of the radial velocity, respectively (unless stated otherwise, the terms “node” and “anti-node” will refer to the radial velocity amplitude throughout the manuscript).

For simulating observations it is also important to consider spatial, temporal, and spectral resolution of the instrument at hand. For each ray we consider four different resolution “pixels”: “0R” (0 radius, equal to the spatial resolution of our model, i.e. 25 km), “1R” (1 radius \(\approx 1/3\ell\), where \(\ell\) is the wavelength of the mode in the base model), “2R” (2 radii \(\approx 2/3\ell\)), and “3R” (\(\approx \ell\)). These pixel sizes correspond to the dotted squares in Fig. 1. A pixel of 1 R would correspond roughly to the size of the instrumental PSF for the 171 and 193 channels of the AIA instrument. For simulating observations it is also important to consider spatial resolution “pixels”.

We also consider coarser spectral resolutions of \(\Delta \ell = 4.2 \text{ mÅ}\) and \(\Delta \ell = 8.5 \text{ mÅ}\), leading to samplings of 16 and 8 points, respectively.

The quantity that we are mostly interested in synthesising is the specific intensity for optically thin (coronal) plasma along a given line-of-sight:

\[
I_\lambda = A_\lambda g_\ell f_{\ell 0} \int G_{A_\lambda}(T, n_e) n_e^2 d\lambda,
\]

where \(A_\lambda\) is the (coronal) abundance of the element (denoted by its wavelength at line centre \(\lambda_0\)) relative to hydrogen, \(g_\ell\) is the Gaunt factor, \(f_{\ell 0}\) is the oscillator strength of the line, \(G_{A_\lambda}(T, n_e)\) is mostly a temperature-dependent function characterising the response of the plasma for that particular line, \(n_e\) is the electron number density, and the integral is evaluated along a ray crossing the emitting plasma (\(d\lambda\) is an element of length along the line-of-sight). The \(G_{A_\lambda}(T, n_e)\) function depends mainly on the ion population fraction, which can be obtained by solving the time-dependent ion balance equations. While such a treatment would provide a thorough analysis of the radiative response of the plasma, it would take us beyond the scope of this paper (as followed by, e.g. Bradshaw \& Mason 2003). Here, we assume that the plasma is at all times in equilibrium ionisation, and we estimate the effects of non-equilibrium on the observable quantities.

The purpose of this work is not to determine the absolute value of line intensities exactly, but rather to analyse the effect on the intensities from temperature, density and especially the geometry (the line-of-sight rays). We therefore concentrate here on the quantities that compose the integrand in Eq. (13). The calculation of the integral in Eq. (13) for all rays crossing the domain is a computationally expensive procedure that can be considerably sped up with the following techniques. For calculating \(G_{A_\lambda}(T, n_e)\), we produce a look-up table that depends on temperature and density using the CHIANTI atomic database (Dere et al. 1997, 2009). For the latter we choose the chianti collisional ionisation equilibria file (chi\_i\_eq) and coronal abundances (sun\_coronal.abund file, from Feldman 1992). The look-up table is composed of a 2000 \times 100 points uniform sampling in the electron number density \(n_e\) – temperature \(T\) domain (respectively), where log \(n_e\) \([8, 10]\) and log \(T\) \([4.95, 6.5]\), which covers the values obtained in our numerical model. Since the \(G\) function mostly depends upon temperature, the values of the table are only interpolated to the temperature values of each pixel in our model. We produce histograms of the line-of-sight velocity choosing a bin size of 0.5 km s\(^{-1}\) (much smaller than the plasma motions produced by the perturbation) and work with the resulting bins instead of pixel-by-pixel. For each resulting bin we produce a second histogram of the emissivity \(G_{A_\lambda}(T, n_e)n_e^2\) with the data points within the bin. Thanks to the symmetry in our model the bin number necessary for high accuracy for this second histogram is lower than 10 000. The spectral line is then calculated for each emissivity bin by assuming a Gaussian distribution for the plasma. The maximum of the Gaussian is given by the value of the emissivity bin. The width of the Gaussian is set by the thermal broadening, given by the logarithmic average temperature of the pixels within the emissivity bin. The

![Fig. 1. Maps of radial velocity (top-left), longitudinal velocity (top-right), density (bottom-left), and temperature (bottom-right) along the middle of the cylinder for the base model \(\ell = 171\) (see Sect. 2.4 for more details). The snapshot is taken at one-third of the mode period. The black and white dashed lines in the top panels denote the four different line-of-sight angles considered: \(0^\circ, 30^\circ, 45^\circ, \text{ and } 60^\circ\). For each angle two rays along the line-of-sight are plotted, one passing through a node of the radial velocity (left ray of the pair) and one passing through an anti-node of the same quantity (right ray of the pair). The different pixel sizes considered are shown centred at a node: “0R” (\(\approx 25\) km), “1R” = 1 Mm, “2R” = 2 Mm, “3R” = 3 Mm. In the base model, 1R, 2R, and 3R correspond roughly to \(\ell/3, 2\ell/3, \text{ and } \ell\), respectively, where \(\ell\) denotes the wavelength of the mode.](image-url)
displacement of the Gaussian’s centre is set by the bin value of the velocity histogram. The last step consists in integrating along the line-of-sight the Doppler-shifted emission. This involves an interpolation from the values of the cartesian grid of the Doppler-shifted emission to equally spaced points along the line-of-sight. With the outlined method the calculation time of the synthetic spectrum for one line for four different line-of-sight angles is eight to ten times faster than with a normal pixel-by-pixel method.

2.4. Models
The modulation of the intensity due to the sausage mode is analysed in several models which differ in one specific way from our base model.

- The “base model – 171” – We analyse the modulation in intensity for our base model in the transition region line Fe\text{xix} 171.073 Å, which has a formation temperature at \( \log T = 5.9 \) K.
- The “base model – 193” – We analyse the modulation in intensity for our base model in the coronal line Fe\text{xii} 193.509 Å, which has a formation temperature at \( \log T = 6.1 \) K.
- The “high-T model” – The effects of high external temperature are analysed in this model. We use an external temperature of \( 8 \times 10^6 \) K, which results in a slightly higher internal density, with a mean value at the anti-node of \( 5.5 \times 10^{-12} \) kg m\(^{-3}\) and a variation around this value of roughly 7%.
- The “long \( \lambda \) model” – Keeping the same values of internal and external thermodynamic quantities for the unperturbed cylinder (base model), here we model the longest possible wavelength for a non-leaky sausage mode for these conditions: \( =5 \) Mm, which results in a wavenumber of \( kR = 1.25 \). Figure 2 shows a snapshot of a cut along the middle axis of the cylinder for the radial and longitudinal velocities, density, and temperature for this case. The snapshot is taken at one-third of the period, which in this case is 5.8 s. For this model two wavelengths in the \( z \) direction are enough to cover the line-of-sight rays, giving \( N_z = 408 \) grid points. The density and temperature have roughly the same average values as before but now exhibit slightly larger variations at the anti-nodes, about 8.5% and 6%, respectively. The radial and longitudinal velocities now have maxima at 23 km s\(^{-1}\) and 3 km s\(^{-1}\).

3. Results
Since the aim of this work is to identify the observational signatures of the sausage mode in coronal structures, we present the results of our models as they would be perceived by the instruments at hand. We therefore divide the results into two relevant categories depending on the instrument: imaging and spectroscopic.

3.1. For imaging instruments
Figure 3 shows the integrated intensity for the base model – 171 (corresponding to the ten times higher spatial resolution model), obtained by integrating the intensity in Eq. (13) over the full Fe\text{xix} 171 Å line, for the four line-of-sight angles: 0\(^\circ\), 30\(^\circ\), 45\(^\circ\), and 60\(^\circ\). The crosses in each panel denote the location of the 2 line-of-sight rays defined in Sect. 2.3. In each panel, the left and right crosses correspond to the rays crossing a node and an anti-node of the oscillation.
similar to the temperature or density structure, as can be seen in the base model – 193 shown by Fig. 4. This effect is further reinforced because at 0° viewing angle, the rays crossing these regions will cross more material since they only correspond to regions of contraction (higher density). This fact highlights the dominant role of the contribution function \( G_{\nu}(T, \rho) \) in the formation of the emergent intensity. It is important to remind the reader that these results are subject to the assumption of equilibrium ionisation, and therefore the plasma responds instantaneously to the changes in temperature and density from the MHD mode. The limitations of this assumption will be discussed at the end of this section.

Figure 5 shows the evolution of the integrated intensity along the line-of-sight at an angle of 0° for the base model – 171 (left panels) and the base model – 193 (right panels), for rays 1 (top panels) and 2 (bottom panels) crossing at a node and an anti-node of the oscillation, respectively. Any other location along the axis of the cylinder displays features similar to either ray 1 or ray 2. For each ray different spatial resolution pixels are taken (see figure for details). In the case of the base model – 171 we have a very low modulation of the intensity, as compared to the density modulation at the centre of the cylinder. While the latter varies by \( \lesssim 7\% \), the intensity varies by \( \lesssim 2\% \) at an anti-node and is basically negligible at the location of a node. Furthermore, as explained earlier, the variation in the intensity is in anti-phase with that of the density because the contribution function \( G_{171}(T, \rho) \) has a peak at lower temperature values than those of the plasma in the cylinder. The slightly longer column thickness created by the area expansion creates the slight asymmetry between the two dips in the intensity cycle.

This scenario is in sharp contrast with that of the base model - 193, shown in the right-hand panels of Fig. 5. The \( G_{193}(T, \rho) \) function presents a peak at a higher temperature value than that of the plasma inside the cylinder. In this case we thus have in-phase intensity variations with the density (or temperature) profile. Also, as shown in Fig. 6, the \( G_{193}(T, \rho) \) contribution function is significantly more sensitive to the temperature changes inside the cylinder than the \( G_{171}(T, \rho) \) function, leading to intensity variations of \( \approx 35\% \). The difference in intensity from the initial value is greater for the maximum values than the minimum values. This is because the gradient of the \( G_{\nu}(T, \rho) \) function is steeper for both 171 and 193 above its initial value (mainly in the direction of higher temperature) than below the initial value. This effect is further amplified by the density enhancement at a time of contraction, since each pixel along the line-of-sight contributes with the square of the local density value. We further notice two small bumps for ray 1 at times of density extrema when considering pixel sizes different from 0R. These are again due to the combined effect of the steepness of the \( G_{\nu}(T, \rho) \) gradient and enhanced density in regions of contraction, which are within the line-of-sight for coarse pixel sizes.

The variation in the intensity decreases significantly with the pixel size for all models, especially at anti-node locations when viewing at a 0° line-of-sight angle. In the considered models the intensity variation is reduced by factors of 10–17 when increasing the pixel size to 3R. This is expected since a larger pixel size implies a higher probability of crossing mixed regions of expansion and contraction. For the models with a wavenumber \( kR = 2.24 \), the unit of the pixel is slightly larger than one-third of the wavelength, and therefore three pixel units \( \approx 3R \) not only covers the entire region of expansion and contraction, but also produces a slight imbalance between the two, as can be seen in Figs. 3 and 4. At a time of contraction the pixel will therefore cover slightly more expanding material, and vice-versa, resulting in a reversal of the variation in intensity at anti-node locations (ray 2). This can be seen in Fig. 5 for both models, 171 and 193. However, in this case, most of the longitudinal intensity structuring is erased, and with it the difference between the 171 and the 193 line intensity variation. Furthermore, if our pixel is centred on a node, regardless of the size of the pixel, the amount of expansion and contraction will always be similar, thus producing minimal intensity variation. As can be seen in the top right-hand panel of Fig. 5, this variation attains a maximum for a 2R pixel size, which is linked to the fact that the amount of material entering and leaving the line-of-sight is close to a maximum for this size. This of course depends on the shape of the pixel, which in our case is a square.

As explained in the introduction, a common approximation to the intensity calculation is \( I \approx \rho^2l \), where \( l \) is the column thickness along the line-of-sight. In Fig. 7 we compare this approach to the outcomes of the more proper intensity calculation performed in this work, plotting \( \rho^2l \) and the results from the base model – 171 and base model – 193. To clearly show the difference we plot the case of a 0° viewing angle and a pixel size resolution of 0R for ray 2 (anti-node). By following the \( I \approx \rho^2l \) approximation, we find maximum intensity variations below 3%, which match those obtained with the 171 line. However, both profiles are in anti-phase with each other because the Fe IX ion population decreases with increasing temperature for the range of temperatures considered here. The discrepancy in amplitude with the 193 line intensity is obvious. This illustrates the important role of the contribution function \( G_{\nu}(T, \rho) \) in the formation of the emergent intensity.

The variation in the integrated intensity due to different line-of-sight angles is shown in Fig. 8. To show the variation best we fix the pixel size resolution at 0R and consider the base model – 193, for which large intensity variation is found for the temperature and density variations created by the sausage mode. By increasing the line-of-sight angle, the rays cross more regions of hot (contraction) and cold (expansion) plasma, thus reducing the variation in the intensity by a factor of 2.5 (down to \( \approx 10\% \)). For rays crossing nodes (ray 1), as discussed previously, the variation is greatly reduced from the crossing of mixed temperature regions in equal quantities along the rays. As in Fig. 5 (right panel), two small bumps can be seen for non-zero viewing angles produced by the combined effect of the local
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Fig. 5. Integrated intensity along the line-of-sight (normalised with respect to the equilibrium value) for the 0° angle case for the base model −171 (left panels) and the base model −193 (right panels) for two specific rays: ray 1 crossing a node (top most panels) and ray 2 crossing an anti-node (bottom panels), shown with crosses in Figs. 3 and 4. Different colours denote different pixel sizes: \(0R\), \(1R\), \(2R\), and \(3R\) in red, purple, blue, and green, respectively, where \(R = 1\) Mm \(\approx \ell\) denotes the radius of the cylinder and \(0R\) denotes the spatial resolution in the high resolution model: 2.5 km. The black curve denotes the density profile at the centre of the cylinder and the same location along the axis of the cylinder as rays 1 and 2. The intensity range of the top panels is set significantly narrower than that of the bottom panels in order to show the low intensity modulation at the nodes.

Fig. 6. Contribution function \(G_{\lambda0}(T, n_e)\) for Fe IX 171 and Fe XII 193. The maximum formation temperature for these ions are, respectively, \(\log T = 5.9\) and \(\log T = 6.2\) K. The black parallelogram in each surface has its corners defined by the minimum and maximum temperature and density values found in the base model, and therefore includes the \(G_{\lambda0}(T, n_e)\) values used here. The temperature range in the upper panel has been inverted in order to show the parallelogram for the \(G_{171}(T, n_e)\) surface.

Fig. 7. Comparison between an intensity calculated as \(I \approx \rho^2 l\), where \(l\) is the column thickness along the line-of-sight (solid), the base model −171 intensity \(I_{171}(t)\) (dotted), and the base model −193 intensity \(I_{193}(t)\) (dashed) for a viewing angle of 0° and a pixel size resolution of \(0R\) for ray 2. The differences between the lines illustrates the importance of the \(G_{\lambda0}(T, n_e)\) function.

Non-equilibrium ionisation effects

Perhaps the most important assumption in the intensity modulation presented here is to consider that the plasma is at all times in equilibrium ionisation, i.e. that the plasma response to the temperature and density changes produced by the MHD mode is instantaneous. However, this is never the case and significant departures from equilibrium can occur on timescales that can be shorter than the timescale of the driver (De Moortel & Bradshaw 2008). The population densities of the ions in the plasma will vary according to the ionisation and recombination rates, which depend on the thermodynamic conditions at each specific moment of time. The rigorous solution to this problem involves solving the time-dependent ion balance equations, which would take us outside the scope of this paper. However, we can estimate the consequences of non-equilibrium ionisation on the emergent intensity. For this we assume that the plasma follows a Maxwellian distribution at all times. Timescales for ionisation and recombination equilibrium for the ions Fe IX and Fe XII can...
then be obtained through CHIANTI. These values are shown in Table 1 (in the case of a $\kappa$-distribution, as shown by Dzifčáková 2002, the rates would increase leading to smaller timescales than those presented here).

For Fe IX we can see that the ionisation and recombination timescales for reaching equilibrium are of the order of 2 s, which is almost half the period of the sausage mode. This means that at a time of expansion (cooling) the material will have just started being ionised and will therefore start recombining without attaining full ionisation. We therefore have a time lag effect and an attenuation (and deformation) of the intensity profile. The loss in amplitude will be similar to what is obtained when integrating the profile over a period of 2 s, in which case the intensity is reduced by a factor of roughly 1.5. This effect is shown in Fig. 13. For Fe XII the ionisation and recombination timescales are between 13 s and 20 s, that is, considerably larger than the period of our mode. In this case, there would basically be no modulation of intensity.

Non-equilibrium ionisation effects would, however, have no influence on the spectrometric results presented in Sect. 3.2. Indeed, as we see in the next section, most of the spectral broadening has a turbulent nature and is not of thermal origin.

3.2. For spectroscopic instruments

We now analyse the spectral variation caused by the sausage mode, which is of interest for observations performed by spectroscopic instruments. For this we concentrate on rays 1 and 2 alone, simulating slits that would cross the cylinder at a perpendicular angle, centred on a node or an anti-node, respectively. All other positions along the cylinder present features similar to either ray 1 or ray 2.

Figures 9 and 10 show the time variation of the specific intensity $I_{\lambda}$ for the base model – 193 for the line-of-sight angles of 0°, 30°, 45°, and 60° correspond to the red, purple, blue, and green curves, respectively.

![Fig. 8. Same as the right panel of Fig. 5 but fixing the pixel size resolution to 0R and varying the angle of the line-of-sight for the base model – 193. 0°, 30°, 45°, and 60° correspond to the red, purple, blue, and green curves, respectively.](image1)

![Fig. 9. Time variation of the specific intensity $I_{\lambda}$ integrated along ray 1 (left panels) and ray 2 (right panels) for the base model – 171 when viewing at an angle of 0° and for a pixel size of 0R (upper panels) and 2R (lower panels). Contours of the intensity are also shown for better visualisation of the variation.](image2)
The angle dependence of the time variation of the specific intensity $I_0$ for rays 1 and 2 is shown in the right-hand panels of Fig. 11 for the 0R pixel size resolution case of the base model $= 171$. For non-zero viewing angles the rays now cross both regions of expansion and contraction. The Doppler velocity values ensuing from the Gaussian fits are therefore the emission measure weighted averages over these regions. A small contribution also comes from the longitudinal velocity component, but it is one order of magnitude smaller than the transverse velocity component. As observed in Fig. 10, depending on the line-of-sight angle one can at any given time have either a dominating blueshift (30° and 45°) or redshift (60°). The variations in spectral line broadening given by the line width and the $\chi^2$ parameter decrease significantly with the angle when crossing an anti-node (with maximum factors for line width between 5.6 and 11.3 between the models). On the other hand, rays crossing a node have slightly increasing variations in spectral line broadening with angle (below 10%). The maximum velocity component is directed perpendicularly to the cylinder axis. The components creating the width of the spectral line therefore decrease with the sine of the line-of-sight angle. The contribution to the non-Gaussianity of the line from the temperature and density profiles can also be observed at various angles. The bumps in the $\chi^2$ parameter profile created at times of maximum or minimum temperature (and density) at the centre of the cylinder are close to the perturbation created by the radial motions for any angle in the case of ray 1 and for angles $\geq 45^\circ$ for ray 2.

To estimate the respective contribution from turbulence (unresolved velocity perturbations) and temperature to the broadening, we plot in Fig. 12 the time variation of two Gaussian widths obtained from rays 1 and 2 with a viewing angle of 0° and a pixel size of 0R. The Gaussian width corresponding to the thermal broadening contribution is obtained from the average of temperature for the pixels along the line-of-sight crossing the cylinder. The Gaussian width corresponding to the turbulent broadening contribution is obtained from a Gaussian fit to the sum of multiple Gaussians, one for each pixel in the cylinder along the line-of-sight, with a fixed temporal averaged thermal broadening and shifted centre given by the line-of-sight velocity at that pixel. We can see that the turbulent broadening is the main contributor to the spectral line broadening. Only for cases of little plasma motion along the line-of-sight (0° angle and 0R pixel size, or at times of 0 radial velocity) is the thermal broadening comparable to the turbulent broadening.

3.3. Effects of temporal and wavelength resolutions

In Sect. 3.1 we discussed the effects of non-ionisation equilibrium, and in the last section we showed the effects of spatial resolution and line-of-sight angle on the detection of intensity modulation by the sausage mode. In this section we would like to present the main effects of temporal and wavelength resolutions. The temporal and wavelength resolutions of our base model are, respectively, 0.15 s and 1.4 mÅ. Here we discuss the differences introduced by taking temporal resolutions of 1 s and 2 s (0.15 s, 1 s, and 2 s correspond, respectively, to 3%, 22%, and 44% of the mode period), and wavelength resolutions of 4.2 mÅ and 8.5 mÅ (1.4 mÅ, 4.2 mÅ, and 8.5 mÅ correspond, respectively, to 48, 16, and 8 points sampling of the spectral line).
Fig. 11. *Left panel*: pixel size resolution dependence of the time variation of the specific intensity $I$ for the $0^\circ$ angle case of the base model $-171$. *From top to bottom* we show quantities ensuing from a Gaussian fit to the spectral line. The first 3 upper panels correspond to the Doppler velocity, the line width and the goodness-of-fit $\chi^2$ parameter for the case of ray 1 (node). The 3 lower panels show the same quantities for the case of ray 2 (anti-node). Different line styles correspond to different pixel size resolution: 0R (solid), 1R (dotted), 2R (dashed), 3R (dot-dashed). The line width is normalised with respect to the initial value at time $t = 0$. The unit for the $\chi^2$ parameter is the logarithm of the normalised value, where the normalisation factor is the equilibrium value. *Right panel*: angle dependence of the time variation of the specific intensity $I$ for the 0R pixel size case of the base model $-171$. The arrangement of these panels is the same as for the left panels. Different line styles denote different line-of-sight angles: $0^\circ$ (solid), $30^\circ$ (dotted), $45^\circ$ (dashed), $60^\circ$ (dot-dashed). For both left and right panels the variation in time of density (red curve) and radial velocity (blue curve) at the centre of the tube is plotted for reference in arbitrary units in the Doppler velocity panel.

Fig. 12. *Estimation of the spectral line broadening contribution from the unresolved velocity perturbations (which we denote as turbulence) and temperature perturbations*. The Gaussian width corresponding to the thermal broadening contribution (dashed curve) is obtained from the average of temperature for the pixels along the line-of-sight crossing the cylinder. The Gaussian width corresponding to the turbulent broadening contribution (solid lines) is obtained from a Gaussian fit to the sum of multiple Gaussians, one for each pixel in the cylinder along the line-of-sight, with a fixed temporal averaged thermal broadening and shifted centre given by the line-of-sight velocity at that pixel.

Table 1. Estimates of timescales for ionisation (I) and recombination (R) equilibrium for Fe IX and Fe XII inside the model.

<table>
<thead>
<tr>
<th>Ion</th>
<th>$T_{\text{min}} \approx 1 \times 10^6$ K</th>
<th>$n_e_{\text{min}} \approx 2.7 \times 10^9$ cm$^{-3}$</th>
<th>$T_{\text{max}} \approx 1.1 \times 10^6$ K</th>
<th>$n_e_{\text{max}} \approx 3 \times 10^9$ cm$^{-3}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fe IX</td>
<td>2 s (I), 2.1 s (R)</td>
<td>1.3 s (I), 2.1 s (R)</td>
<td>12 s (I), 1.5 s (R)</td>
<td>12.9 s (I), 1.5 s (R)</td>
</tr>
<tr>
<td>Fe XII</td>
<td>22.5 s (I), 1.5 s (R)</td>
<td>12.9 s (I), 1.5 s (R)</td>
<td>22.5 s (I), 1.5 s (R)</td>
<td>12.9 s (I), 1.5 s (R)</td>
</tr>
</tbody>
</table>

Notes. The timescales are given in seconds and are calculated as $1/(n_e \times X(T))$, where $X(T)$ denotes either the ionisation or recombination rate obtained with CHIANTI assuming a Maxwellian distribution for the plasma. The temperature ($T$) and number density ($n_e$) values used for the calculation are extreme values found in the centre of the cylinder.

Figure 13 shows the effect of temporal resolution on the integrated intensity and spectral broadening obtained from the modulation by the sausage mode for the base model $-193$. We choose a viewing angle of $0^\circ$ and ray 2 (anti-node), for which the effects are strongest for the integrated intensity (top panel), line width (third panel from top to bottom), and $\chi^2$ parameter (bottom panel), and a viewing angle of $45^\circ$ and ray 1 (node) for the Doppler velocity (second panel from top to bottom). We also fix the spatial resolution to 0R. Different temporal resolutions are obtained by integrating the intensity profiles over temporal windows corresponding to the designated resolution. Since the period of the sausage mode is about 4.5 s, only a few points of the full profile are obtained per period. To obtain full period profiles, approximately 7 and 13 periods are needed, respectively, for 1 s and 2 s resolutions. Longer time integrations also generate phase differences between the profiles equal to the resolutions of each
Fig. 13. Effects of the temporal resolution on the modulation of observable quantities. We take the base model – 193, fix the pixel size resolution to 0R and consider cadences of “0s” (=0.15 s, solid curve), “1s” (=1 s) ≃ P/5 (dotted curve), and “2s” (=2 s) ≃ 3P/7 (dashed curve), where P ≃ 4.5 s is the period of the mode. The upper panel shows the temporal evolution of the normalised integrated intensity along the line-of-sight for ray 2 taking a viewing angle of 0°. The rest of the panels, respectively from top to bottom, show the temporal evolution of the Doppler velocity, the line width and (logarithm of) the intensity profile for ray 1 for 0s temporal resolution. That of the intensity profile. We choose, however, to correct for this effect and present the shifted profiles in Fig. 13 in order to facilitate comparison.

As seen in the top panel of Fig. 13, the intensity variations from the sausage mode decreases with temporal resolution. Factors ranging from 1.2 to 1.5 were found among the models. Although this effect may not appear as important for strong intensity variations as those obtained for the base model – 193, they are especially relevant for low intensity variations, such as those obtained in the base model – 171. Longitudinal variation can therefore be erased in this case.

In the lower 3 panels of Fig. 13 we show the effects of temporal resolution on the Doppler velocity, the line width and the $\chi^2$ non-Gaussianity parameter obtained from the Gaussian fits to the specific intensity profiles $I_\lambda(t)$. As being the displacement of the bulk of the plasma along the line-of-sight, the Doppler velocity is the least affected quantity, with maxima decreasing from 7 km s$^{-1}$ to ≤5 km s$^{-1}$ (decreasing factors between 1.1 to 1.5 among the models). On the other hand, the strength of the spectral broadening depends mostly on the fast components of the plasma. Correspondingly, the line width variations of about 40% obtained in the model are reduced to 30% and <10% for time cadences of 1 s and 2 s, respectively, compromising its detectability with the current instruments. Accordingly, decreasing factors between 4.6 and 6.3 are found between the models. Similarly, the variation in the $\chi^2$ parameter is reduced (spectra become more and less Gaussian at times of expansion and compression, respectively), especially in the 2 s cadence case, where it is reduced by several orders of magnitude. For the 2 s time cadence, therefore, the spectral line is seen as a profile with almost constant shape and the width roughly equal to the average width of the true profile, but for which bulk Doppler motions can still be observed.

The effects of wavelength resolution on the spectral broadening of the specific intensity profile $I_\lambda(t)$ for the base model – 193 are shown in Fig. 14. As for Fig. 13, here we show the case of ray 1 (node) with a viewing angle of 45° for the Doppler velocity and the case of ray 2 (anti-node) with a viewing angle of 0° for the line width and the $\chi^2$ parameter. We fix the spatial resolution to 0R. Different spectral resolutions are produced by integrating the (high wavelength resolution) intensities over specific wavelength bins. We can see that no changes are produced in the Doppler velocity. This is due to the lack of asymmetries in our model: regardless of the non-Gaussianity of the profiles, they will always be symmetric (with respect to the wavelength centre panel). The upper panel shows the temporal evolution of the Doppler velocity (upper panel), the line width (centre panel) and (logarithm of) the $\chi^2$ non-Gaussianity parameter (lower panel) resulting from Gaussian fits to the specific intensity profile $I_\lambda(t)$ obtained from the base model – 193, for different wavelength resolutions. We consider samplings of 1.4 mÅ (solid curve), 4.2 mÅ (dotted curve) and 8.5 mÅ, leading to 48, 16 and 8 points along the spectral line, respectively. In order to show best the effects of the wavelength we fix the pixel size resolution to 0R and show the case of ray 1 with a viewing angle of 45° for the top panel and the case of ray 2 with a viewing angle of 0° for the middle and bottom panels. The normalisation values are the same as in Fig. 13.
3.4. Differences between models

The results presented in the previous section apply in a qualitative manner to all the models presented in this paper. Apart from the differences in the integrated intensity between the 171 Å line (base model – 171) and the 193 Å line (base model – 193) treated in Sect. 3.1, differences between spectral broadening of the different models were also briefly stated in Sects. 3.2 and 3.3.

Figure 15 shows the time evolution of the spectral line broadening (the line width and the non-Gaussianity $\chi^2$ parameter) resulting from the Gaussian fit to the specific intensity $I_\lambda(t)$ for the different models studied in this work, as indicated in the legend. The normalisation values are the time averages of the corresponding quantities for ray 1 and 0° viewing angle.

![Figure 15](image_url)

As can be seen in the panels containing the line profile width all models except the long $\lambda$ model have essentially the same variation. This is mainly because the same velocity field is achieved for the same wave number. Longer wavelengths (small wave number) produces higher velocity fields, leading to larger variations in line widths. Higher velocities also lead to stronger compression and rarefaction, hence greater variation in temperatures and densities. The effects on the spectral broadening of the line are low, however, since plasmas with a hotter temperature produce lower intensities in the 171 Å line. The longer wavelengths produce wider regions of compression and rarefaction, thus modifying the emission crossed by rays 1 and 2 between the models. This can be observed in the 45° angle case for ray 2, leading to stronger variation in line widths and $\chi^2$ values.

The modulation of the integrated intensity, especially important for imaging instruments, severely depends on the selected spectral line(s) of the observation. In the case of a coronal line formed at temperatures below those present in the structure, such as the 171 Å line for the base model – 171, the intensity is only slightly modulated by the sausage mode, even when increasing the mode’s wavelength, with maximum amplitudes of two to four percent. Such models present intensity variations in anti-phase with the temperature and density variation, due to the negative slope of the ion population function at these temperatures. However, the modulation can be increased by a factor of 10–15 when considering coronal lines with formation temperature higher than that of the plasma, as is the case for the base model – 193. In this case we have an in-phase variation between these quantities.

In our model the intensity is governed by the ion population fraction rather than the density of emitting ions. Indeed, as shown by Fig. 6, the change in the contribution function from the temperature modulation (at average density) is one order of magnitude greater than the change from the density modulation (at average temperature). This implies that non-equilibrium ionisation effects will be important, especially for Fe XII, in which the modulation of intensity would completely disappear for the short timescales of the sausage mode (as discussed in Sect. 3.1).

The important role of the contribution functions of spectral lines,
especially concerning non-equilibrium ionisation effects, have been discussed by De Moortel & Bradshaw (2008). Through synthetic intensity modelling of TRACE channels, the authors show similar results as those stated above. They further show that double periodicities can be obtained from the shape of the response function of the instrument due to perturbations leading to temperatures that drift in and out of the maximum formation temperature of the line.

Variation in the modulation of the intensity by kink and sausage modes due to variation in the angle between the line-of-sight and the emitting structure were first treated analytically by Cooper et al. (2003a,b). Considering the effect of curvature they showed that propagating kink and sausage modes could produce an increase in intensity along part of the loop, such as observed by Williams et al. (2001, 2002). In their work the intensities are approximated by the line-of-sight column thickness $l$ and the density $\rho$, as $I \propto \rho^2 l$. As discussed in Sect. 3.1, the neglect of the contribution function can be misleading, and the variation in line intensities can be severely underestimated. In the present work we have monotonically decreasing dependence on the line-of-sight angle for the range of parameters considered here, matching the results of Cooper et al. (2003a). In Cooper et al. (2003b) the case of a smooth density profile is considered (with the corresponding dispersion relations associated with that profile), which introduces an optimal angle for which the intensity variations are largest. This is because the MHD modes in a 2D model are more compressive, and therefore produce significant density variations outside the cylinder. This effect is, however, severely reduced for 3D geometries, as shown by Luna et al. (2008), suggesting that the existence of an optimal angle could be debated. The effect of such density profiles in a 3D model, such as the one considered here, is the subject of future research.

Gruszczek et al. (2012) have performed 3D numerical simulations of (trapped and leaky) sausage modes oscillating in a cylinder with a smooth density profile and analysed the modulation on the integrated intensity. As in Cooper et al. (2003a), the intensity is approximated by integrating the density squared along the line-of-sight (for a viewing angle of $0^\circ$), but they further consider the pixel size resolution. With the same amplitude as used in this work they find intensity variations of the order of 2% with 0R pixel size resolution, which are strongly reduced by a factor of roughly 15 when increasing the pixel size to 3R (one wavelength), thus matching the results presented here. As can be seen in the table, among all parameters, we find the pixel size resolution to play a dominant role. A pixel size resolution roughly the same as wavelength erases the longitudinal structuring in all models.

The sausage mode in the corona oscillates with relatively short periods. Indeed, in the non-leaky regime and for low-$\beta$ plasma conditions, the period of an MHD sausage mode can be shown to satisfy the relation $P < \frac{4\pi}{\lambda_0}$, where $\lambda_0 \approx 2.4$ is the first zero of the Bessel function $J_0(x)$ (Nakariakov et al. 2003; Kopylova et al. 2007). In our models, the periods oscillate around 5 s, making the cadence of the instrument a very important parameter. Intensity variations can be decreased by a factor of 1.5 and more than three to five periods of the mode need to be observed in order to half resolve the full profile.

All the interpretations as sausage modes in observations are mostly based on qualitative arguments, especially restricted by the spatial resolutions of the instrument, which in most cases does not allow the longitudinal variation of the oscillations to be investigated in detail along the flaring coronal structure. Still, resolutions such as that of NoRH have allowed the detection of different oscillatory power between loop top and footpoint, and allow more precise identification of the mode harmonics (Nakariakov et al. 2003; Melnikov et al. 2005; Inglis et al. 2008; Inglis & Nakariakov 2009). In these works, the fundamental mode and sometimes the first overtone can be identified. As discussed in Andries et al. (2009), observations of higher overtones are specifically important, since they significantly improve physical parameter estimates from application of MHD seismology. Observations of a fundamental mode at the apex of loops would be comparable to the case of ray 2 in our model, while observations towards the footpoints would correspond better to the case of ray 1. Most observations of sausage modes report short and thick loops, with lengths around 25 Mm. In this case, the

Table 2. Influence of line-of-sight angle, and spatial, temporal, and wavelength resolution on the modulation of observable quantities caused by the sausage mode.

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Ray</th>
<th>Amplitude</th>
<th>Angle</th>
<th>Spatial</th>
<th>Cadence</th>
<th>$\lambda$ (mÅ)</th>
<th>Period</th>
</tr>
</thead>
<tbody>
<tr>
<td>Intensity</td>
<td>1</td>
<td>~0</td>
<td>0° → 60°</td>
<td>0 R → 3 R</td>
<td>0 s → 2 s</td>
<td>1.4 → 8.5</td>
<td>~</td>
</tr>
<tr>
<td>Doppler velocity</td>
<td>2</td>
<td>2–4% (35%, 193)</td>
<td>↓ 2.5</td>
<td>↓ 10–17</td>
<td>↓ 1.2–1.5</td>
<td>P</td>
<td></td>
</tr>
<tr>
<td>Line</td>
<td>2</td>
<td>≤1 km s⁻¹</td>
<td>↓ 1</td>
<td>↓ 1</td>
<td>↓ 1.1–1.4</td>
<td>1</td>
<td>P</td>
</tr>
<tr>
<td>width</td>
<td>1</td>
<td>7–20%</td>
<td>↑*</td>
<td>↑*</td>
<td>↑*</td>
<td>↓ 4.6–6.3</td>
<td>↓ 1.04–1.09</td>
</tr>
<tr>
<td>$\chi^2$</td>
<td></td>
<td>2.1–2.9</td>
<td>↓ 4</td>
<td>↓ 4</td>
<td>↓ 4–5</td>
<td>↑ 1.20–1.23</td>
<td>P, P</td>
</tr>
</tbody>
</table>

Notes. Since the sausage mode introduces longitudinal structuring we show values for rays 1 (node) and 2 (anti-node) for geometrical quantities. The amplitude denotes the maximum variation in time with respect to the value at $t = 0$ of the quantity considering all parameters. The unit corresponds to percentage except for the Doppler velocity where it denotes the maximum value, and the $\chi^2$ parameter, where it denotes the variation in orders of magnitude. A range in the values of the quantity corresponds to variations between the models. The values in the other columns denote the factor by which the variation in the quantity is modified when varying the specific parameter of the column. The direction of the parameter variation is indicated in the column head. Up and down arrows (or both) denote, respectively, an increase or a decrease (or both if non-monotonic) by the specified factor as the parameter is varied. An asterisk indicates that the variation in time of the quantity is negligible for the possible observed period in the specific observed quantity, with $P$ the period of the sausage mode.
resolutions of NoRH (5″−10″) corresponds to a pixel size below \(\frac{\lambda}{D}\) or \(\frac{\lambda}{L}\), with \(\ell_0\) and \(\ell_1\) being the wavelengths of the fundamental mode and the first overtone. According to the results presented here a pixel size of \(\frac{\lambda}{D}\) reduces the intensity variations by a factor of 30%−40%. For detecting higher harmonics, the pixel size starts to severely decrease the intensity variation, as seen in the lower bottom panel of Fig. 5. Observations of modes with large line-of-sight angles with respect to the normal to the loop plane can easily have rays crossing mixed regions of expansion and contraction, corresponding for instance to nodes of the first overtone and the fundamental mode. These scenarios would bring results that are qualitatively similar to those obtained in the present model when varying the line-of-sight angle.

### 4.2. Spectral line broadening modulation

Table 2 especially shows that even when intensity variations are low (as in the base model − 171), spectral line broadening can be important and could therefore be observed by current spectrometers. In Sect. 3.2 we have shown that the nature of the spectral line broadening from the sausage mode is not thermal but mainly turbulent broadening. This implies that non-equilibrium ionisation and contraction, corresponding for instance to nodes of the loop plane can easily have rays crossing mixed regions of expansion and contraction, for instance to nodes of the first overtone and the fundamental mode. These scenarios would bring results that are qualitatively similar to those obtained in the present model when varying the line-of-sight angle.

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So far very few reports have existed of periodic spectral broadenings in EUV lines with little or no associated intensity variations interpreted as fast sausage modes. Most of these studies are performed with the Hinode/EIS imaging spectrometer (Culhane et al. 2007), with the 1″ slit (with a pixel size resolution of 2″) and temporal resolutions of the order of 10 s or more. Kitagawa et al. (2010) Fourier analyse EUV intensity, Doppler velocity, and line width time series of data in an active region observed in the Fe XII 195 line. Mss regions were found to exhibit significant correlated intensity and Doppler velocity oscillations, with variations of 0.4% to 5.7% and 0.2 to 1.2 km s\(^{-1}\) respectively, consistent with fast MHD waves modulation. Depending on the significance level of intensity oscillations to Doppler velocity and line width oscillations, the waves were interpreted as either fast sausage modes, Alfvén, or kink modes. However, our results suggest that a low significant level in intensity can be obtained with a sausage mode (any pixel size resolution for 171 line, 3R pixel size resolution for 193), while keeping a relatively high significant level for Doppler velocities and line width (above 10% variation). The long reported periods of around minutes could be produced by leaky fast sausage modes, especially towards the footpoints of loops, as explained below.

Many reports exist of observations in the same lines having similar attributes, interpreted as slow modes, kink modes, or Alfvén waves (see review by De Moortel & Nakariakov 2012). Although the authors discard the sausage mode interpretation for other reasons, the essential characteristic: discarding sausage modes are the long reported periods. Sausage modes with long periods can exist in the corona, as shown by Pascoe et al. (2007b), but are leaky, and therefore their observability is severely limited for ranges matching the reported periods.

Often, observations of propagating disturbances are interpreted as slow modes based on the phase speed closely matching the local sound speed, periods between two and ten minutes, (low) intensity variations (of a few percent with respect to the background intensity) and the intensity fluctuation lagging the Doppler shifts by a quarter period (Wang et al. 2003). Here we would like to stress that it is the combination of all these characteristics that supports such an interpretation. Apart from the first two, (phase speed and period), a sausage mode can also explain the rest (intensity modulation and phase shift, as obtained when observing with a non-0° angle).

Wavelength resolution is found to play a minor role, compared to spatial and temporal resolutions. As shown in Sect. 3.4 only minor differences appear in the spectral broadening (and none in the Doppler velocity) when decreasing the wavelength resolution to only eight points across the spectrum (\(\Delta \lambda = 8.5\) mÅ). This may be due to the symmetric nature of the sausage mode (with respect to the axis of the cylinder), but also to the absence of non-uniformities in density or temperature in the present models. Pascoe et al. (2007a, 2009) have considered the effects of varying loop cross-section and fine multilayered structuring on the resonant periods and the spatial profiles of fast sausage mode oscillations. These numerical studies find that the resonant properties of long-wavelength sausage standing modes of the slab are not sensitive to the details of fine structuring, and the spatial profiles are only weakly affected by the cross-section inhomogeneity. This suggests that the inherent symmetries of the fast sausage mode are rather robust to loop divergence and internal density fine-structuring and, therefore, that the properties of the modulation found for simple cylindrical geometries, such as those used here, are robust as well.

As discussed in the previous section, the detection of sausage modes is severely limited by its leaky nature in most coronal conditions. On the other hand, the lack of reported observations of sausage modes with spectrometers may also be due to an instrumental reason. Our results show that high spatial and temporal resolution in EUV lines is essential for the detection of such waves. Perhaps the most promising instrument for detecting these waves in the near future is the Interface Region Imaging Spectrograph (IRIS), whose launch is scheduled for June 2013. IRIS is specially designed for spectrometric observations of the solar atmosphere in EUV lines with high spatial and temporal resolutions. For instance, observation in the Fe XII 1349 Å line (log \(T = 6.2\) K) will have a cadence of 1–2 s, a spatial resolution of 0.4″ (with a field of view of 0.3″ × 40″), an effective area of 2.8 cm\(^2\), and a wavelength resolution of \(\Delta \lambda = 12.5\) mÅ.

The new Atacama Large Millimeter/submillimeter Array (ALMA) telescope has started to operate and offers unique advantages for solar observations. Spatial resolutions from 0.06″ at 85 GHz to 0.005″ at 950 GHz and short integration times of 32 ms are expected, although a special filter is needed for solar observations, which may considerably reduce the capabilities of the telescope. Nevertheless, flare and chromospheric research

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may considerably benefit from ALMA, especially for fast waves such as the ones studied here.

The results obtained here would correspond to the ideal case of an imaging spectrometer with at least 2 s cadence, a pixel size resolution of at least one wavelength, and a wavelength resolution of at least 8 points across the line. Furthermore no blending of lines emission was considered, as is produced when observing with the channels of the AIA instrument onboard the Solar Dynamics Observatory, no background optically thick contribution and no instrumental noise. Together with the effects of curvature and non uniform media (leading to different wave dispersion relations) these scenarios will be treated in future work.

5. Conclusions

In this paper we have aimed to understand the variations in observable quantities introduced by the fast MHD sausage mode in coronal structures, by considering geometrical and instrumental effects. Complexities introduced by non-uniformity of the cylinder or the background, curved geometries, or complex instrumental effects, such as instrumental noise, are not taken into account. Although important for realistic models of loops, such characteristics are secondary and their effects on intensity modulation cannot be properly tackled before understanding the effects of simpler parameters on simple geometrical models such as the ones considered in this work. Details from the main results of this work can be found in Table 2. The main findings can be summarized as follows.

The intensity modulation strongly depends on the formation temperature of the spectral line with respect to the temperature of the plasma. Assuming equilibrium ionisation, for plasmas with higher temperature than the formation temperature of the line, such as the case of the base model – 193, the modulation is low (2%−4%) and is slightly affected by the geometrical variation of the cylinder. On the other hand, for plasmas with lower temperature than the formation temperature of the line, such as the base model – 193, the modulation matches the thermodynamical evolution (density and temperature), and can therefore be significant (35%). Non-equilibrium ionisation would completely eliminate the Fe XII intensity modulation (and reduce by a factor of 1.5 or more the Fe IX intensity) due to the fast timescales of the sausage mode. Simple approximations to the intensity that take the column thickness into account and disregard the contribution function $G_A(T, n_e)$ can therefore be very misleading.

Depending on the contribution function, the intensity can be in anti-phase with the density (or temperature) profile (case of the base model – 193) or in-phase (case of the base model – 193). The line width and the $\chi^2$ parameter are in phase with the square of the radial velocity. The $\chi^2$ parameter can also respond to the density variation, which becomes significant for coarse pixel size or large viewing angle. The Doppler velocity is in anti-phase with the radial velocity when watching at an angle (non $0^\circ$). Correspondingly, for these angles, the Doppler velocity presents a phase shift of one fourth of the period with the intensity. In accordance with the previous result, the intensity and Doppler velocity exhibit the same periodicity as the mode. Double periodicities are characteristic of the line width and the $\chi^2$ parameter. The $\chi^2$ parameter can present quadruple periodicities for coarse pixel size or large viewing angle.

The detection of intensity modulation from sausage modes strongly depends on the angle of observation. The intensity decreases with the viewing angle (where $0^\circ$ angle denotes the perpendicular to the axis of the cylinder) by a factor of 2.5 for the studied range. Furthermore, the intensity modulation can significantly vary longitudinally (along the axis of the cylinder). Rays crossing the cylinder at nodes exhibit considerably less variation than those crossing the anti-nodes (a factor of 20 or more, depending on the pixel size resolution).

Setting aside equilibrium ionisation effects, the detection of intensity modulation strongly depends on spatial and temporal resolutions. Both can be the dominant parameters, especially if the pixel size is close to the mode’s wavelength or the temporal resolution is close to the mode’s period. A pixel size or a cadence with these values (respectively) can completely erase the longitudinal structuring, therefore eliminating the possibility of detection. Wavelength resolution is not particularly important for the case of sausage modulation. This is due to the inherent symmetry of the sausage mode with respect to the axis of the cylinder, leading to symmetric line profiles. Numerical studies suggest that this and most results presented here may be robust to any inhomogeneities in the model (leading to possible asymmetries), as well as to the effects of varying the cross-section along the cylinder.

Even when the intensity modulation is low, the variation in the Doppler velocity, and especially the line width and the $\chi^2$ non-Gaussianity parameter, can be significant (a factor of up to 40% for line width and up to four orders of magnitude change for the $\chi^2$ parameter), placing spectrometers in a clear advantage over imaging instruments for detecting these waves. This result is independent of the ionisation state of the plasma, since the spectral line is mainly affected by the unresolved turbulent motions rather than the thermal motions. Significant variability in all quantities can still be obtained when viewing at an angle of up to $30^\circ$, with pixel size resolutions up to 1R, or temporal resolution of 1 s and for all considered wavelength resolutions. We consider this to be the most important result of this paper.

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