Theoretical light curves of type Ia supernovae

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ABSTRACT

\textbf{Aims.} We present the first theoretical SN Ia light curves calculated with the time-dependent version of the general purpose model atmosphere code PHOENIX. Our goal is to produce light curves and spectra of hydro models of all types of supernovae.

\textbf{Methods.} We extend our model atmosphere code PHOENIX to calculate type Ia supernovae light curves. A simple solver was implemented which keeps track of energy conservation in the atmosphere during the free expansion phase.

\textbf{Results.} The correct operation of the new additions to PHOENIX were verified in test calculations. Furthermore, we calculated theoretical light curves and compared them to the observed SN Ia light curves of SN 1999ee and SN 2002bo. We obtained LTE as well as NLTE model light curves.

\textbf{Conclusions.} We have verified the correct operation of our extension into the time domain. We have calculated the first SN Ia model light curves using PHOENIX in both LTE and NLTE. For future work the infrared model light curves need to be further investigated.

\textbf{Key words.} supernovae: general – radiative transfer – methods: numerical

1. Introduction

All types of supernovae are important for the role that they play in understanding stellar evolution, galactic nucleosynthesis, and as cosmological probes. Type Ia supernovae are of particular cosmological interest, e.g., because the dark energy was discovered with type Ia supernovae (Riess et al. 1998; Perlmutter et al. 1999).

In dark energy studies, the goal now is to characterize the nature of the dark energy as a function of redshift. While there are other probes that will be used (gravitational lensing, baryon acoustic oscillations), a JDEM or Euclid mission will likely consider supernovae in some form. In planning for future dark energy studies both from space and from the ground, it is important to know whether the mission will require spectroscopy of modest resolution, or whether pure imaging or grism spectroscopy will be adequate. Several purely spectral indicators of peak luminosity have been proposed (Nugent et al. 1995; Hachinger et al. 2006; Bongard et al. 2006; Bröcker et al. 2008; Foley et al. 2008; Chotard et al. 2011). What is required is an empirical and theoretical comparison of both light curve shape luminosity indicators (Pskovskii 1977; Phillips 1993; Riess et al. 1996; Goldhaber et al. 2001) and spectral indicators.

To make this comparison one needs to know more about the physics going on in a supernova explosion and to be able to calculate light curves and spectra self-consistently. Thus, we need to extend our code to time-dependent problems. While our primary focus is on type Ia supernovae, the time-dependent radiative transfer code is applicable to all types of supernovae, as well as to other objects, e.g., stellar pulsations.

In the following we present the methods we used to implement time dependence. First we focus on solving the energy equation (first law) and then present our first theoretical LTE light curves of type Ia supernova events. In a further section, we present results of NLTE model light curve calculations.

2. Energy solver

In our previous paper (Jack et al. 2009), we presented our approach to calculate light curves of type Ia supernovae events. We implemented a simple energy solver into our general purpose model atmosphere code PHOENIX where we kept track of the overall energy change of the radiating fluid and the energy exchange between the matter and radiation. Simple test light curves confirmed that our approach worked correctly. We now present a new approach to calculate theoretical light curves of SNe Ia. Again, we are using a simple solver where we keep track of the energy conservation. In the new approach, we consider only the energy density of the material. We assume free expansion and do not solve the equations of hydrodynamics. In order to obtain the result for the new time step, we use an explicit scheme. We apply this scheme and compute time steps until radiative equilibrium is reached. These are the points in our light curves.

The direct change of the energy density of the material considering absorption and emission of radiation and energy deposition by gamma rays is given by Eq. (96.7) in Mihalas & Mihalas (1984)

\begin{equation}
\rho \left( \frac{dE}{dt} + p \frac{d}{dt} \left( \frac{1}{\rho} \right) \right) = \int (c \chi E - 4 \pi \eta) + \rho e, \tag{1}
\end{equation}

where $\rho$ is the density, $p$ the gas pressure and $e$ is the energy density of the material. The quantities of the radiation field are $\chi$ which is the absorption coefficient, $\eta$ is the emission coefficient and $E = \Phi J$ is the radiation energy density with the mean intensity $J$. To obtain $E$, the radiative transfer equation in spherical symmetry is solved including special relativity. All additional
energy sources are put in $\varepsilon$ such as the energy input from gamma ray deposition. This equation represents the first law of thermodynamics for the material. The change of the energy density of the material depends on the coupling of matter and radiation field, the absorption of gamma-radiation and positron annihilation energy, the expansion work and the change of the ionization and excitation of matter.

Dividing equation \ref{eq:1} by the material density $\rho$ we obtain

$$\frac{de}{dt} = \frac{1}{\rho} \int (c \chi E - 4\pi \eta) \, d\lambda - \frac{1}{\rho} \frac{d}{dt} \rho + \varepsilon. \quad \text{(2)}$$

The radiation energy density is given by $E = \frac{4\pi}{c} J$, where $J$ is the mean intensity. Using this, we obtain for the radiation term

$$\int (c \chi E - 4\pi \eta) \, d\lambda = 4\pi \int (\chi J - \eta) \, d\lambda = 4\pi \int (\chi (J - S)) \, d\lambda, \quad \text{(3)}$$

where $S = \frac{2}{3}$ is the source function. All these quantities can be derived from the solution of the radiative transfer equation. The term of the change of the energy density by the radiation is therefore given by

$$Q = \int \chi (J - S) \, d\lambda. \quad \text{(4)}$$

Another change of the energy density is due to the work $W$ done by the adiabatic expansion of the SN Ia atmosphere. For a discrete step this work is given by

$$W = \rho \left( \frac{1}{\rho_2} - \frac{1}{\rho_1} \right). \quad \text{(5)}$$

The expansion is assumed to be homologous. Since we solve the energy equation for the matter, we do not include the radiation pressure work. Since the system is radiation dominated there is the possibility of numerical inaccuracies in coupling the matter and radiation only by $Q$. For the calculation of the new radii and densities as well as a discussion about the accuracy of this assumption see Jack et al. (2009).

Including all energy changing effects, the new energy density of the material $e_2$ after a discrete time step $\Delta t$ is explicitly given by

$$e_2 = e_1 - \rho \left( \frac{1}{\rho_2} - \frac{1}{\rho_1} \right) + \frac{4\pi}{\rho} \Delta t \int \chi (J - S) \, d\lambda + \varepsilon \Delta t, \quad \text{(6)}$$

where $e_1$ is the old energy density.

To obtain all the needed quantities we have to solve the spherically symmetric special relativistic radiative transfer equation. The advantage of our new approach is that we do not have to iterate for each time step. In our previous paper the calculation of each time step involved an iteration process to obtain the new matter temperature. With the new approach we can calculate the new temperature for the next time step directly from all the known quantities.

The translational energy density of the material is given by

$$e_{\text{trans}} = \frac{3}{2} \frac{p}{\rho} - \frac{3}{2} \frac{R}{\mu}, = \frac{3}{2} N_k kT, \quad \text{(7)}$$

with the mean molecular weigh $\mu$ and the universal gas constant $R$. The gas pressure is represented by $p$ and the density by $\rho$. $T$ stands for the temperature of the material. This equation of the energy density is now used to determine the new temperature after the next time step.

During the first phase of the SN Ia envelope evolution, the material of the atmosphere is hot and, therefore, highly ionized. The energy change due to ionization and excitation changes of the atoms present in the SN Ia atmosphere cannot be neglected. PHOENIX already solves the equation of state (EOS), where all the excitation and ionization stages of the present atoms and molecules are included. Using the EOS, we obtain the overall energy density of the material by the sum of the ionization energy $e_{\text{ions}}$ and the translational energy $e_{\text{trans}}$

$$e = e_{\text{trans}} + e_{\text{ions}}. \quad \text{(8)}$$

Hence, the energy density change of the material goes into a change of the translational energy and the ionization energy, which both depend on the temperature. Therefore, we obtain the new temperature by an iteration scheme. The matter density at the next point in time is determined by homologous expansion. A first temperature guess is used, and the EOS is solved to obtain the ionization energy density. Combined with the translational energy density, the overall energy density is computed. This is checked against the target energy density, which we obtained Eq. (6). If the obtained energy density is incorrect, a new temperature guess is made. This new temperature guess is obtained by assuming a linear dependence of the energy density and temperature. The current temperature guess is iterated to the target energy density. It takes about 5–10 iteration steps to determine the new temperature. If the EOS delivers the correct target energy density, the new temperature of the next time step has been found. The accuracy relative of the energy density in this iteration process is set to $10^{-5}$.

\subsection*{2.1. $\gamma$-ray deposition}

The maximum of the light curve of an SN Ia event is observed around 20 days after explosion. Causing this later maximum of the light curve of an SN Ia event is the energy release into the envelope caused by the radioactive decay of $^{56}\text{Ni}$ and its also radioactive decay product $^{56}\text{Co}$. Therefore, this energy deposition has a strong influence on the energy change of the SN Ia envelope structure. Hence, the energy deposition due to radioactive decay has to be taken into account for the calculation of the SN Ia envelope evolution.

The energy deposition due to the $\gamma$-rays emitted by radioactive isotopes needs to be computed by a radiative transfer solver for the $\gamma$-rays. In this work, we solve the $\gamma$-ray deposition with the assumption of a gray atmosphere for the $\gamma$-rays. Jeffery (1998) did a detailed study of the $\gamma$-ray deposition and pointed out that this is an adequate approach to calculate $\gamma$-ray deposition in SN Ia atmospheres. In the decay of a $^{56}\text{Ni}$ nucleus, a $\gamma$-photon is emitted with an energy of 2.136 MeV. The $^{56}\text{Ni}$ nucleus decays to an $^{56}\text{Fe}$ nucleus and emits a $\gamma$-photon, which has an energy of 4.566 MeV. In the decay of $^{56}\text{Co}$ about 19% of the energy is released by positrons. The positrons are assumed to be locally trapped. They annihilate by emitting two photons each with an energy of 512 keV, which has to be taken into account for the energy deposition calculation. The opacity is considered to be constant and a pure absorption opacity, meaning that no scattering is assumed. As in Jeffery (1998), $\kappa_{\gamma} = 0.06 (Z/A) \text{cm}^2 \text{g}^{-1}$ was chosen as the opacity. $(Z/A)$ is the proton fraction, which is counts both bound and free electrons, since the electron binding energy is small compared to the energy of gamma rays. The energy deposition into the atmosphere per unit time is given by

$$\rho \epsilon = 4\pi \sum f_j,$$
Thus, rewriting Eq. (10), we obtain the time step size change to a prescribed amount of the energy of the material. The idea of the adaptive time step procedure is to limit the energy by the energy transport and the energy deposition by $\gamma$-rays. The energy change due to the expansion is ignored in this case. On the one hand, this energy change depends on the new matter density after the time step, which is unknown because it depends on the size of the time step itself. Furthermore, the energy change because of the expansion is small compared to the changes caused by the energy transport and the energy deposition by $\gamma$-rays. The energy change does not change, the previous time step might have been too large, therefore, the factor $x$ is decreased. This means that for each time step, the allowed energy change is adapted and the factor $x$ is updated to get the optimal time step during the whole evolution of the SN Ia atmosphere.

\[
\Delta e = x \cdot \epsilon = \Delta t \cdot (Q + \epsilon), \tag{10}
\]

where $Q$ is the energy change of the interaction with the radiation, and $\epsilon$ is the energy deposition by the gamma rays. The energy change due to the expansion is ignored in this case. On the other hand, this energy change depends on the new matter density after the time step, which is unknown because it depends on the size of the time step itself. Furthermore, the energy change because of the expansion is small compared to the changes caused by the energy transport and the energy deposition by $\gamma$-rays. The energy change does not change, the previous time step might have been too large, therefore, the factor $x$ is decreased. This means that for each time step, the allowed energy change is adapted and the factor $x$ is updated to get the optimal time step during the whole evolution of the SN Ia atmosphere.

\[
\Delta t = \frac{\epsilon}{Q + \epsilon} \cdot x, \tag{11}
\]

where $x$ is the introduced limiting energy change factor. The factor $x$ ranges between $x_{\text{min}}$ and $x_{\text{max}}$, which mark the largest and smallest allowed energy change. These are input parameters for the adaptive time step procedure. The time step size is calculated for every layer, and the minimum time step size of all layers is used for the energy solver.

In Fig. 1, a comparison of the temperature structure of the energy solver to the result of the temperature correction procedure is shown. The differences in the temperature structure for most layers are less than 1%. But the temperature differences of the inner layers are clearly higher. These differences arise in the PHOENIX temperature correction result which produces a spike in the temperature structure. This is likely due to the boundary condition in the temperature correction. Hence, the resulting temperature structure obtained with the energy solver is more accurate. Here, the temperature structure is smooth. In order to obtain an atmosphere in radiative equilibrium, the energy transport part of the energy solver can be used instead of the temperature correction procedure. The main problem is that about a few hundred time steps are needed to obtain the resulting atmosphere structure in radiative equilibrium, while the temperature correction needs fewer iteration steps and is, therefore, significantly faster.

\[
J = \frac{\rho c^2 v}{\sqrt{1 - \frac{v^2}{c^2}}}, \tag{3.2}
\]

where $J$ is the mean intensity, which has been obtained by solving the gray radiative transfer for the $\gamma$-rays. This obtained energy deposition has to be taken into account for the calculation of the overall energy change.

### 2.2. Adaptive time step procedure

The timescale for energy changes in the SN Ia envelope will change during the evolution of the light curve. In order to save computation time, the light curves have to be calculated with the optimal time step size for each phase of light curve evolution. Therefore, we implemented an adaptive time step routine to determine the optimal time step size for the current time step.

The energy change $\Delta e$ of the energy of the material $e$ may be approximated by

\[
\Delta e = x \cdot e = \Delta t \cdot (Q + \epsilon), \tag{10}
\]

where $Q$ is the energy change of the interaction with the radiation, and $\epsilon$ is the energy deposition by the gamma rays. The energy change due to the expansion is ignored in this case. On the one hand, this energy change depends on the new matter density after the time step, which is unknown because it depends on the size of the time step itself. Furthermore, the energy change because of the expansion is small compared to the changes caused by the energy transport and the energy deposition by $\gamma$-rays. The idea of the adaptive time step procedure is to limit the energy change to a prescribed amount of the energy of the material. Thus, rewriting Eq. (10), we obtain the time step size $\Delta t$ for the current time step by

\[
\Delta t = \frac{\epsilon}{Q + \epsilon} \cdot x, \tag{11}
\]

where $x$ is the introduced limiting energy change factor. The factor $x$ ranges between $x_{\text{min}}$ and $x_{\text{max}}$, which mark the largest and smallest allowed energy change. These are input parameters for the adaptive time step procedure. The time step size is calculated for every layer, and the minimum time step size of all layers is used for the energy solver.

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### 3.1. Energy transport

In this section, the energy transport through the atmosphere is tested. The energy solver considers only the energy change caused by emission and absorption of radiation, where the result of the radiative transfer equation is needed. All other influences are neglected. As a first test, we check how the initial temperature structure changes if the energy solver is changing the SN Ia envelope. As the initial atmosphere structure is already in radiative equilibrium, the energy solver should not change the temperature structure significantly, because it also pushes the atmosphere towards a radiative equilibrium state.

In Fig. 1, a comparison of the temperature structure of the energy solver to the result of the temperature correction procedure is shown. The differences in the temperature structure for most layers are less than 1%. But the temperature differences of the inner layers are clearly higher. These differences arise in the PHOENIX temperature correction result which produces a spike in the temperature structure. This is likely due to the boundary condition in the temperature correction. Hence, the resulting temperature structure obtained with the energy solver is more accurate. Here, the temperature structure is smooth. In order to obtain an atmosphere in radiative equilibrium, the energy transport part of the energy solver can be used instead of the temperature correction procedure. The main problem is that about a few hundred time steps are needed to obtain the resulting atmosphere structure in radiative equilibrium, while the temperature correction needs fewer iteration steps and is, therefore, significantly faster.

### 3.2. Expansion

In a further test calculation, the expansion part of the energy solver is checked. The only energy change considered is the adiabatic cooling due to free expansion of the SN Ia envelope. The energy deposition by $\gamma$-rays or an energy change due to energy transport is disabled. For this test case, the expectation is that the atmosphere should just cool down, so the temperature of the atmosphere and the observed luminosity should be decreasing.
The observed luminosity is shown in Fig. 2. The observed luminosity of the SN Ia atmosphere decreases in time. The temperature structure of the first and the last time step is plotted in Fig. 3. The adiabatic expansion has cooled the atmosphere everywhere, and the new temperature structure is now significantly lower than the initial one.

### 3.3. Energy deposition

To test the energy deposition by the radioactive decay of nickel and cobalt into the SN Ia atmosphere, a test case is considered, where only this γ-ray deposition is calculated with the energy solver. The energy change due to free expansion and energy transport are neglected to see the direct effect of the additional energy put into the test SN Ia atmosphere.

The results of the energy deposition by γ-rays calculation with the energy solver is shown in Fig. 4, where the light curve is plotted. Due to the energy added to the atmosphere, the luminosity seen by an observer increases with time.

### 3.4. Realistic test scenario

After all single effects have been tested, we now calculate a test case where all effects are considered for the solution of the energy solver. Again, the same initial temperature structure is used and we start our calculation at day 10 after the explosion. Free expansion as well as energy deposition and energy transport are active for this computation.

The observed light curve is shown in Fig. 5. The luminosity increases because of the energy input from deposition of energy from the γ-rays produced by decay of nickel and cobalt. It takes a certain time, until the whole atmosphere has relaxed to this new condition. The atmosphere is then in radiative equilibrium state, and the luminosity stays constant. The initial and final temperature structure are plotted in Fig. 6. The energy input caused by radioactive decay has increased the temperature of the whole atmosphere. The atmosphere is heated by γ-ray deposition in the inner part of the atmosphere. Due to this additional energy, the luminosity of these layers increases and the heat is radiated away and absorbed by the surrounding layers. This energy transport takes care that the deposited energy is moving through the whole atmosphere so that the temperature increases everywhere and the additional energy from the radioactive decay is radiated away towards the observer. The atmosphere is then in radiative equilibrium.

### 4. SN Ia model light curves

We now present our first theoretical SN Ia light curves obtained with our extensions to the general purpose model atmosphere code PHOENIX and compare them to observed SN Ia light

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**Fig. 2.** Light curve of a test atmosphere that is just expanding and adiabatically cooling.

**Fig. 3.** Initial and final temperature structure of a test atmosphere which is just expanding and adiabatically cooling.

**Fig. 4.** Light curve of a test atmosphere with energy deposition. Because of the additional energy, the luminosity increases with time.

**Fig. 5.** Model light curve of a realistic test scenario.

**Fig. 6.** Model light curve of a realistic test scenario.
curves. The online supernova spectrum archive (SUSPECT) (Richardson et al. 2001, 2002)\(^1\) provides numerous of observations of different types of supernovae. For this work, the observed light curves of SN 2002bo and SN 1999ee are used to compare them to our results of model light curves. Photometric light curve observations of SN 2002bo in different photometric bands (Benetti et al. 2004) have been obtained. SN 1999ee also has observed spectra (Hamuy et al. 2002) and photometry (Stritzinger et al. 2002).

4.1. Method

The energy solver is now applied to calculate synthetic light curves of SNe Ia. The SN Ia light curve evolution is calculated during the free expansion phase. For the initial model atmosphere structure, the results of the explosion calculation of other groups are used as the input structure. Each layer has a certain expansion velocity, which does not change during the evolution, because homologous expansion is assumed. We start the model light curve calculation a few days after explosion. In the first few days the SN Ia envelope is optically thick and compact. Another point is, in the first few days the SNe Ia light curves are quite faint, and there are almost no observations of this early time phase that have been obtained. Thus, for the model light curve calculation, it is adequate to start the light curve calculation a few days after the explosion. The initial structure is given by the result of the explosion model simulation. The results of the explosion model give the expansion velocities, density structure and the non-homogeneous abundances of all chemical elements present in the SN Ia envelope. The envelope expands for the first few days by assuming homologous expansion. The radii are determined by the expansion velocities and time after explosion. For the first temperature structure guess, the PHOENIX temperature correction procedure has to be obtained an initial temperature structure, which is in radiative equilibrium. Alternatively we could calculate RE models starting at day one.

For the computation of an SN Ia model light curve, we let the energy solver change the obtained initial model atmosphere structure. The atmosphere structure adapts to the new conditions caused by γ-ray deposition and other energy effects. After a certain time, the atmosphere eventually reaches the radiative equilibrium state. A typical time step of an energy change in the model atmosphere is about 0.1 s. It takes about 500 time steps to reach radiative equilibrium depending on in which evolution phase the SN Ia is. For the later phase after the maximum of the SN Ia light curve, fewer time steps are needed. We use this first radiative equilibrium atmosphere structure to calculate a more detailed spectrum, where more wavelength points are used. This model spectrum is then used to obtain the first point of the model light curve for each band by using the filter functions described below. It certainly would require too much computation time to calculate a whole light curve evolution by using the typical time steps of about 0.1 s. Therefore, to obtain the next point of the light curve, big time steps are computed. For these big time steps, the atmosphere is only expanding. This means that neither energy deposition by γ-rays or energy transport through the atmosphere is considered for the solution of the energy solver. After half a day computed with big time steps, the whole energy solver changes the atmosphere structure again and the next point in the light curve is obtained after the atmosphere structure moves back to radiative equilibrium. Even with the use of these big time steps, the radiative transfer for a light curve of 50 days has to be solved about 10 000 times. For normal model atmosphere calculation in PHOENIX with the temperature correction procedure, the radiative transfer equation has to be solved about 100 times, at most. Therefore, the computation of a whole SN Ia model light curve is very computationally expensive, because the solution of the radiative transfer equation has to be obtained too many times. It takes a huge amount of computation time to calculate even simple SN Ia model light curves, even when using only a few wavelength points. Basically, the SN Ia model light curve is a curve consisting of half day points, where the atmosphere is in radiative equilibrium. During the later phase after maximum light, the big time steps have been performed for one or even two days, as the energy changes is the SN Ia atmosphere become smaller.

As described above, a model spectrum is calculated with the obtained atmosphere structure, which is in radiative equilibrium at each half day point of the light curve. To obtain a model light curve for different photometric bands, filter functions were used to calculate the luminosity in different bands. In Fig. 7, an SN Ia model spectrum and the filter functions for the U, B, V, R and I bands are shown. These filter functions are described in Hamuy et al. (1992). With these filter functions, SNe Ia model light curves.

\(^1\) http://suspect.nhn.ou.edu/
curves can now be obtained for these five different photometric bands.

4.2. Light curves of LTE models

For the first calculations of theoretical light curves, the model atmosphere of the SN Ia is considered to be in LTE. For a first approach to obtain model light curves this is adequate. Another reason for the assumption of LTE is that model light curve calculations with an atmosphere treated in NLTE use more computation time. In order to obtain an SN Ia model light curve in reasonable computation time, a model atmosphere in LTE is a necessary assumption. For the model light curve calculations presented in this section the following parameters were chosen. The model atmosphere is divided into 128 layers. The radiative transfer is solved including atomic lines of the Kurucz atomic data line list. The number of wavelength points used for the solution of the radiative transfer is about 2400. For the inner boundary condition of the radiation, we use the nebular boundary condition, which means that the radiation is just passing through the inner empty region, therefore all the radiation is produced by the ejecta itself, there is no inner lightbulb. The outer boundary condition is zero.

For the first LTE light curve calculation, the W7 deflagration explosion model is used to obtain model light curves of SNe Ia in different photometric bands. The first point of the light curve was calculated at three days after the explosion. The method to obtain the theoretical light curves is described in Sect. 4.1.

Before we present our resulting model light curves, we present plots of various terms that change the energy density for several moments in time. In Fig. 8, the energy change due to the expansion is shown for several moments in time. The energy change is decreasing for later days in the light evolution. The additional energy input due to the radioactive decay is shown in Fig. 9. With increasing time, the amount of energy input into the atmosphere decreases. It also shows, that the additional energy is located in the inner part of the envelope, where the $^{56}$Ni has been produced. Figure 10 shows the energy loss due to the emission of radiation. The temperature structures of the atmosphere for several moments in time are shown in Fig. 11.

Figure 12 shows the LTE SN Ia model light curve of the W7-based explosion model in the optical $V$ band. The theoretical light curve accurately reproduces the observed light curves of two SNe Ia. The steep rise of the model light curve beginning at three days after explosion is in agreement with the observed light curves. The maximum of the W7-based model light curve seems to be later than that of the observed light curves. At 20 days after the explosion, the model light curve has its maximum, while the maximum of the observed light curves is around 17 days after the explosion. After maximum, the decline of the light curve of the W7-based model well reproduces the observed light curve. Even up to the later phase at 50 days after the explosion, where the atmosphere becomes significantly thinner, the fit to the observed light curves is quite accurate.
The theoretical light curve in the ultraviolet $U$ band is shown in Fig. 13. Only an observed light curve of SN 1999ee is available. The observational data are scattered. The rise in the beginning as well as the maximum phase is well represented by the model light curve. However, the decline of the theoretical light curve seems to be too steep. This same effect is present in the model light curve of the $B$ band, which is shown in Fig. 14. The first days of the model light curve are too bright compared to both observed SN Ia light curves. The maximum phase of the model light curve is in good agreement with the observed ones. At day 50, the model light curve becomes brighter than the observed light curves.

In Fig. 15, a plot of the model light curve of the $R$ band is shown. The steep rise in the beginning and the maximum phase of the observed SN Ia light curves is well represented by the computed model light curve. However, the theoretical light curve fit becomes worse for later phases. The luminosity of the model light curve seems to rise again at around day 25 after the explosion. Up to day 45, the model light curve has a second bump, which is not observed in the light curves of SN 1999ee and SN 2002bo. In the infrared $I$ band, the decline after the maximum phase is missing, as shown in Fig. 16. As in the $R$ band, the rise in the beginning and maximum are well represented in the model light curve. However, at maximum, the luminosity of the SN Ia model light curve rises further, which is not seen in the observed light curves of SN 2002bo and 1999ee. Around day 30, the difference between model and observed light curve in the $I$ band are about 1 mag. Up to day 50, the model light curve declines, while the observed light curves show their second maximum around 40 days after explosion.

In Fig. 17, we compared the relation $U - B$ of the theoretical and observed light curves. The same comparison for the $B - V$ relation is shown in Fig. 18.

### 4.3. Dynamical models

We have three different results of explosion calculations of SN Ia events. The structure of these models are results from hydrodynamical explosion calculations. One is the W7 deflagration model of Nomoto et al. (1984). The W7 dynamical model assumes that the ongoing explosion is a deflagration. The flame propagates with a velocity lower than the speed of sound outwards. Another possible explosion model is the delayed detonation model. The explosion starts with a deflagration which eventually proceeds to a detonation. We used two different dynamical models named as DD25 and DD16. For more detailed information about the used delayed detonation models see Höflich et al. (2002).
The resulting optical model light curves of the $V$ band are plotted in Fig. 19. The light curve of the DD16 is fainter than the other ones. This is due to the fact that in this explosion model less $^{56}$Ni is produced. The W7 and DD25 model are quite similar. DD25 is slightly brighter than W7. The shape of the light curves are in good agreement with the observed ones. The maximum of the DD16 is later than the one of the W7 and DD25.

In Fig. 20 the light curves in the $I$ band of the three dynamical models are shown. The infrared light curves deviate strongly from the observations. As in the optical light curve, the DD16 light curve is fainter than W7 and DD25. DD16 also has only one maximum and a decline. However, this maximum is later than the observed ones. The DD25 and W7 light curves are still rising after the observed light curves have reached their maximum and are declining. The theoretical light curves in the infrared must be improved for all explosion models.

5. Light curves of NLTE models

The LTE model light curves in the $V$ band and most other bands are in quite good agreement with observed SN Ia light curves. However, in the near-infrared of the $I$ band, the model light curves need improvements especially for the later phase to fit the observational light curves more accurately. So far, the SN Ia model atmosphere is considered to be in LTE during the whole evolution time. In this section, we calculate the model light curves with the assumption of an atmosphere which is not in LTE. The computation of model light curves with SN Ia model atmospheres in NLTE requires a huge amount of computation time. At first, we model light curves with atmospheres in NLTE that are computed with LTE temperature structures. More realistic NLTE model light curves with a temperature structure that adapts to NLTE conditions are computed to investigate the NLTE effects on the model light curves.

The first approach to compute NLTE model light curves is to consider the atmosphere to be in NLTE, but use a fixed LTE temperature structure. For this computation of NLTE model light curves, we used the calculated radiative equilibrium LTE temperature structure of the W7 deflagration model. We keep this temperature structure constant and perform 20 iterations to let the NLTE converge, which is mainly the occupation numbers of the species that are considered for the NLTE calculation. We considered the following species for the calculations in NLTE: H I, He I, He II, C I-III, O I-III, Ne I, Na I, Mg I-III, Si I-III,
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Fig. 20. $I$ band light curves for the dynamical models W7, DD16 and DD25 are compared to the two observed SN Ia light curves.

Fig. 21. Model light curves of the W7 explosion model in the $V$ band. The NLTE model atmosphere has an LTE temperature structure.

Fig. 22. Model light curves of the W7 model in the U band. The NLTE model atmosphere has an LTE temperature structure.

Fig. 23. Model light curves of the W7 model in the B band. The NLTE model atmosphere has an LTE temperature structure.

Fig. 24. Model light curve of the $R$ band is shown. The luminosity of the NLTE light curve is fainter than the LTE light curve. It has almost the same shape. But for the phase after 25 days after the explosion, the NLTE model light curve rises again. The assumption of NLTE does not improve the fit to the observed light curves of SN 1999ee and SN 2002bo. The infrared light curve of the $I$ band is shown in Fig. 25. During the maximum phase, the NLTE light curve is fainter than the LTE light curve. A distinctive maximum is missing in the NLTE model light curve. For the phase between day 15 and day 25, the NLTE model light curve fits the observed SN Ia light curves very accurately. Here, there is a significant improvement compared to the light curve of the LTE model atmosphere. But, after day 25 the NLTE model light curve starts to

S I-III, Ca II, Ti II, Fe I-III and Co II. These are the species that are most abundant in SN Ia atmospheres and mainly contribute to the spectrum. There is only little H and He in SN Ia, and in W7, there is none. However, considering H I, He I and He II in NLTE does not cost much computation time. The advantage of this approach to an NLTE model light curve is that no temperature iterations have to be performed. This reduces the computation time significantly, although about 200 000 wavelength points are calculated instead of 2400 in case of LTE.

In Fig. 21, the SN Ia model light curve in the $V$ band of an NLTE calculation with an LTE temperature structure is shown. The NLTE light curve is fainter than the LTE light curve. During the maximum phase there is about 0.4 mag difference between both light curves. We have to point out that for our NLTE models, the energy is not conserved because the radiation does not thermalize within the envelope. After maximum the NLTE model light curve approaches the LTE light curve and agrees with the observed light curves as well as the LTE light curve. However, the NLTE model light curve in the $V$ band does not agree with the observed light curves very accurately. With the assumption of an atmosphere in LTE, a better fit is obtained, although NLTE is more accurate.

The NLTE model light curve of the $U$ band is shown in Fig. 22. The NLTE light curve shows almost no deviations from the LTE light curve. During the later phase the steep decline is also present in the NLTE model light curves. In Fig. 23, the NLTE model light curve in the B band is presented. The NLTE model light curve is slightly fainter than the LTE light curve. The shape of the NLTE light curve seems to be the same as for the LTE light curve. The NLTE model light curve is also an accurate fit to the observed light curves.

In Fig. 24, the NLTE model light curve of the $R$ band is shown. The luminosity of the NLTE light curve is fainter than the LTE light curve. It has almost the same shape. But for the phase after 25 days after the explosion, the NLTE model light curve rises again. The assumption of NLTE does not improve the fit to the observed light curves of SN 1999ee and SN 2002bo. The infrared light curve of the $I$ band is shown in Fig. 25. During the maximum phase, the NLTE light curve is fainter than the LTE light curve. A distinctive maximum is missing in the NLTE model light curve. For the phase between day 15 and day 25, the NLTE model light curve fits the observed SN Ia light curves very accurately. Here, there is a significant improvement compared to the light curve of the LTE model atmosphere. But, after day 25 the NLTE model light curve starts to
rise and becomes too bright. This is the same problem that already emerged in the LTE light curve.

5.1. NLTE atmosphere structures

We perform a more realistic NLTE calculation of the SN Ia model atmosphere evolution. The temperature structure is now changing and adapting to the new conditions of NLTE. The calculation of an NLTE model light curve takes a huge amount of computation time. Considerably more wavelength points are needed for the calculation of the solution of the radiative transfer. For all the species considered in NLTE, the rate equations have to be solved. Note that a time step in the NLTE calculation is not a real time step. The rate equation changes the energy of the atmosphere, but this is not included in the energy solver. However, it is adequate as the goal is to obtain a temperature structure, where the atmosphere is in radiative equilibrium.

In a first try to calculate a more realistic NLTE light curve, numerous species up to calcium are considered to be in NLTE. These are the species H I, He I, He II, C I-III, O I-III, Ne I, Na I, Mg I-III, Si I-III, S I-III and Ca II. Higher species are neglected because they have more levels, which would increase the computation time significantly. Nevertheless, the computation of an NLTE light curve needs significantly more time than LTE. For this computation of NLTE model light curves, about 200,000 wavelength points need to be calculated, compared to about 2400 wavelength points for a pure LTE light curve calculation. To obtain an NLTE model light curve in a reasonable time, we started the calculation at day 10 after the explosion and used the LTE temperature structure as the initial atmosphere structure. The main focus is to check if the infrared light curves during the later phase can be further improved.

In Fig. 26, the NLTE and LTE light curves of the W7 explosion model in the V band are shown. The maximum phase is not well fitted by the NLTE model light curve. The LTE light curve fits the observed light curves better. At day 20 the NLTE and LTE light curves are almost the same. Compared to the NLTE light curve obtained with the LTE temperature structure, there are only small differences to the NLTE calculation where the temperature structure adapts to the LTE conditions.

In Fig. 27, the I band model light curves of NLTE and LTE are shown. During the maximum phase, the NLTE light curve is fainter than the LTE light curve. Between day 15 and day 25 the NLTE model light curve fits the observed light curves quite accurately. Here, the use of NLTE improves the fit to the observed
light curves. However, we obtained this improvement also with the NLTE model light curve calculated with the LTE temperature structure. At day 25 the NLTE model light curve starts to rise again. Although the consideration of NLTE improves the model light curve in the I band, the problem with a rise in brightness after the maximum remains.

5.2. Line scattering

The fits to the infrared light curves need to be improved, as they are too bright during the phase of 20 to 50 days after the explosion in all models. We found that a change in the ratio of line scattering to absorption in the LTE case improves the fits to the I band light curve. The resulting light curve is shown in Fig. 28. The line scattering is here roughly inversely proportional to the density and was for the figure “hand tuned” to produce a good match. As the density becomes lower due to the ongoing expansion, the scattering becomes more important, as expected. A more detailed investigation of the IR line scattering and its effects on SN Ia light curve modeling will be a topic of future work. To treat this effect more accurately, very detailed NLTE model atoms are required that include the important infrared lines. In the atomic data we have presently available, these lines are mostly “predicted” lines and were not included in the our current NLTE model atoms. This result indicates that an accurate treatment of line scattering and NLTE effects in the IR lines is very important to model and interpret the IR light curves of SNe.

6. Conclusion

We have presented a new approach for an energy solver which can be applied to expanding SN Ia envelopes to compute SN Ia model light curves. Test calculations confirm that the implemented code works properly. We applied the energy solver to calculate SN Ia model light curves during the free expansion phase.

We present the first PHOENIX light curves of type Ia supernovae in different photometric bands. At first, we solved the radiative transfer equation with the assumption of the atmosphere being in LTE. The model light curves were in decent agreement with the observed ones at early times. However, in the infrared I band, the theoretical light curves do not fit the observed light curves. Blinnikov et al. (2006) had the same deviations in their model light curves compared to observations. Their light curve in the I band is also too bright and further rising, even after the maximum in observed light curves. Kasen (2006) presented a detailed study of SN Ia light curves in the near IR. His I band light curve fits the observations better. He also showed how variable and dependent on different parameters the light curves in the near infrared can be.

Three different dynamical models were compared to observed SN Ia light curves. The delayed detonation model DD 16 is unlikely to be the best explosion model because the model light curves are too faint to fit the observed light curves due to the low 56Ni mass. The results of the W7 model are the best fit to the observed light curves.

For the later phase of the light curves, especially in the infrared, we need the atmosphere to be considered in NLTE. We showed that NLTE model light curves computed with an LTE temperature structure leads to improvements in the model light curves. For future work more investigation of the infrared model light curves and the NLTE needs to be performed. The focus has to lie on the influence of line scattering on the shape of the light curves. It would also be interesting to look in detail on the spectral evolution during the free expansion phase. Further improvements may be achieved with a full 3D radiative transfer and energy solver.

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Fig. 28. Light curves in the I band. The light curve with variable scattering is fainter than the LTE light curve.

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