

Stellar mixing

II. Double diffusion processes[★]

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ABSTRACT

In this paper, *salt-fingers* (also called thermohaline convection) and *semi-convection* are treated under the name of *double-diffusion* (DD). We present and discuss the solutions of the RSM (Reynolds stress models) equations that provide the momentum, heat, μ fluxes, and their corresponding diffusivities denoted by $K_{m,h,\mu}$. Such fluxes are given by a set of linear, algebraic equations that depend on the following variables: mean velocity gradient (differential rotation), temperature gradients (for both stable and unstable regimes), and μ -gradients (DD). Some key results are as follows. *Salt-fingers*. When shear is strong and DD is inefficient, heat and μ diffusivities are identical. *Second*, when shear is weak $K_\mu > K_h$ and the difference can be sizeable $O(10)$ meaning that heat and μ diffusivities must therefore be treated as different. *Third*, for strong-to-moderate shears and for R_μ less than 0.8, both heat and μ diffusivities are practically independent of R_μ . *Fourth*, the latter result favors parameterizations of the type $K_{h,\mu} \sim CR_\mu^0$ suggested by some authors. Our results, however, show that C is not a constant but a linear function of the Reynolds number $Re = \varepsilon(\nu N^2)^{-1}$ defined in terms of the kinematic viscosity ν , the Brunt-Väisälä frequency N , and the rate of energy input into the system, ε . *Fifth*, we suggest that ε is an essential ingredient that has been missing in all diffusivity models, but which ought to be present because without a source of energy, turbulence dies out and so does the turbulent mixing (for example, the turbulent kinetic energy is proportional to the power $2/3$ of ε). Moreover, since different stellar environments have different ε , its presence is necessary for differentiating mixing regimes in different stars. *Semi-convection*. In this case the destabilizing effect is the T -gradient, and when shear is weak, $K_h > K_\mu$. Since the model is symmetric under the change R_μ to R_μ^{-1} , most of the results obtained in the previous case can be translated to this case.

Key words. turbulence – diffusion – convection – hydrodynamics – methods: analytical – stars: rotation

1. Introduction

Double-diffusion (DD) processes (e.g., semi-convection and salt fingers) are important mixing mechanisms, for example, in low-mass red giants (e.g., Eggleton et al. 2006; Charbonnel & Zahn 2007; Denissenkov & Pinsonneault 2008; Cantiello & Langer 2008; Cantiello 2010; Denissenkov 2010). For lack of better models, these processes have thus far been quantified with either empirical relations or results from linear stability analysis, or both. The first methodology has obvious limitations, while the second faces the following problems.

First, linear analyses cannot fix amplitudes, and that explains why most of the results are presented as “ratios” in which amplitudes cancel out, for example, the heat-to-salt flux ratio in the ocean. A satisfactory comparison of such ratio vs. laboratory data (as in the salt-fingers case) is a welcome feature but is no assurance that each individual flux is reliable; and yet, what is required in the astrophysical case are the individual fluxes themselves. *Second*, though based on the results of dynamic equations, results of linear analysis run the risk of overestimating the efficiency of the DD processes. In stars, DD processes do not occur as they do in laboratory conditions chosen to highlight the DD processes alone where there is no shear. Stellar

environments contain shear, which is known to disrupt salt fingers.

Third, none of the DD models based on linear stability analysis (or 2D simulations, Denissenkov 2010) has included shear; this amounts to assuming that the effect of shear is negligible or that the Richardson number is large. However, since when $Ri < 1$ (strong shear), DD processes are considerably weakened, assuming that shear is unimportant is risky at best.

However, we suggest that the most conspicuous shortcoming of all the models proposed thus far is the absence of a physically key ingredient, *the energy required to sustain any type of turbulent motion*. The conceptual underpinning of all models begins with the search for an instability that occurs when $Re \approx Re(cr)$, where Re is the Reynolds number, a process that is ordinarily carried out using linear stability analysis. The next step is to realize that when the instabilities grow, and $Re \gg Re(cr)$, the treatment requires the inclusion of nonlinearities, a feature that is outside the purview of linear models. Nonlinearities, while difficult to treat, have an interesting property: their volume integral is zero, and so they do not generate or destroy energy: they merely distribute whatever energy is available among the different scales.

Since energy is only distributed but not consumed, the energy input into the system percolates unchanged all the way to the smallest scales where irreversible processes such as kinematic viscosity and radiative losses degrade it into heat. That is

[★] This work is dedicated to Aura Sofia Canuto.

why such the energy input equals the dissipation rate, usually denoted by ε ($\text{cm}^2 \text{s}^{-3}$). Without such power, there would be no turbulent motion or, equivalently, turning such power off would lead to a decaying turbulence and ultimately to no mixing. The well-known Kolmogorov law $E(k) = \text{Koe}^{2/3} k^{-5/3}$, which gives the kinetic eddy spectrum generated by the nonlinear interactions, contains ε , which varies from system to system, while the k -dependence of the spectrum has a universal character. Thus, since ε is not and cannot be a universal value and different stellar interiors have different power sources, its presence would ensure that different stellar interiors are characterized by different intensities of mixing. Diffusivity models that do not contain ε lack, in our opinion, a key physical ingredient.

Since the combination (N is the Brunt-Väisälä frequency¹),

$$\frac{\varepsilon}{N^2} \quad (1a)$$

has the dimensions of a diffusivity, and the ratio of (1a) to the kinematic viscosity ν is the Reynolds number

$$\text{Re} = \frac{\varepsilon}{\nu N^2}, \quad (1b)$$

one might conclude that the diffusivities K_α (the subscript α stands for momentum, heat, passive tracer, etc.) in units of the radiative value χ ($\text{cm}^2 \text{s}^{-1}$) are given by the relation:

$$\frac{K_\alpha}{\chi} = \left(\frac{\varepsilon}{\nu N^2} \right) \left(\frac{\nu}{\chi} \right) = \text{Re Pr}, \quad \text{Pr} = \frac{\nu}{\chi} \quad (1c)$$

where Pr is the Prandtl number, which may be as small as 10^{-7} in stellar interiors. A concrete example may help. Consider a fully convective, unstably stratified regime $N^2 < 0$, in which nearly the entire outward flux is carried by convective motion. In a steady state, where production balances dissipation, we have for the $R_\mu = 0$ case

$$F_c = g\alpha\overline{w'T'}, \quad g\alpha_T\overline{w'T'} = \varepsilon, \quad \overline{w'T'} = K_h\beta \quad (1d)$$

and thus

$$K_h = \frac{\varepsilon}{|N^2|} \quad (1e)$$

which shows that (1a) is the physically correct combination to express the diffusivity².

On the other hand, while convection leading to (1e) is an extremely efficient limiting case without competing effects, in regimes with $N^2 > 0$ (stable stratification) mixing may come from: a) shear; b) differential rotation; c) μ -gradients while T -gradients work against it (salt fingers); and d) T -gradients while μ -gradients work against it (semi-convection). In such circumstances, one must account for competing effects, which means that there must be a “mixing efficiency”, usually denoted by Γ , with generalizes (1e) to

$$K_\alpha = \Gamma_\alpha \frac{\varepsilon}{N^2} \quad (1f)$$

¹ We recall the relations $N^2 = -g\rho_0^{-1}\partial\bar{\rho}/\partial z = -gH_p^{-1}(\nabla - \nabla_{\text{ad}})(1 - R_\mu)$, $R_\mu = \nabla_\mu(\nabla - \nabla_{\text{ad}})^{-1}$, $\alpha_\mu\bar{\mu}_{,z} = -H_p^{-1}\nabla_\mu\nabla_\mu \equiv \partial\ln\mu/\partial\ln P$, $\alpha_T[-\bar{T}_{,z} + (\bar{T}_{,z})_{\text{ad}}] = H_p^{-1}(\nabla - \nabla_{\text{ad}})$, $\beta = -\frac{\partial\bar{T}}{\partial z} + (\frac{\partial\bar{T}}{\partial z})_{\text{ad}}$, $\alpha_{T,\mu} = -(\partial\ln\rho/\partial\bar{T})_{p,\mu}$, $(\partial\ln\rho/\partial\bar{\mu})_{p,T}$.

² We recall that $L/M|_{\text{sun}} = O(1) \text{ cm}^2 \text{ s}^{-3} \sim 10^{-4} \text{ W/kg}$, $L|_{\text{sun}} \sim 10^{26} \text{ W}$ ($W = \text{Watts}$); in the convective zone, the mixing length theory gives $\varepsilon(\text{CZ}) : \ell^2 N^3 : \alpha_p^2 H_p^{1/2} g^{3/2} (\nabla - \nabla_{\text{ad}})^{3/2}$ where $\ell = \alpha_p H_p$. In the middle of the solar CZ, $\varepsilon \approx 35 \text{ cm}^2 \text{ s}^{-3}$ (solar code courtesy of Mazzitelli). Below the CZ, the internal gravity waves give $\varepsilon(\text{IGW}) : 10^{-3} \text{ cm}^2 \text{ s}^{-3}$ (Kumar et al. 1999).

and thus

$$\frac{K_\alpha}{\chi} = \Gamma_\alpha \left(\frac{\varepsilon}{\nu N^2} \right) \left(\frac{\nu}{\chi} \right) = \Gamma_\alpha \text{Re Pr}. \quad (1g)$$

As we shall prove below, the RSM (Reynolds stress models) not only give rise to exactly expression (1f), which we arrived at above using heuristic arguments, but it further provides the full form of the dimensionless functions Γ

$$\Gamma_\alpha(\text{Ri}, R_\mu, \text{Pe}, M). \quad (1h)$$

Here, Ri is the Richardson number (measuring the competing effect on the mixing generated by shear and the opposite effect due to stable stratification), R_μ is the density ratio (which measures the DD processes), Pe is the Peclet number defined in (5b), which measures the effect of radiative losses and M represents meridional currents.

Using the general expression (1g), in Sect. 5.1), we show how all previous models have essentially guessed the form of the function (1h) by neglecting all dependences except the one on R_μ , see for example, Eqs. (15d, e). At the same time, they took the Re Pr dependence to be a constant C, an assumption that cannot be valid since, as just discussed, this is a key variable that depends on the particular star one is considering. Relations (1g), (1h) resulting from the RSM model are shown in Figs. 1–3.

The Ri dependence in (1h) requires comments. First, its definition is

$$\text{Ri} = \frac{N^2}{\Sigma^2}, \quad \Sigma = (2S_{ij}S_{ij})^{1/2}, \quad S_{ij} = \frac{1}{2}(\bar{u}_{i,j} + \bar{u}_{j,i}), \quad \bar{u}_{i,j} = \partial\bar{u}_i/\partial x_j \quad (1i)$$

where \bar{u}_i represents the mean flow velocity and S_{ij} the shear. Stable and/or unstable regimes are characterized by the relations

$$\begin{aligned} \text{Stable regime:} & \quad N^2 > 0, \text{ Ri} > 0 \\ \text{Unstable regime:} & \quad N^2 < 0, \text{ Ri} < 0. \end{aligned} \quad (1j)$$

The first regime corresponds to a density profile that decreases with height, while the second regime corresponds to one in which the density profile increases with height as in thermal convection. Next, consider the conditions for semi-convection and salt-finger regimes.

Semi-convection: $\nabla - \nabla_{\text{ad}} > 0$, $\nabla_\mu > 0$, $R_\mu > 0$

Ledoux stable, $N^2 > 0$: $\nabla_\mu > \nabla - \nabla_{\text{ad}}$, $R_\mu > 1$, $\text{Ri} > 0$

Ledoux unstable, $N^2 < 0$: $\nabla - \nabla_{\text{ad}} > \nabla_\mu$, $R_\mu < 1$, $\text{Ri} < 0$ (1k)

Salt fingers: $\nabla_{\text{ad}} - \nabla > 0$, $\nabla_\mu < 0$, $R_\mu > 0$

Ledoux stable, $N^2 > 0$: $\nabla_{\text{ad}} - \nabla > |\nabla_\mu|$, $R_\mu < 1$, $\text{Ri} > 0$

Ledoux unstable, $N^2 < 0$: $|\nabla_\mu| > \nabla_{\text{ad}} - \nabla$, $R_\mu > 1$, $\text{Ri} < 0$. (1l)

Oceanic *salt fingers* correspond to warm-salty over cold-fresh water, a regime in which the z -gradients of T and S are positive. Though the T -gradient is stable and the S -gradient unstable, the overall N^2 is positive, corresponding to a stably stratified regime. The Mediterranean Sea is a known example of such a regime. A *semi-convection* regime, which in oceanography is called *diffusive-convection*, corresponds to cold-fresh over warm-salty water. Both $T - S$ gradients are negative, but N^2 is

positive corresponding to a stably stratified regime. A typical example is water under ice.

In what follows, we present the algebraic 3D solutions of the RSM that provide the ingredients needed to construct $\Gamma_{h,\mu}$. In Sect. 3.6, we work out a physical representation of $\Gamma_{h,\mu}$ that exhibits the shear and DD contributions in a fairly transparent way.

2. Stresses and fluxes

For completeness, we summarize the relevant equations that we have derived in Paper I and that correspond to the local, stationary case.

Reynolds stresses:

$$b_{ij} = R_{ij} - \frac{2K}{3}\delta_{ij};$$

$$b_{ij} = -\frac{8}{75}\tau K S_{ij} - \frac{1}{10}\tau Z_{ij} + \frac{1}{10}\tau B_{ij}. \quad (2a)$$

Vorticity tensor:

$$Z_{ij} = b_{ik}V_{jk} + b_{jk}V_{ik}. \quad (2b)$$

Buoyancy tensor:

$$B_{ij} = g \left(\lambda_i J_j^p + \lambda_j J_i^p - \frac{2}{3}\delta_{ij}\lambda_k J_k^p \right). \quad (2c)$$

Buoyancy-density flux:

$$J_i^p = -\bar{\rho}^{-1}\overline{\rho'u_i} = g^{-1}\overline{b'u_i} = \alpha_T J_i^h - \alpha_\mu J_i^\mu \quad (2d)$$

$$\lambda_i \equiv -(g\bar{\rho})^{-1}\frac{\partial \bar{p}}{\partial x_i}, \quad \tau = \frac{2K}{\varepsilon}, \quad b = -g\bar{\rho}^{-1}\rho. \quad (2e)$$

It is easy to check that all the above tensors are traceless.

Heat fluxes: $\bar{\rho}J_i^h = \overline{\rho u_i' T'}$

$$(\delta_{ij} + \eta_{ij})J_j^h = \gamma_{ij}\beta_j$$

$$\gamma_{ij} = \pi_4\tau(R_{ij} - \pi_2 g\alpha_\mu\tau\lambda_i J_j^h)$$

$$\eta_{ij} = \pi_4\tau[S_{ij} + V_{ij} - g\tau\lambda_i(\pi_5\alpha_T\beta_j + \pi_2\alpha_\mu\bar{\mu}_{,j})]. \quad (3)$$

μ -fluxes: $\bar{\rho}J_i^\mu = \overline{\rho u_i' \mu'}$

$$(\delta_{ij} + \xi_{ij})J_j^\mu = -d_{ij}\bar{\mu}_{,j}$$

$$d_{ij} = \pi_1\tau(R_{ij} + \pi_2 g\alpha_T\tau\lambda_i J_j^h)$$

$$\xi_{ij} = \pi_1\tau[S_{ij} + V_{ij} - g\tau\lambda_i(\pi_2\alpha_T\beta_j + \pi_3\alpha_\mu\bar{\mu}_{,j})] \quad (4a)$$

where:

$$\beta_i = -\frac{\partial T}{\partial x_i} - \lambda_i g c_p^{-1}. \quad (4b)$$

Dissipation-relaxation times scales:

$$\pi_1 = \pi_1^0 \left(1 + \frac{\text{Ri}R_\mu}{a + R_\mu} \right)^{-1}, \quad \pi_4 = \pi_4^0 f(\text{Pe}) \left(1 + \frac{\text{Ri}}{1 + aR_\mu} \right)^{-1}$$

$$\pi_2 = \pi_2^0 (1 + \text{Ri})^{-1} [1 + 2\text{Ri}R_\mu(1 + R_\mu^2)^{-1}], \quad \pi_5 = \pi_5^0 g(\text{Pe}),$$

$$\pi_1^0 = \pi_4^0 = (27 \text{Ko}^3/5)^{-1/2} (1 + \sigma_t^{-1})^{-1},$$

$$\pi_2^0 = 1/3, \quad \pi_3 = \pi_3^0 = \pi_5^0 = \sigma_t$$

$$f(\text{Pe}) = b\text{Pe}(1 + b\text{Pe})^{-1}, \quad g(\text{Pe}) = c\text{Pe}(1 + c\text{Pe})^{-1},$$

$$a = 10, \text{Ko} = 5/3, \quad 4\pi^2 b = 5(1 + \sigma_t^{-1}), \quad 7\pi^2 c = 4\sigma_t^{-1}. \quad (5a)$$

Here, Pe is the Peclet number representing radiative losses,

$$\text{Pe} = \frac{4\pi^2 K^2}{125 \varepsilon \chi}, \quad (5b)$$

where χ ($\text{cm}^2 \text{s}^{-1}$) = $K_r(c_p\rho)^{-1}$ is the thermometric conductivity, $K_r = 4acT^3(3\rho\kappa)^{-1}$ is the radiative diffusivity, and κ is the opacity. In the previous relations, K , ε , and τ are the eddy kinetic energy, its rate of dissipation, and the dynamical time scale, which are related to one another as follows

$$\tau = \frac{2K}{\varepsilon}. \quad (5c)$$

3. The 1D case. Solutions of Eqs. (2–4)

Since Eqs. (3–5) are algebraic relations, in the 1D case the solutions representing the heat, concentration and momentum fluxes have a particularly simple form:

$$\overline{w'T'} = K_h\beta, \quad \overline{w'\mu'} = -K_\mu \frac{\partial \bar{\mu}}{\partial z},$$

$$\overline{w\mathbf{u}} = -K_m \frac{\partial \bar{\mathbf{u}}}{\partial z} \quad (6a)$$

where $K_{h,\mu,m}$ are the T , μ and momentum diffusivities. The simplest representation that emerges from solving the rms equations is (see Eq. C.1 of Paper I)

$$K_\alpha = \tau \overline{w^2} A_\alpha, \quad (6b)$$

where $\overline{w^2}$ is twice the vertical component of the eddy kinetic energy and the A_α are dimensionless functions discussed below. Using the representation (1f), we find

$$\Gamma_\alpha = \frac{1}{2}(\tau N)^2 S_\alpha, \quad S_\alpha = A_\alpha \frac{\overline{w^2}}{K} \quad (6c)$$

where the functions A_α and $\overline{w^2}$ are given next. In Sect. 3.6, we work out a representation of $\Gamma_{h,\mu}$ that exhibits the shear and DD contributions in a transparent way.

3.1. Dimensionless structure functions A_α

The solution of the RSM yields the following results:

$$A_h = \pi_4 [1 + px + \pi_2 \pi_4 x(1 - r^{-1})]^{-1},$$

$$A_\mu = A_h (rR_\mu)^{-1}, \quad A_m = \frac{A_{m1}}{A_{m2}}, \quad (6d)$$

where

$$A_{m1} = \frac{4}{5} - \left[\pi_4 - \pi_1 + \left(\pi_1 - \frac{1}{150} \right) (1 - r^{-1}) \right] x A_h,$$

$$A_{m2} = 10 + (\pi_4 - \pi_1 R_\rho)x + \frac{1}{50}(\tau\Sigma)^2. \quad (6e)$$

The solution of the Reynolds Stresses yields the following result

General case:

$$\frac{\overline{w^2}}{2K} = \frac{1}{3} \left[1 + \frac{2}{15} A_\rho (\tau N)^2 + \frac{1}{10} A_m (\tau\Sigma)^2 \right]^{-1} \quad (6f)$$

$$P = \varepsilon \quad (6g)$$

$$\frac{\overline{w^2}}{2K} = \left[\frac{30}{7} + A_\rho (\tau N)^2 \right]^{-1}, \quad (6h)$$

where we have defined the following dimensionless functions:

$$x \equiv (\tau N_h)^2 = -\tau^2 g H_p^{-1} (\nabla - \nabla_{\text{ad}}) = (\tau N)^2 (1 - R_\mu)^{-1} \quad (7a)$$

$$r = \frac{\text{heat flux}}{\mu - \text{flux}} = \frac{\alpha_T \overline{w'T'}}{\alpha_\mu \overline{w'\mu'}} = \frac{1}{R_\mu} \frac{K_h}{K_\mu} \quad (7b)$$

$$A_\rho = \frac{A_h - R_\mu A_\mu}{1 - R_\mu}. \quad (7c)$$

The model results are as follows:

$$r = \frac{1}{R_\mu} \frac{\pi_4}{\pi_1} \frac{1 + qx}{1 + px} \quad (7d)$$

$$q = \pi_1 \pi_2 (1 + R_\mu) - \pi_1 \pi_3 R_\mu, \quad p = \pi_4 \pi_5 - \pi_2 \pi_4 (1 + R_\mu). \quad (7e)$$

3.2. The variable $(\tau N)^2$. Nonlocal model

As discussed in Paper I, Sect. 6, since the dynamical time scale defined in (5c) depends on the kinetic energy and on its rate of dissipation, one must solve two dynamic equations for K and ε

$$\frac{DK}{Dt} + \frac{\partial F_i^{ke}}{\partial x_i} = P_s + P_b - \varepsilon \quad (8a)$$

$$\frac{2K}{\varepsilon} \frac{D\varepsilon}{Dt} = \frac{1}{2} \frac{\partial F_i^{ke}}{\partial x_i} + c_1 P_b + c_3 P_s - c_2 \varepsilon, \quad (8b)$$

where using (6a), the production due to shear and buoyancy are given by

$$P_s = -(\overline{u'w'u_z} + \overline{v'w'v_z}) = K_m \Sigma^2 > 0 \quad (8c)$$

$$P_b = g \lambda_i J_i^p = g \lambda_i (\alpha_T J_i^h - \alpha_\mu J_i^\mu) = -K_\rho N^2, \quad (8d)$$

where the *density diffusivity* is defined as

$$K_\rho = K_h \frac{1 - r^{-1}}{1 - R_\mu}. \quad (8e)$$

When the heat and concentration diffusivities are the same, Eq. (7b) gives $r \rightarrow R_\mu^{-1}$ and (8e) yields $K_\rho = K_h = K_\mu$, as expected. The flux of eddy kinetic energy F_i^{ke} was commented upon in Sect. 6 of Paper I and will be discussed again in Paper V.

3.3. The variable $(\tau N)^2$. Local model $P = \varepsilon$

If instead of solving the nonlocal model (8a, b), with the diffusion terms represented by the fluxes of K and ε , we assume a local model where production is equal dissipation, the model simplifies considerably. While the A_h, μ remain the same, the expression for A_m simplifies to

$$A_m = \frac{2}{(\tau \Sigma)^2} \left[\frac{15}{7} + A_\rho (\tau N)^2 \right]. \quad (9a)$$

In the local limit, Eq. (8a) becomes

$$P_s + P_b = \varepsilon, \quad K_m \Sigma^2 - K_\rho N^2 = \varepsilon. \quad (9b)$$

Using the notation first introduced by Mellor & Yamada (1982)

$$G_m \equiv (\tau \Sigma)^2, \quad (9c)$$

Equation (9b) becomes, after a great deal of algebra, the following equation for G_m in terms of Ri , R_ρ , and Pe

$$c_3 G_m^3 + c_2 G_m^2 + c_1 G_m + 1 = 0 \quad (9d)$$

$$c_3 = A_1 Ri^3 + A_2 Ri^2,$$

$$c_2 = A_3 Ri^2 + A_4 Ri,$$

$$c_1 = A_5 Ri + A_6 \quad (9e)$$

where the functions A_k are given in Appendix A, Eq. (A.3).

3.4. Dissipation rate, Reynolds number

As already noted, the advantage of the representation (1f,g) is that it highlights the role of the power available to generate a mixing state, the degree of stratification N^2 and the role of χ . Clearly, different physical environments have quite different Re because the power to generate mixing can be of quite different nature. In addition to the example of convection in Eqs. (1d–e), we can consider the region below the CZ, where an estimate of ε was presented by Kumar et al. (1999) and which represents the power of *internal gravity waves*. Their results is

$$\varepsilon = 10^{-3} \text{ cm}^2 \text{ s}^{-3}. \quad (10a)$$

If we employ typical values $N^2 = 10^{-7} \text{ s}^{-2}$ and $\chi = 10^9 \text{ cm}^2 \text{ s}^{-1}$ from the second and third relations in (1g), we obtain

$$\text{Re Pr} = 10^{-5}, \quad (10b)$$

which is one of the values we considered in presenting the results of our model in Figs. 1–4. To gain an appreciation of what (10b) implies, consider a realistic Prandtl number of $Pr = \nu/\chi = 10^{-7}$. The Reynolds number then becomes

$$\text{Re} \approx 100. \quad (10c)$$

The value (10c) shows that, below the CZ, turbulence is only moderately strong, as one indeed expects from general considerations. However, since our model is valid in general, we present the results for different Re since different stellar environments have different values of ε than in (10a).

Instead of Re could we have labeled the figures with Pe? The answer is negative since Pe is not an outside variable, such as N^2, χ, ε but an *internal dynamical variable* that depends on the turbulent kinetic energy and as such, it is determined internally as part of the solution of the problem. Pe is therefore an output, not an input, which implies that it cannot be assumed to be a fixed value since it is a dynamical variable. That makes the comparison with numerical simulations difficult since they treat Pe as fixed. For example, Fig. 14 of Brummel et al. (2002) shows that, unless Pe is very large, the resulting “overshooting measure” would exceed the helio-seismic data of $\sim 0.1 H_p$ (cited in the Discussion section of the above reference) by an order of magnitude. Specifically, in order to bring their OV extent into the range of the helio data, Brummel et al. (2002) had to invoke a value of Pe about 100 times larger than what they used, that is, a value of $Pe \sim 10^4$. Such a value is predicted by the present model as one can see from Figs. 1–3 but, as before, other conditions must be satisfied, namely,

$$Pe \sim 10^4 : \text{Re Pr} \approx 10^3, \quad (10d)$$

which is quite restrictive since it seems to exclude the bottom of the convective zone and the underlying shear dominated tachocline.

3.5. Peclet number dependence

The determination of Pe that enters the time scales Eq. (5a) begins with the definition (5b), which we rewrite as

$$Pe = \frac{\pi^2}{125} Ri \text{ Re Pr } G_m \quad (10e)$$

and which shows that Pe is *not a fixed number* but a dynamical variable that depends on Ri , Re , R_μ ; that is,

$$Pe = Pe(Ri, \text{Re}, R_\mu) \quad (10f)$$

corresponding to arbitrary T and μ -gradients, arbitrary shear, and Reynolds number. Relation (10f) naturally complicates the solution of Eq. (9d) since the coefficients $A_{1,\dots,6}$ in (9e) depend on the π_k which in turn depend on Pe, which itself depends on the unknown function G_m . For large values of Pe corresponding to negligible radiative losses, the π_k are practically independent of Pe, and the solution of Eq. (9d) is simplified. It is only when radiative losses are important and Pe is small that the solution of Eq. (9d) becomes more involved and requires an iterative process.

In conclusion, the diffusivities of heat, μ , and momentum measured in units of χ , are given by Eqs. (1f, g) and (6c). Since the amount of energy needed to generate the turbulent state is an outside parameter, it is physically correct to consider the variable RePr as an external parameter, and for this reason in Figs. 1–3, we present the results for different values of such variable, that is, the diffusivities are functions of

$$K_\alpha = K_\alpha(\text{Ri}, R_\mu, \text{RePr}). \quad (10g)$$

The Richardson number Ri represents the competition between stable stratification (a sink of mixing) and shear (a source of mixing), R_μ represents DD processes and Re represents the amount of energy dissipated. The nonexistence of a critical Richardson number was discussed in Paper I and in Canuto et al. (2008a).

3.6. Alternative representation of $\Gamma_{h,\mu}$

Though relations (1g) and (6c) are the basic relations for computing the various diffusivities, it is instructive to present an expression for $\Gamma_{h,\mu}$ that exhibits the shear and DD contributions in a transparent way. Let us begin by taking the rhs of (8a) as zero which corresponds to the local model production = dissipation. Use of relations (8c, d) in the $P_s + P_b = \varepsilon$ relation leads to

$$\varepsilon = K_\rho N^2 \frac{1 - R_f}{R_f}, \quad (10h)$$

where the *flux Richardson number* is defined as

$$R_f = \text{Ri} \frac{K_\rho}{K_m}. \quad (10i)$$

Next, using Eq. (8e), we obtain the desired expression for $\Gamma_h = \frac{K_h N^2}{\varepsilon}$ which is

$$\Gamma_h(\text{Ri}, R_\mu) = \frac{R_f}{\underbrace{1 - R_f}_{\text{shear}}} \frac{1 - R_\mu}{\underbrace{1 - r^{-1}}_{\text{DD}}}, \quad (10j)$$

which exhibits the dependence on shear (Ri) and DD (R_μ). Consider some limiting cases. In the presence of strong shear, heat and μ , diffusivities become equal, and from (7b) we have $r \rightarrow R_\mu^{-1}$. Relation (10j) then becomes the well-known expression

Strong shear (No DD):

$$\Gamma_h = \frac{R_f}{1 - R_f}, \quad R_f = \text{Ri} \frac{K_h}{K_m} = \frac{\text{Ri}}{\sigma_t(\text{Ri})} \quad (10k)$$

where the turbulent Prandtl number $\sigma_t(\text{Ri})$ is known to be an increasing function of Ri as Fig. 1f shows. Conversely, in the absence of shear, $R_f \rightarrow \infty$, relation (10j) becomes

No shear (DD):

$$\Gamma_h = -\frac{1 - R_\mu}{1 - r^{-1}} > 0. \quad (10l)$$

In the salt fingers case, one has $R_\mu < 1$, $r < 1$ which yields a positive Γ_h . In the semi-convective regime, $R_\mu > 1$, $r > 1$ and $\Gamma_h > 0$. Finally, the expression for Γ_μ is

$$\Gamma_\mu = \frac{\Gamma_h}{r R_\mu} = \frac{R_f}{\underbrace{1 - R_f}_{\text{shear}}} \frac{1 - R_\mu}{\underbrace{R_\mu}_{\text{DD}}} \frac{1}{r - 1} > 0. \quad (10m)$$

There is only one set of data from the North Atlantic Tracer Release Experiment (NATRE, Ledwell et al. 1993, 1998) that provide the function

$$\Gamma_h(\text{Ri}, R_\mu) \quad (10n)$$

in the presence of both DD (salt fingers) and shear. Such data (St. Laurent & Schmitt 1999) were used to test relation (10j) or, more specifically, the model used to evaluate the different terms in it. The model presented in Sects. 3.1–3.3 was found to reproduce such data well (Canuto et al. 2008b).

4. Ledoux vs. Schwarzschild criteria for semi-convection

In the case of semi-convection, the Ledoux & Schwarzschild criteria are often discussed as if they were antithetic, implying an uncertainty in the choice of one of the two. To discuss the topic, let us consider the case of *no shear*, and thus the second of (9b) implies that

$$-K_\rho N^2 > 0, \quad K_\rho = \frac{K_h - K_\mu R_\mu}{1 - R_\mu}. \quad (11a, b)$$

If we consider the mass flux, we see that, using (2d) we find

$$\overline{w'\rho'} = -K_\rho \frac{\partial \bar{\rho}}{\partial z} = g^{-1} \rho_0 K_\rho N^2 < 0, \quad (11c)$$

which corresponds to a *downward mass flux*. We distinguish several regimes of interest:

Semi-convection, Ledoux stable, $R_\mu > 1, N^2 > 0$. From (11b) we obtain

$$\frac{K_h}{K_\mu} (\nabla - \nabla_{\text{ad}}) > \nabla_\mu > \nabla - \nabla_{\text{ad}}, \quad K_h > K_\mu. \quad (11d)$$

Dynamical stability ($\nabla_\mu > \nabla - \nabla_{\text{ad}}$) sets the lower limit of ∇_μ and does not depend on any characteristics of turbulent mixing, while the latter sets the upper limit. The Schwarzschild instability criterion $\nabla - \nabla_{\text{ad}} > 0$ corresponds to rewriting (11c) as

$$\nabla - \nabla_{\text{ad}} > \frac{\nabla_\mu}{K_h/K_\mu} = 0, \quad K_h/K_\mu \rightarrow \infty. \quad (11e)$$

However, the last relation is not satisfied in any known regime.

Semi-convection, Ledoux unstable, $R_\mu < 1, N^2 < 0$. In this case we have

$$\nabla - \nabla_{\text{ad}} > \frac{K_\mu}{K_h} \nabla_\mu \quad K_h < K_\mu. \quad (12a)$$

Salt-fingers, Ledoux stable, $R_\mu < 1, N^2 > 0$. In this case we have

$$\frac{K_h}{K_\mu} (\nabla - \nabla_{\text{ad}}) < \nabla_\mu < \nabla - \nabla_{\text{ad}}, \quad K_h < K_\mu. \quad (12b)$$

Salt-fingers, Ledoux unstable, $R_\mu > 1, N^2 < 0$. In this case we have

$$(\nabla - \nabla_{\text{ad}}) \frac{K_h}{K_\mu} < \nabla_\mu, \quad K_h > K_\mu. \quad (12c)$$

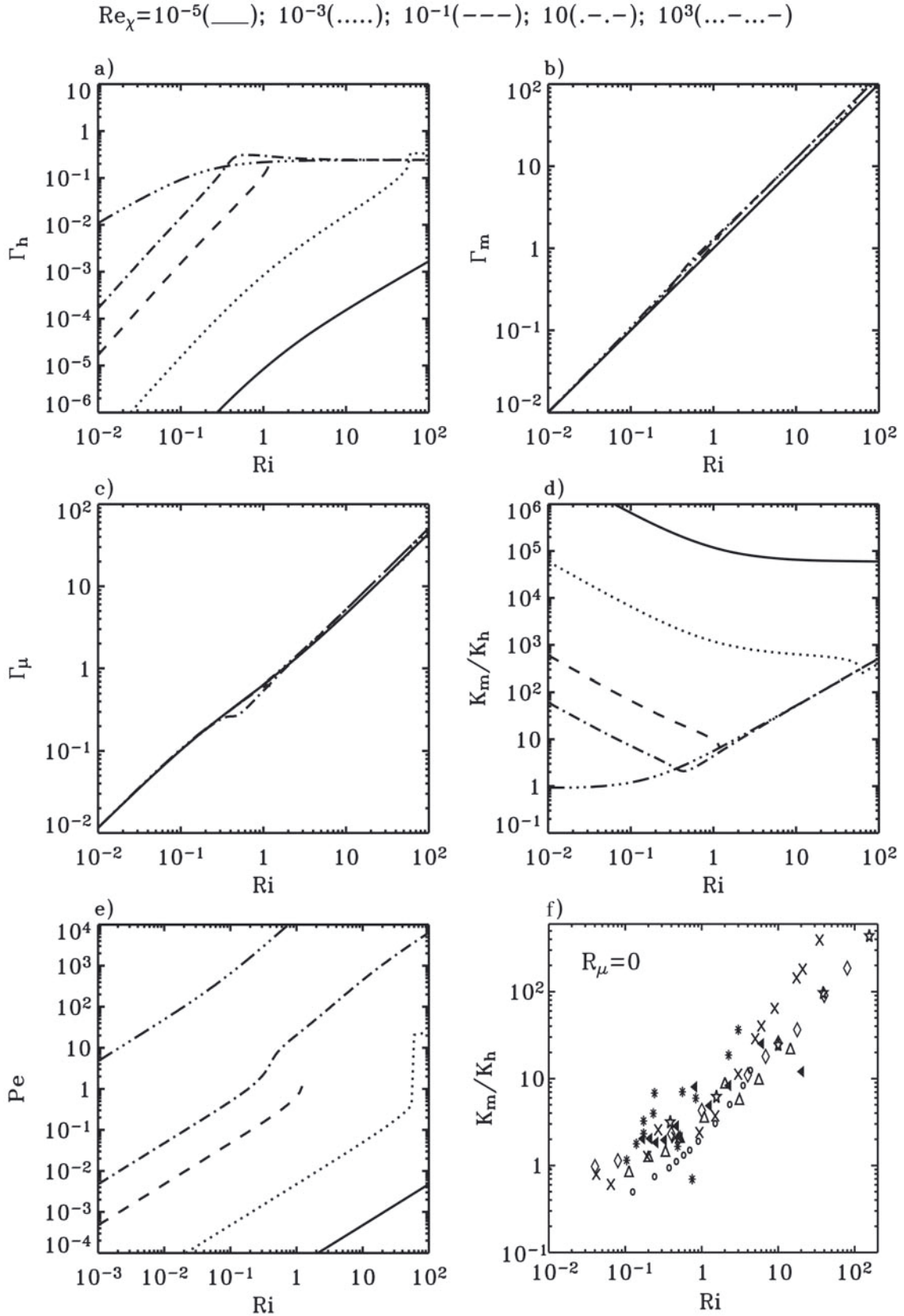


Fig. 1. *No doublediffusion, shear only.* The heat, momentum, and μ mixing efficiencies, as defined in Eq. (1f), vs. Ri for different values of the combination Re_χ which in the figures is denoted by Re_χ . In Fig. 1d we plot the turbulent Prandtl number σ_τ defined in Eq. (14) vs. Ri for different Re_χ . In Fig. 1e we plot the Peclet number vs. Ri. In Fig. 1f we plot the data corresponding to the case $Pe \gg 1$, which well reproduced well by the present model, lower curve in panel 1e. The data are as follows: meteorological observations (Kondo et al. 1978, slanting black triangles; Bertin et al. 1997, snow flakes), lab experiments (Strang & Fernando 2001, black circles; Rehmann & Koseff 2004, slanting crosses; Ohya 2001, diamonds), LES (Zilitinkevich et al. 2007a,b, triangles), DNS (Stretch et al. 2001, five-pointed stars).

Thus, in summary, we have:

$$\begin{array}{l} \text{Semi-Convection Salt Fingers} \\ N^2 > 0 \quad K_h > K_\mu \quad K_\mu > K_h \\ N^2 < 0 \quad K_\mu > K_h \quad K_h > K_\mu. \end{array} \quad (12d)$$

5. Results

The formalism presented above shows that the diffusivities depend on three parameters, namely,

$$\text{Ri}, R_\mu, \text{Re Pr}. \quad (13)$$

We have numerically solved the 1D model in the local limit $P = \varepsilon$, Appendix C, and the results are shown in Figs. 2–3 where we present the heat, momentum, and μ diffusivities in units of the thermometric diffusivity, χ , defined after Eq. (5b), as a function of R_μ for different values of RePr and Ri. We recall that salt fingers and semi-convection are represented by $R_\mu < 1$, $R_\mu > 1$ respectively, see Eqs. (1k, l). For completeness, for the $R_\mu = 0$ case, we also present the Peclet number Pe, Eqs. (5b, 10e), and the turbulent Prandtl number:

$$\sigma_t(\text{Ri}, \text{Pe}) \equiv \frac{K_m}{K_h}. \quad (14)$$

As expected, the ratio (14) is not constant but increases with Ri, a feature that the model predicts since it is physically clear that stable stratification affects temperature more than velocity, and thus it lowers the heat diffusivity more than the momentum one, yielding a σ_t that increases with Ri, as is indeed observed. For the large Pe regime, the model reproduces the available data discussed in Canuto et al. (2008) and presented in Fig. 1f well. As expected, the stronger the radiative losses, represented by small values of RePr, the smaller the heat diffusivity, first panel in each figure.

5.1. Results

No DD. In this case, all the mixing models used thus far in stellar structure calculations (e.g., Mathis et al. 2004; Palacios et al. 2003, 2006; Charbonnel & Talon 2005, 2007) assume the existence of a finite Ri(cr) since their starting point is the relation

$$\text{Ri} < \text{Ri}(\text{cr}) \quad (15a)$$

which ultimately gives

$$\text{Pe} \gg 1: \quad \frac{K_{m,h}}{\chi} = 2 \frac{\text{Ri}(\text{cr})}{\text{Ri}} = \frac{1}{3\text{Ri}}, \quad (15b)$$

since Ri(cr) was taken to be 1/6 (Maeder & Meynet 2001). As stated by the previous authors, relations (15a,b) are only valid in the absence of “thermal leakage” that is, for $\text{Pe} \gg 1$. The first remark is that the basis of this model, Eq. (15a), disagrees with the data shown in Fig. 1f since there is no Ri(cr), see Canuto et al. (2008a). Let us, however, assume for a moment that (15b) was arrived at in a way that does not involve the existence of Ri(cr); that is, consider it an heuristic relation and compare it with the results of the model. From Figs. 1d, e, we observe that the equality of momentum and heat diffusivities can be satisfied only under the conditions

$$K_m \sim K_h: \quad 10^{-2} \leq \text{Ri} \sim 10^{-1}, \quad \text{Re Pr} \sim 10^2 - 10^3, \quad \text{Pe} \approx 100. \quad (15c)$$

The problem is not so much the validity of (15b), but rather how legitimate it is to use (15b) in regimes of Ri, Pe, and RePr other than those described in (15c).

Salt fingers (thermohaline convection). The relevance of this process was recognized quite early (Stothers & Simon 1969), but even today its modeling is still based on largely heuristic relations, the first of which was proposed by Ulrich et al. (1972) and used by several authors (Kippenhahn et al. 1980; Vauclair 2004, 2008; Eggleton et al. 2006; Charbonnel & Zahn 2007). The Ulrich model for the ratio K_h/χ reads

$$\frac{K_h}{\chi} = C R_\mu, \quad \frac{K_\mu}{\chi} = C r^{-1}, \quad (15d)$$

where r is the ratio of heat-to- μ fluxes, see Eq. (7b). The value of C has been a matter of debate: Cantiello & Langer (2008, 2010) use $C = 3$, while Charbonnel & Zahn (2007) use $C = 658$. A different relation,

$$\frac{K_\mu}{\chi} = 2 \times 10^{-2}, \quad (15e)$$

was used by Denissikov and Pinsonneault (2008) to reproduce data for low-mass RGB stars. Relation (15d) with $C = 3$, 1000 are consistent with (15e) for $R_\mu \approx 10^{-2}, 10^{-5}$ respectively, so these models cannot be ruled out. However, due to a difference of a factor of a thousand in their values of R_μ , the two models must have different implications.

The results presented in Fig. 2 exhibit interesting features. Since in this case, the destabilizing effect comes from the μ gradient, in Fig. 2 we plot K_μ/χ for the following parameters

$$\text{Ri} = 0.1, 1, 10 \quad \text{Re}_\chi \equiv \text{Re Pr} = 10^{-3}, 10^{-1}, 1. \quad (15f)$$

- For strong shear, e.g., Ri = 0.1, there is little difference between heat and μ diffusivities, as indeed expected;
- when shear is weak, e.g., for Ri = 10, panel f) shows that the μ diffusivity is larger than the heat diffusivity, as expected, since in the salt-finger case, it is the μ field that causes the instabilities. The ratio K_μ/K_h may be significant, as one can observe in panel f). This implies that heat and μ diffusivities cannot be taken to be the same;
- in each case the dependence on $\text{Re Pr} = \text{Re}_\chi$ of Eq. (1g) is clearly seen.
- in each of the panels on the rhs there is only one curve since the variable $\text{Re}_\chi \equiv \text{Re Pr}$ cancels out in the ratio K_μ/K_h ;
- the broad insensitivity on the density parameter R_μ up to values of about 0.8, for the case of strong-moderate shear favors models of the form (15e), but since such models have no Ri-dependence, it is more consistent to compare them with the results for small shear, large Ri of panel e);
- contrary to (15e), the coefficient C is not a constant but a linear function of RePr;
- if we regard (15e) as an empirical input, panel e) shows that it is reproduced by the RSM for $R_\mu \ll 1$ and for

$$\text{Re Pr} = \frac{\varepsilon}{\chi N^2} = 10^{-3}. \quad (15g)$$

Using Fig. 2 of Denissenkov & Pinsonneault (2008) which yields $\text{Pr} = \text{O}(10^{-6})$ and $\nu = \text{O}(10^2) \text{ cm}^2 \text{ s}^{-1}$, one can then deduce a value for ε .

Semi-convection. In this case the pertinent literature was reviewed in Sect. 1 of Canuto (1999), so there is no need to repeat it here again. As discussed in the last reference, the models by Langer et al. (1989) read as

$$\frac{K_\mu}{\chi} = \frac{1}{6} \alpha_{\text{sc}} \frac{1}{R_\mu - 1}, \quad 8 \times 10^{-3} < \alpha_{\text{sc}} < 5 \times 10^{-2}. \quad (15h)$$

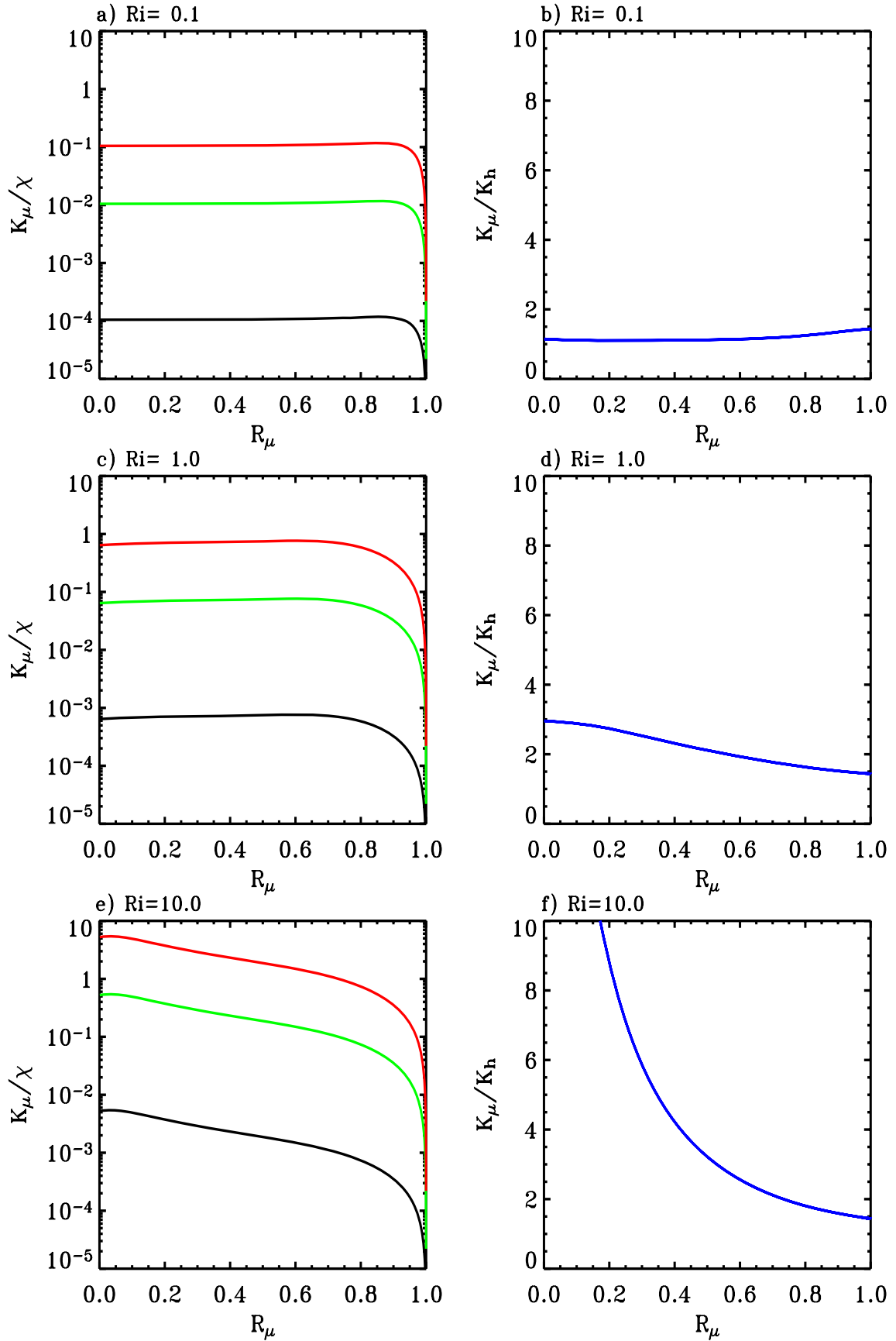
Salt-Fingers: $\text{Re}_\chi = 10^{-3}, 10^{-1}, 1$ 

Fig. 2. Salt fingers. The normalized diffusivities $K_{h,\mu}/\chi$ vs. $R_\mu < 1$, for different values of Ri and $\text{RePr} \equiv \text{Re}_\chi$. See relation (1g).

Semi-convection: $Re_\chi = 10^{-3}, 10^{-1}, 1$

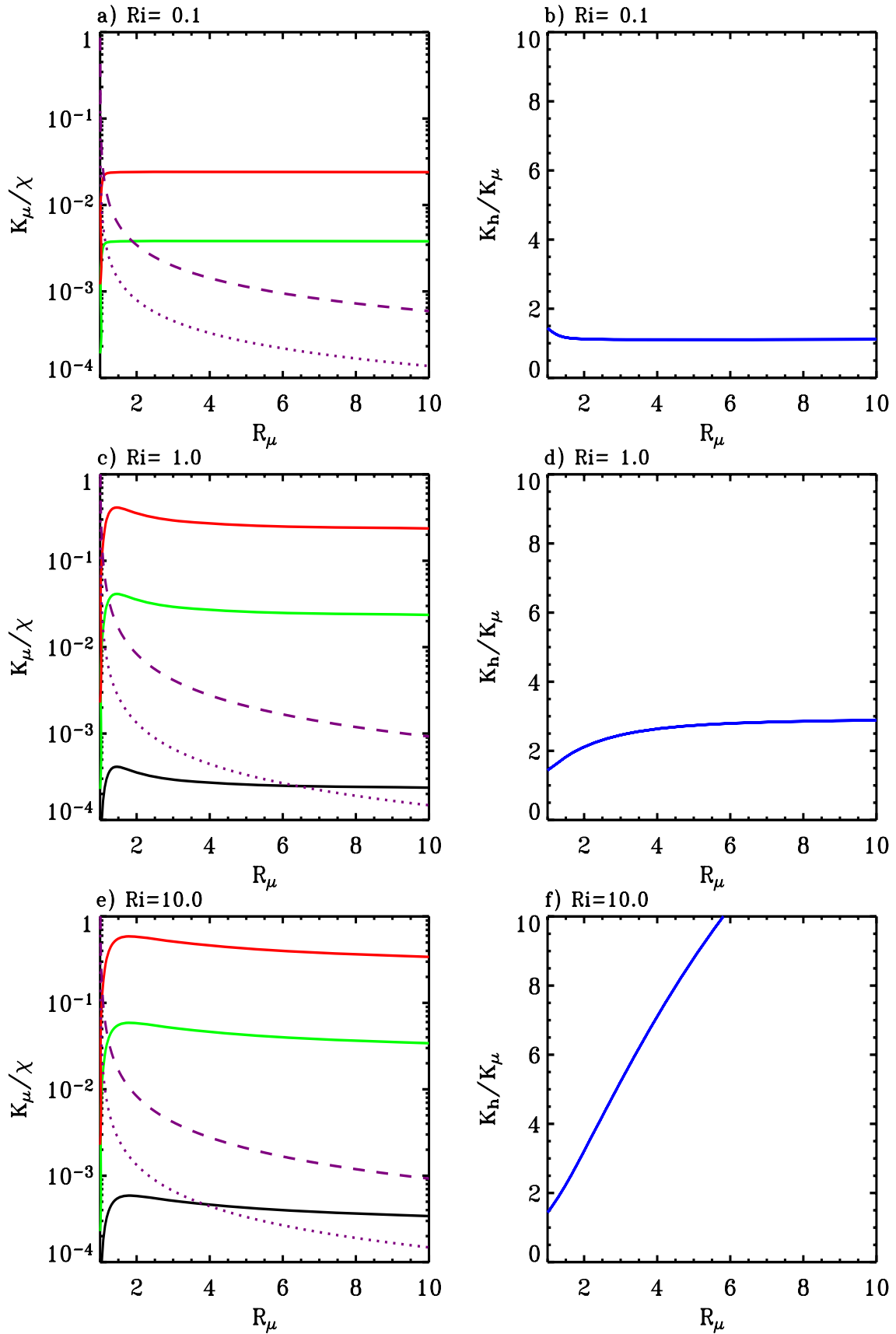


Fig. 3. Semi convection. Same as Fig. 2 but for $R_\mu > 1$. The dash-dotted curves represent the empirical relation (15h).

Since in this case the destabilizing effect is the T -gradient, when shear is weak-to-moderate, $K_h > K_\mu$, as shown in Fig. 3. Most of the conclusions of the salt-finger case can be repeated here since the model is symmetric under the change R_μ to R_μ^{-1} .

In conclusion, in both salt-finger and semi-convection regimes, the present model yields a dependence of the ratio K_μ/χ on the variables:

$$\text{Ri}, \text{R}_\mu, \text{Re Pr}. \quad (15i)$$

Heuristic mixing models such as (15d), (15e), and (15h) have focused only on the R_μ dependence, while neglecting the dependence on

$$\text{Re Pr} = \frac{\varepsilon}{\chi N^2} \quad (15j)$$

which they assume to be a constant, e.g., C and/or $\alpha_{sc}/6$ in the previous relations, while in reality it is a key factor since it determines the strength of the ratios $K_{h,\mu}/\chi$, and it varies from star to star.

6. Conclusions

A welcome feature of the RSM is the relative simplicity of the equations determining the Reynolds stresses, heat and μ fluxes. The presence of two differential equations for K and ε is a common feature of all turbulence models. When a local model is applicable, the present model is fully algebraic and yet the amount of information these relations contain is quite substantial: stable stratification, unstable stratification, rigid rotation, shear, and radiative losses (Peclet number).

Appendix A: The functions A_k in relation (9e)

We begin with relations (9d, e), which we rewrite here:

$$c_3 G_m^3 + c_2 G_m^2 + c_1 G_m + 1 = 0 \quad (A.1)$$

with

$$c_3 = A_1 \text{Ri}^3 + A_2 \text{Ri}^2, \quad c_2 = A_3 \text{Ri}^2 + A_4 \text{Ri}, \quad c_1 = A_5 \text{Ri} + A_6. \quad (A.2)$$

The coefficients A_k are given by the following algebraic expressions:

$$150(1 - R_\rho)^3 A_1 = \pi_1 \pi_4 (\pi_4 - \pi_1 R_\rho) \{ \pi_2 (15\pi_3 + 7)(R_\rho^2 + 1) + [14(\pi_2 - \pi_3) - 15\pi_3^2] R_\rho \}$$

$$9000(1 - R_\rho)^2 A_2 = \pi_1 \pi_4 \{ \pi_2 (210\pi_1 - 150\pi_3 + 7)(R_\rho^2 + 1) + [14(\pi_2 - \pi_3)(1 + 15\pi_1 + 15\pi_4) + 150\pi_3^2] R_\rho + 210\pi_2(\pi_4 - \pi_1) \}$$

$$150(1 - R_\rho)^2 A_3 = \pi_1 [5\pi_2 \pi_4 (30\pi_3 + 17) + \pi_1 (15\pi_3 + 7)(R_\rho^2 + 1) - (15\pi_3 + 7)(\pi_1^2 - \pi_4^2) - [10\pi_1 \pi_3 \pi_4 (15\pi_3 + 17) + 15\pi_2(\pi_1^2 + \pi_4^2) + 14\pi_1 \pi_4 (1 - 10\pi_2)] R_\rho]$$

$$9000(1 - R_\rho) A_4 = [150(\pi_1 \pi_3 + \pi_2 \pi_4) - 7\pi_1 (1 + 30\pi_1)] R_\rho - 150(\pi_1 \pi_2 + \pi_3 \pi_4) + 7\pi_4 (1 + 30\pi_4)$$

$$30(1 - R_\rho) A_5 = [-30(\pi_1 \pi_3 + \pi_2 \pi_4) - 17\pi_1] R_\rho + 30(\pi_1 \pi_2 + \pi_3 \pi_4) + 17\pi_4,$$

$$A_6 = -1/60. \quad (A.3)$$

Appendix B: 3D Mixing model

Reynolds stresses:

$$b_{ij} = -2K_m S_{ij} - \frac{1}{10} \tau Z_{ij} + \frac{1}{10} \tau B_{ij}. \quad (B.1)$$

Momentum diffusivity and dynamical time scale:

$$K_m = \frac{8K^2}{75\varepsilon}, \quad \tau = \frac{2K}{\varepsilon}. \quad (B.2)$$

Vorticity tensor:

$$Z_{ij} = b_{ik} V_{jk} + b_{jk} V_{ik}. \quad (B.3)$$

Buoyancy tensor:

$$B_{ij} = g \left(\lambda_i J_j^\rho + \lambda_j J_i^\rho - \frac{2}{3} \delta_{ij} \lambda_k J_k^\rho \right). \quad (B.4)$$

Buoyancy flux:

$$J_i^\rho = \alpha_T J_i^h - \alpha_\mu J_i^\mu \quad (B.5)$$

$$\lambda_i \equiv -(\overline{g\rho})^{-1} \frac{\partial \overline{p}}{\partial x_i}. \quad (B.6)$$

Shear and vorticity:

$$2S_{ij} = \overline{u_{i,j}} + \overline{u_{j,i}}, \quad 2V_{ij} = \overline{u_{i,j}} - \overline{u_{j,i}}. \quad (B.7)$$

Heat fluxes: $\overline{\rho} J_i^h = \overline{\rho u_i' T'}$

$$(\delta_{ij} + \eta_{ij}) J_j^h = \gamma_{ij} \beta_j$$

$$\gamma_{ij} = \pi_4 \tau (R_{ij} - \pi_2 g \alpha_\mu \tau \lambda_i J_j^\mu)$$

$$\eta_{ij} = \pi_4 \tau [S_{ij} + V_{ij} - g \tau \lambda_i (\pi_5 \alpha_T \beta_j + \pi_2 \alpha_\mu \overline{\mu}_{,j})]. \quad (B.8)$$

μ -fluxes: $\overline{\rho} J_i^\mu = \overline{\rho u_i' \mu'}$

$$(\delta_{ij} + \xi_{ij}) J_j^\mu = -d_{ij} \overline{\mu}_{,j}$$

$$d_{ij} = \pi_1 \tau (R_{ij} + \pi_2 g \alpha_T \tau \lambda_i J_j^h)$$

$$\xi_{ij} = \pi_1 \tau [S_{ij} + V_{ij} - g \tau \lambda_i (\pi_2 \alpha_T \beta_j + \pi_3 \alpha_\mu \overline{\mu}_{,j})] \quad (B.9)$$

where

$$\beta_i = -\frac{\partial T}{\partial x_i} - \lambda_i \frac{g}{c_p}. \quad (B.10)$$

Appendix C: 1D Mixing model with $P = \varepsilon$

Heat, concentration and momentum diffusivities (subscript α):

$$\frac{K_\alpha}{\chi} = \Gamma_\alpha \text{Re Pr},$$

$$\text{Re} \equiv \frac{\varepsilon}{\nu N^2}, \quad \text{Pr} = \frac{\nu}{\chi}, \quad \Gamma_\alpha = \frac{1}{2} G_m \text{Ri} S_\alpha. \quad (C.1)$$

Dimensionless structure functions:

$$S_\alpha = A_\alpha \frac{\overline{w^2}}{K}, \quad G_m \equiv (\tau \Sigma)^2 \quad (C.2)$$

$$A_h = \pi_4 [1 + p x + \pi_2 \pi_4 x (1 - r^{-1})]^{-1},$$

$$A_\mu = A_h (r R_\mu)^{-1} \quad (C.3)$$

$$A_m = \frac{2}{(\tau \Sigma)^2} \left[\frac{15}{7} + A_\rho (\tau N)^2 \right] \quad (C.4)$$

Heat to concentration flux ratio:

$$r = \frac{1}{R_\mu} \frac{\pi_4}{\pi_1} \frac{1 + qx}{1 + px} \quad (C.5)$$

$$q = \pi_1 \pi_2 (1 + R_\mu) - \pi_1 \pi_3 R_\mu, \quad p = \pi_4 \pi_5 - \pi_2 \pi_4 (1 + R_\mu). \quad (C.6)$$

Ratio of vertical to total kinetic energy:

$$\frac{1}{2} \frac{\overline{w^2}}{K} = \left[\frac{30}{7} + A_\rho (\tau N)^2 \right]^{-1}. \quad (C.7)$$

Dimensionless dynamical time scale:

$$x \equiv (\tau N)^2 (1 - R_\mu)^{-1}. \quad (C.8)$$

Equation for G_m : see Eqs. (9d, e)

Flux Richardson number:

$$R_f = \text{Ri} \sigma_t^{-1} (1 - r^{-1}) (1 - R_\mu)^{-1}. \quad (C.9)$$

Density structure function:

$$S_\rho = S_h (1 - r^{-1}) (1 - R_\mu)^{-1}. \quad (C.10)$$

Turbulent Prandtl number:

$$\sigma_t = \frac{K_m}{K_h}. \quad (C.11)$$

Density ratio:

$$R_\mu \equiv \frac{\alpha_\mu \overline{\mu}_{,z}}{\alpha_T [\frac{\partial \overline{T}}{\partial z} - (\frac{\partial \overline{T}}{\partial z})_{\text{ad}}]} = \frac{\nabla_\mu}{\nabla - \nabla_{\text{ad}}}. \quad (C.12)$$

Richardson number:

$$\text{Ri} = \frac{N^2}{\Sigma^2}. \quad (C.13)$$

Brunt-Väisälä frequency:

$$N^2 = -g H_p^{-1} (\nabla - \nabla_{\text{ad}}) (1 - R_\mu). \quad (C.14)$$

Mean shear:

$$\Sigma = (2S_{ij} S_{ij})^{1/2},$$

$$S_{ij} = \frac{1}{2} (\overline{u}_{i,j} + \overline{u}_{j,i}), \quad \overline{u}_{i,j} = \partial \overline{u}_i / \partial x_j. \quad (C.15)$$

Dimensionless time scales:

$$\pi_1 = \pi_1^0 \left(1 + \frac{\text{Ri}}{1 + 10 R_\mu^{-1}} \right)^{-1},$$

$$\pi_4 = \pi_4^0 f(\text{Pe}) \left(1 + \frac{\text{Ri}}{1 + 10 R_\mu^{-1}} \right)^{-1} \quad (C.16)$$

$$\pi_2 = \frac{1}{3} \left[\frac{1}{2} (R_\mu + R_\mu^{-1}) \right]^{-1}, \quad \pi_5 = \pi_5^0 g(\text{Pe}),$$

$$\pi_3 = \pi_3^0 = \pi_5^0 = \sigma_t, \quad \pi_1^0 = \pi_4^0 = 0.08,$$

$$f(\text{Pe}) = \frac{b\text{Pe}}{1 + b\text{Pe}}, \quad g(\text{Pe}) = \frac{c\text{Pe}}{1 + c\text{Pe}},$$

$$(4\pi^2)b = 5(1 + \sigma_t^{-1}), \quad (7\pi^2)c = 4\sigma_t^{-1}.$$

Peclet number:

$$\text{Pe} = \frac{\pi^2}{125} \text{Ri Re Pr} G_m. \quad (C.17)$$

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