Self-gravity at the scale of the polar cell

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ABSTRACT

We present the exact calculations of the gravitational potential and acceleration along the symmetry axis of a plane, homogeneous, polar cell as a function of mean radius \( \bar{a} \), radial extension \( \Delta a \), and opening angle \( \Delta \phi \). Accurate approximations are derived in the limit of high numerical resolution at the geometrical mean \( (a) \) of the inner and outer radii (a key-position in current FFT-based Poisson solvers). Our results are the full extension of the approximate formula given in the textbook of Binney & Tremaine to all resolutions. We also clarify definitely the question about the existence (or not) of self-forces in polar cells. We find that there is always a self-force at radius \( (a) \) except if the shape factor \( \rho \equiv \bar{a} \Delta \phi / \Delta a \to 3.531 \), asymptotically. Such cells are therefore well suited to build a polar mesh for high resolution simulations of self-gravitating media in two dimensions. A by-product of this study is a newly discovered indefinite integral involving complete elliptic integral of the first kind over modulus.

Key words. accretion, accretion disks – gravitation – methods: analytical – methods: numerical

1. Introduction

The structure and dynamical evolution of astrophysical discs is governed mainly by gravity. In this context, the numerical computation of the gravitational potential and forces of discs is of fundamental importance and the improvement in accuracy, resolution and computing time remains an interesting challenge (e.g., Mueller & Steinmetz 1995; Matsumoto & Hanawa 2003; Londrillo 2004; Huré 2005; Jusélius & Sundholm 2007; Li et al. 2008). In many (if not all) hydrodynamical simulations of flat, self-gravitating discs (e.g., Huber & Pfenniger 2001; Zhang et al. 2008; Baruteau & Masset 2008), the potential is derived everywhere in the disc by means of Fast Fourier Transforms (e.g., Binney & Tremaine 1987). This is an efficient technique, which can be extended to deduce directly accelerations (Baruteau & Masset 2008). A weak point however is in the determination of the self-gravitating component (i.e., the effect of a cell on itself), which involves an improper integral. An approximation of this self-potential was proposed in Binney & Tremaine (1987). This is an efficient technique, which can be extended to deduce directly accelerations (Baruteau & Masset 2008). A weak point however is in the determination of the self-gravitating component (i.e., the effect of a cell on itself), which involves an improper integral. An approximation of this self-potential was proposed in Binney & Tremaine (1987). This is an efficient technique, which can be extended to deduce directly accelerations (Baruteau & Masset 2008). A weak point however is in the determination of the self-gravitating component (i.e., the effect of a cell on itself), which involves an improper integral. An approximation of this self-potential was proposed in Binney & Tremaine (1987).

a potential created by an homogeneous disc and the other a potential due to horseshoe-like surface. Sections 3 and 4 are devoted to the determinations of these two contributions. The results for the polar cell (potential and acceleration) are obtained in Sect. 5. We discuss the case of high resolutions in Sect. 6 and show that there is always a self-acceleration except if the cell has a special shape. These results are important since they contributed to the reliability and accuracy of current simulations of self-gravitating media on a polar mesh.

2. The polar mesh

We consider a planar, homogeneous, polar cell with inner polar radius \( a_1 \), outer radius \( a_2 = a_1 + \Delta a \), lower azimuth \( \phi'_1 \), and upper azimuth \( \phi'_2 = \phi'_1 + \Delta \phi \) as shown in Fig. 1. At any position \((R, \phi)\) in the plane of this cell, the gravitational potential is given by Newton’s generalized formula:

\[
\psi(R, \phi) = -2G\Sigma_0 \int_{\phi_1}^{\phi_2} \int_{\phi'_1}^{\phi'_2} \frac{da d\phi'}{\sqrt{a^2 + R^2 - 2arR \cos(\phi' - \phi)}}
\]

where \( \Sigma_0 \) is the surface density. This cell has a single axis of symmetry defined by \( \phi = \frac{1}{2}(\phi'_1 + \phi'_2) \). If we introduce the quantity:

\[
m = \frac{2\sqrt{aR}}{a + R}
\]

as well as the new variable \( \theta' \) such that \( 2\theta' = \pi - (\phi' - \phi) \), the potential along its axis of symmetry is given by:

\[
\psi(R) = -2G\Sigma_0 \int_{\phi_1}^{\phi_2} \int_{0}^{\theta'} \frac{1}{R} \frac{da d\theta'}{\sqrt{1 - m^2 \sin^2 \theta'}}.
\]

where \( 4\theta' = 2\pi - \Delta \phi \). The integral over \( \theta' \) can be decomposed into two integrals with 0 as lower bound. We then have:

\[
\psi(R) = -2G\Sigma_0 \int_{\phi_1}^{\phi_2} da \sqrt{\frac{m}{R}} [K(m) - F(\theta, m)],
\]

in Sect. 2 the integral expression for the potential along the axis of a polar cell which can be decomposed into two parts:
We can easily derive

\[ \psi \]  

where

\[ \Delta \psi = a_2 - a_1, \]  

and

\[ \pm m' \frac{da}{2R} = -\left(1 \pm m'\right)^2 \frac{dm}{m}, \]  

where \( m' = \sqrt{1 - m^2} \) is the complementary modulus, \( +m' \) is for \( R \leq a \) (i.e., matter is located right to the position \( R \)) and \( -m' \) is for \( R \geq a \) (i.e., matter is located to the left). From Eqs. (2) and (9), we deduce that the self-gravitating potential in the cell along its symmetry axis is:

\[ \psi(R) = 4G\Sigma_0 R \int_{a_1}^{a_2} \left(1 \pm m^3\right) \left[K(m) - F(\theta, m)\right] dm. \]  

We note that this expression is rarely seen in the literature.

### 3. The homogeneous disc

#### 3.1. Classical derivation

To calculate \( \psi_d \), one classically changes\(^1\) the modulus \( m \) of \( K \) by setting \( m = \frac{2\sqrt{x}}{x} \) where \( x \leq 1 \). The new modulus \( x \) is either \( a/R \equiv u \leq 1 \) or \( R/a \equiv v \leq 1 \) depending on \( R \). So, the potential due to an homogeneous disc is given by:

\[ \psi_d(R) = -\frac{4G\Sigma_0}{4G\Sigma_0} \begin{cases} -\int_{\theta_1}^{\theta_2} \frac{K(v)}{v} \frac{dv}{\theta}, & \text{in region (I),} \\ \int_{\theta_1}^{\theta_2} uK(u)du - \int_{\theta_1}^{\theta_2} K_0(u)du, & \text{in region (II),} \\ \int_{\theta_1}^{\theta_2} uK(u)du, & \text{in region (III),} \end{cases} \]  

(12)

where region (I) is for \( R \leq a_1 \), region (II) is for \( a_1 \leq R \leq a_2 \), and region (III) is for \( R \geq a_2 \) (see Fig. 2). Since the indefinite integrals in Eqs. (12) are known\(^2\), a close-form expression for \( \psi_d \) can finally be deduced. It is:

\[ \psi_d(R) = -\frac{4G\Sigma_0}{4G\Sigma_0} \begin{cases} \left[E(u) - u^2K(u)\right]_{\theta_1}^{\theta_2}, & \text{in (I),} \\ \left[E(u) - u^2K(u)\right]_{\theta_1}^{\theta_2} + \left[E(u) - u^2K(u)\right]_{\theta_1}^{\theta_2}, & \text{in (II),} \\ \left[E(u) - u^2K(u)\right]_{\theta_1}^{\theta_2}, & \text{in (III).} \end{cases} \]  

(14)

#### 3.2. A new indefinite integral?

From a numerical point of view, it is preferable to use \( u \) and \( v \) as modulus of the complete elliptic integrals rather than \( m \) (see Sect. 6). However, an interesting issue is raised if we perform a change of modulus in Eqs. (14), to restore \( m \) as the modulus of \( E \) and \( K \). We find:

\[ \psi_d(R) = -\frac{4G\Sigma_0}{4G\Sigma_0} \begin{cases} \left[E(u) + mK(u)\right]_{\theta_1}^{\theta_2}, & \text{in (I),} \\ \left[E(u) - mK(u)\right]_{\theta_1}^{\theta_2} + \left[E(u) + mK(u)\right]_{\theta_1}^{\theta_2}, & \text{in (II),} \\ \left[E(u) - mK(u)\right]_{\theta_1}^{\theta_2}, & \text{in (III),} \end{cases} \]  

(15)

\(^1\) The transformation is (e.g. Gradshteyn & Ryzhik 1965):

\[ K' = \frac{2\sqrt{x}}{1 + x} \]  

(11)

\(^2\) In particular, we have for any \( k \leq 1 \) (Gradshteyn & Ryzhik 1965):

\[ \int K(k) dk = \frac{E(k)}{k} \]  

(12)

where \( E \) is the complete elliptic integral of the second kind and \( k' = \sqrt{1 - k^2} \) is the complementary modulus.
If we now compare these expressions with the first part of Eq. (10), we conclude that:
\[
\int \frac{(1 \pm k^3)}{k^3k'} K(k)dk = \pm \frac{E(k) \pm k'E(k)}{1 \pm k'}.
\]
for any modulus \(k\) and complementary modulus \(k'\). This indefinite integral is probably new (Jeffrey 2009).

4. The homogeneous horseshoe
To calculate \(\psi_{hs}\), we have attempted to proceed as for the disc, by applying a change of modulus. We failed, mainly because, as mentioned, the new amplitude \(a\) of \(F\) resulting from Eq. (11) now becomes a function of the modulus. This introduces a severe mathematical difficulty that we were unable to circumvent. The answer is however obtained by considering Eq. (16) with incomplete elliptic integrals. Using the partial derivative\(^3\) of \(F\) and \(E\) with respect to their modulus (keeping the amplitude constant), we have:
\[
\frac{\partial}{\partial k} \left[ \frac{E(k) \pm k'F(k)}{1 \pm k'} \right] = \frac{(1 \pm k^3)}{k^3k'} F(\theta, k) + H(\theta, k)
\]
(18)
where
\[
H(\theta, k) = \frac{(1 \pm k^3)}{2kk'k} \sin 2\theta
\]
and \(\Delta = \sqrt{1-k'^2}\sin^2\theta\). In fact, \(\int H(\theta, k)dk\) can be expressed exactly in terms of basic functions. Actually, after some algebra, we have:
\[
\phi_{hs}(R) = -4G\Sigma_0 R \left[ \int_{\text{in (I)}} \frac{E(\theta, m)F(\theta, m)}{1-m'} + \sin 2\theta \ln \left( \frac{\Delta-m'}{\Delta+m'} \right) \right]_{m_0}^{m_1}
\]
(19)
\[
\phi_{hs}(R) = -4G\Sigma_0 R \left[ \int_{\text{in (II)}} \frac{E(\theta, m)F(\theta, m)}{1-m'} + \sin 2\theta \ln \left( \frac{\Delta-m'}{\Delta+m'} \right) \right]_{m_0}^{m_1}
\]
(20)
\[
\phi_{hs}(R) = -4G\Sigma_0 R \left[ \int_{\text{in (III)}} \frac{E(\theta, m)F(\theta, m)}{1-m'} + \sin 2\theta \ln \left( \frac{\Delta-m'}{\Delta+m'} \right) \right]_{m_0}^{m_1}
\]
(21)
It follows from Eqs. (10), (18), (19), and (20) that the potential along the axis of the homogeneous horseshoe is given by:
\[
\frac{\psi_{hs}(R)}{-4G\Sigma_0 R} = -\frac{\sin 2\theta}{4} \ln \left( \frac{\Delta-m'}{\Delta+m'} \right) \left( \frac{\Delta-m'}{\Delta+m'} \right)_{m_0}^{m_1}
\]
(22)
As for Eq. (14), the expression for region (II) can be simplified.

5. Potential and acceleration in the polar cell
The potential inside a polar mesh and along its symmetry axis is found from Eqs. (15b) and (21b). It is:
\[
\frac{\psi(R)}{-4G\Sigma_0 R} = \frac{E(m_2) - E(\theta, m_2) + m'_2 \left[K(m_2) - F(\theta, m_2)\right]}{E(m_1) - E(\theta, m_1) - m'_1 \left[K(m_1) - F(\theta, m_1)\right]}
\]
\[
-\sin 2\theta \ln \left( \frac{\Delta-m'}{\Delta+m'} \right) \left( \frac{\Delta-m'}{\Delta+m'} \right)_{m_0}^{m_1}
\]
(23)
where \(\Delta^2 = 1 - m''^2\sin^2\theta\) with \(i = \{1, 2\}\). This expression is exact. Figure 3 displays \(\psi_{hs}\), \(\psi_{hs}\), and their difference \(\psi\) versus \(R\) for a typical cell. By deriving this formula with respect to \(R\), we obtain the relation:
\[
\frac{\phi_{hs}(R)}{-4G\Sigma_0 R} = \frac{\psi_{hs}(\theta)}{\phi_{hs}(\theta)} + S_\phi(\theta)\]
(24)
is the potential due to the cell at the origin \(R = 0\), and
\[
S_\phi(\sigma) = \frac{\phi_{hs}(\theta)}{\phi_{hs}(\theta)} - \frac{\psi_{hs}(\theta)}{\phi_{hs}(\theta)}\]
(25)
then Eq. (23) takes the form:
\[
\frac{d\psi}{d\sigma} = \frac{\psi}{\sigma} + S_\phi(\sigma).
\]
(26)
This is the generalization of the Ordinary Differential Equation (ODE) derived by Huré & Hersant (2007) to a polar cell with opening angle \(\Delta\phi = 2\pi - 4\theta\) (which becomes a disc for \(\theta = 0\)). This ODE can be easily solved numerically using standard schemes since \(\psi\) is known both at the center (see Eq. (24)) and at infinity where \(\psi = 0\). The full generalization to polar cells where the surface density \(\Sigma\) is a power-law of the radius, i.e., \(\Sigma(\rho) = \Sigma_0(\rho/\rho_0)^{3}\), seems straightforward.

6. Approximations at high numerical resolutions and the “magic” shape factor
At high resolution, polar cells tends to become segments, squares, or arcs depending on the shape factor \(\rho\) of the cell defined by:
\[
\frac{d\Delta\phi}{\Delta\theta} = \rho\Delta\theta
\]
(27)
where $\bar{a} = \frac{1}{2}(a_1 + a_2)$ is the center of physical cells. When both $\Delta \theta \ll 1$ (i.e. $\theta \to 2\pi$) and $\Delta a \ll \bar{a}$, we can expand $F(\theta, m), E(\theta, m), K(m)$, and $E(m)$ over $m^2$ (e.g., Carlson & Gustafson 1985; Gradsteyn & Ryzhik 1965) to obtain an approximation for $\psi$ and $g_R$ as a function of $R$ and the cell geometrical parameters ($\bar{a}, \Delta \theta, \Delta \phi$). A radius plays a key role in current FFT-based Poisson solvers (see references in Sect. 1): this is the geometrical mean of the inner and outer radii, namely $R = \sqrt{\bar{a}\Delta a}$. This radius is the center of computational cells when a radial logarithmic mapping is applied to the entire physical mesh. For $R = \bar{a}$, the two modulus $m_1$ and $m_2$ are equal (and so are the complementary), and we have $m_1^2 = m_2^2 = \frac{\Delta \theta}{\bar{a}}$ to first order. After some algebra, we find:

$$\psi(\langle a \rangle) \approx -2G\Sigma_0 \Delta a \left[ \arcsin \rho + \rho \arcsinh \frac{1}{\rho} \right],$$

and

$$g_R(\langle a \rangle) \approx G\Sigma_0 \frac{\Delta a}{\bar{a}} \left( 2\rho \arcsin \frac{1}{\rho} - \arcsinh \rho \right).$$

Figure 4 compares exact values of $\psi(\langle a \rangle)$ and $g_R(\langle a \rangle)$ given by Eqs. (22) and (23) with approximate values obtained from Eqs. (28) and (29) respectively, for three factors $\rho = \{0.5, 1, 2\}$. We note that, for $\Delta a/\bar{a} \leq 10^{-3}$, relative errors increase. This is due to the “low dynamic” of the variable $m$ as it approaches unity (and $\Delta a \to 0$). In this case, it is advisable to use $u$ and $\phi$ as the moduli of elliptic integrals instead of $m$ to restore the accuracy in Eq. (22).

The potential always has its minimum inside the cell at a certain radius $R_{\text{min}}$ regardless of the opening angle $\Delta \theta$. This radius is found by equating the right-hand side of Eq. (23) to zero. It depends on the parameters $\bar{a}, \Delta a$, and $\rho$. We expect $R_{\text{min}} \leq \bar{a}$ for large opening angles (or low azimuthal resolutions) and $R_{\text{min}} > \bar{a}$ for small ones (high azimuthal resolutions). When $\Delta \theta \to 0$, $R_{\text{min}} \to \bar{a}$ as the polar cell becomes a rectangle. Since $\bar{a} \neq \langle a \rangle$, there is in general a self-force at $R = \langle a \rangle$ at high azimuthal resolution. However, the gravitational acceleration exceptionally cancels out if the shape factor has the remarkable value $\rho_{\text{magic}} \approx 3.530937746935705$. This is the single root of Eq. (29).

For $\rho = \rho_{\text{magic}}$, we have $\psi(\langle a \rangle) \approx -5.922555527732666 G\Sigma_0 \Delta a$. Thus, if the computational mesh $(\Delta a, \Delta \phi)$ contains cells all with shape factor $\rho = \rho_{\text{magic}}$, then there is need to compute the gravitational force at $R = \langle a \rangle$, since it is zero in the high resolution limit.

More generally, since the two moduli $m_1$ and $m_2$ appearing in Eq. (23) are functions of the ratio $a_2/a_1$, it is always possible to find a shape factor for which the acceleration vanishes at a fixed value of $R/a_1$. It can therefore be advantageous to build the polar mesh accordingly. For instance, let $N_R$ and $N_{\phi}$ be the numbers of cells in the radial and azimuthal directions, respectively, and $R_{\text{in}} \equiv R_1$ be the radius of the disc inner edge. Once the shape factor $\rho$ has been numerically determined such that $g_R = 0$ (this is $\rho_{\text{magic}}$ in the high resolution limit), the radius $R_{\text{out}} = R_{N_{\phi}+1}$ of the outer edge is found from the relation:

$$R_{\text{out}} = R_{\text{in}} \times \left( \frac{N_R \rho + \pi}{N_R \rho - \pi} \right)^{N_R} \approx R_{\text{in}} \times \left( 1 + \frac{2\pi N_R}{\rho N_\phi} \right).$$

With such a mesh, there is no gravitational acceleration at the center of computational cells.

7. Concluding remarks

We have reported exact expressions for the self-gravitating potential and acceleration in homogeneous polar cells whatever their shape. The high resolution limit has been analyzed and reliable approximations have been derived. We confirm the validity of Binney & Tremaine (1987)’s prescription for the singular term $K(0,0)$ to first order. We have shown that there is always a self-acceleration at the center of computational cells. However, this acceleration can cancel out by an appropriate choice of cell shape. This work contributes to the treatment of self-gravity in hydrodynamical simulations, and especially for discs.

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References

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4 A Fortran 90 package called PolarCELL is available at the following address: http://www.obs.u-bordeaux1.fr/radio/JMHure/intro2polarcell.html