

Migration and giant planet formation

Y. Alibert, C. Mordasini, and W. Benz

Physikalisches Institut, University of Bern, Sidlerstrasse 5, 3012 Bern, Switzerland

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Abstract. We extend the core-accretion model of giant gaseous planets by Pollack et al. (1996) to include migration, disc evolution and gap formation. Starting with a core of a fraction of an Earth's mass located at 8 AU, we end our simulation with the onset of runaway gas accretion when the planet is at 5.5 AU 1 Myr later. This timescale is about a factor ten shorter than the one found by Pollack et al. (1996) even though the disc was less massive initially and viscously evolving. Other initial conditions can lead to even shorter timescales. The reason for this speed-up is found to result from the fact that a moving planet does not deplete its feeding zone to the extent of a static planet. Thus, the uncomfortably long formation timescale associated with the core-accretion scenario can be considerably reduced and brought in much better agreement with the typical disc lifetimes inferred from observations of young circumstellar discs.

Key words. stars: planetary systems – stars: planetary systems: formation – solar system: formation

1. Introduction

The current paradigm for the formation of giant gaseous planets is based on the so-called core accretion model in which a growing solid core reaches a critical mass and accretes rapidly a massive atmosphere (Pollack et al. 1996, hereafter referred to as P96). While this model has many appealing features, it suffers at least from two shortcomings which, as we shall show later, are actually coupled.

First, the timescale (close to 10 Myr) found by P96 to form Jupiter at its present location is uncomfortably close to the typical lifetime of protoplanetary discs which is believed to be of the order of 1–10 Myr (Haisch et al. 2001). This timescale problem has led others to look for more rapid formation mechanisms based on direct gravitational collapse (Boss 2002). Second, P96 assumed that the giant planets of our solar system have been formed where they are observed today. However, the discovery over the last decade of extrasolar planets at very short distances to their parent star, has open the possibility that planets may actually migrate over large distances (Lin et al. 1996; Trilling et al. 1998; Papaloizou & Terquem 1999, hereafter referred to as PT99). The timescale of migration is still very uncertain, but conservative estimates give values between 0.1 and 10 Myr. This timescale is therefore comparable to the planet formation timescale and the disc lifetime and thus migration cannot be neglected in a self-consistent picture.

In this Letter, we extend the core accretion model of P96 to include migration, disc evolution and gap formation and show that the formation timescales of giant planets can be reduced by factors of ten or more.

Send offprint requests to: Y. Alibert,
e-mail: yann.alibert@phim.unibe.ch

2. The model

Our model consists of three different modules that calculate: 1) the disc structure and time evolution, 2) the interaction of planetesimals with the atmosphere of the planet, and 3) the internal structure of the planet. A detailed description of the model and of the tests performed will be given in a forthcoming paper, here we only briefly point out the main features of the different modules.

2.1. Disk structure and evolution

This module determines the structure (both vertical and radial) of a protoplanetary disc modelled as an α -disc. For this, we follow the method described in PT99, and refer the reader to this paper for more details. Using their procedure we calculate, as a function of the surface density Σ and the radial distance to the star r , the mid-plane temperature and pressure $T_{\text{mid}}(r, \Sigma)$, $P_{\text{mid}}(r, \Sigma)$, the mean viscosity $\tilde{\nu}(r, \Sigma)$ and the disc density scale height $\tilde{H}(r, \Sigma)$.

The time evolution of the disc is governed by a diffusion equation, modified to take into account the momentum transfer between the planet and the disc. The rate of momentum transfer between the planet and the disc is calculated using the formula derived by Lin & Papaloizou (1986) (Eq. (14)).

2.2. Migration

Gravitational interactions between the growing protoplanet and the disc lead to inward migration and possibly gap formation (Lin & Papaloizou 1986; Ward 1997; Tanaka et al. 2002). For low mass planets, the migration rate is linear with mass (type I

migration, Ward 1997). Higher mass planets open a gap and the migration rate is set by the viscosity independently of planetary mass (type II migration, Ward 1997).

While the general physical understanding of the origin of migration is clear, the actual migration rates obtained for type I migration especially are so short that all planets should actually be destroyed by the central star long before the disappearance of the gaseous disc. Tanaka et al. (2002) have performed new analytical calculations of type I migration, in two or three dimensional discs and found longer migration timescales but unfortunately still too short to ensure survival. Indications for longer type I migration timescales can be found in calculations by Nelson & Papaloizou (2003). As suggested by these authors, torques exerted on at least small mass planets ($M_{\text{planet}} < 30 M_{\oplus}$) embedded in turbulent MHD discs are strongly fluctuating resulting in a slow down of the net inward motion.

These considerations seem to indicate that the actual migration timescales may in fact be considerably longer than originally estimated by Ward (1997) or even by Tanaka et al. (2002). For these reasons, and for lack of better knowledge, we allow us the freedom to use for type I migration the formula derived by Tanaka et al. (2002) reduced by an arbitrary numerical factor f_1 (set to 1/30 in this paper). Tests have shown that provided this factor is small enough to allow planet survival, its actual value *does not* change our main conclusion but only the extend of migration. For type II migration, the inward velocity is set by the viscosity of the disc. Migration type switches when the planet becomes massive enough to open a gap in the disc. In our work, this transition occurs when the Hill radius of the planet becomes greater than the density scale height \tilde{H} of the disc.

2.3. The planetesimals

2.3.1. Interaction with the growing atmosphere

In our second module we determine the trajectory, the energy and mass loss of planetesimals falling through the atmosphere of the planet under the influence of gravity and aerodynamic drag forces. The drag coefficient is calculated (assuming a sphere) as a function of the local Mach and Reynolds number using the equations given by Henderson (1976). The loss in kinetic energy results in a local heating of the planet's atmosphere which enters in the calculation of the internal structure. Given the size of the planetesimals considered here (100 km), ablation is found to be negligible and deposition of mass occurs almost entirely due to fragmentation which occurs when the pressure at the stagnation point becomes larger than its tensile strength. For the envelopes considered here, this occurs typically at or quite close to the core making the difference between the sinking and the no-sinking case as defined by P96 much smaller. Note that in the current version of the code we do not include the effect of heavy elements enrichment in the opacity and the equation of state.

2.3.2. Accretion rate of solids

We assume that due to the scattering effect of the planet, the surface density of planetesimals is constant within the current

feeding zone but decreases with time proportionally to the mass accreted by the planet. The feeding zone is assumed to extend to a distance $a_f = 4 \times R_H$ on each side of the planetary orbit, where $R_H \equiv \left(M_{\text{planet}}/3M_{*}\right)^{1/3} a_{\text{planet}}$ is the Hill radius of the planet, a_{planet} the star-planet distance and M_{*} the mass of the central star. We use the expressions in the Appendices B and C of Greenzweig & Lissauer (1992) to calculate the gravitational enhancement factor F_g . The solid accretion rate is given by: $\frac{dM_{\text{core}}}{dt} = R_c^2 \Sigma_p \Omega F_g / (2\pi)$ where Σ_p is the surface density of solids at $r = a_{\text{planet}}$ and R_c is the capture radius of the planet, calculated as in P96, using our second module. For the inclination and eccentricities of the planetesimals we adopt the same values as in P96.

2.4. Protoplanet structure and evolution

2.4.1. Internal structure equations

In the third module, we calculate the internal structure of the planet including a growing core (and the inner luminosity due to the accretion of planetesimals) and gas accretion due to both the contraction of the envelope and the increase of the outer radius of the planet (see P96). The standard equations of planet evolution are solved, using opacities from Bell & Lin (1994) and the equation of state (EOS) from Chabrier et al. (1992). Note that in the present models we neglect the change of entropy while computing the luminosity gradient. This approximation is justified by the fact that until runaway gas accretion, the energy deposition by infalling planetesimals largely dominates the energy budget.

The core radius is set to $R_{\text{core}} = (3M_{\text{core}}/4\pi\rho_{\text{core}})^{1/3}$ and the core luminosity is equal to the remaining energy of planetesimals after having passed through the atmosphere. The density of the core is fixed to 3.2 g/cm^3 . The two outer boundary conditions are given by requiring that the disc and the planet joint smoothly at the outer radius, i.e. $P_{\text{surf}} = P_{\text{mid}}$, and $T_{\text{surf}} = T_{\text{mid}}$ where P_{mid} and T_{mid} are the local mid-plane values obtained from the disc structure calculations (see above). These two conditions are valid as long as the disc can supply enough mass to keep the outer radius equal the Hill (or the accretion) radius (see next section).

2.4.2. Gas accretion rate

The gas accretion rate onto the planet is determined by the condition: $R_{\text{planet}} = \min(R_H, R_{\text{accr}})$ where R_{planet} is the outer radius of the planet, and $R_{\text{accr}} \equiv GM_{\text{planet}}/C_s^2$, C_s is the local sound velocity in the disc (see P96). At each timestep, we iterate on the mass of the envelope (and then the total mass) until this condition is met.

In reality, the condition $R_{\text{planet}} = \min(R_H, R_{\text{accr}})$ can only be satisfied if the disc can actually supply enough gas to the planet. When a gap opens, the gas available for the planet to accrete drops significantly. Hence, we limit the gas delivery rate from the disc to the planet to the maximum value given by Veras & Armitage (2003).

2.5. Tests of the model

Various tests have been performed to validate our entire model and we will describe them in detail in a forthcoming paper. Let us here only mention that our disc structure calculations reproduce the results given in PT99 whereas the module dealing with the internal structure of the planet is in agreement with the results of Bodenheimer & Pollack (1986). Our planetesimal accretion module has been tested extensively by comparing results of simulations of impacts on Earth (Hills & Goda 1993), on Venus (Zahnle 1992), and Jupiter (e.g. comet Shoemaker-Levy 9, MacLow & Zahnle 1994). Moreover, the entire code has been tested using the same initial conditions as P96 (case J1) turning disc evolution and migration off. In this case, we obtain a formation time of ~ 9 Myr, in close agreement to their result.

3. Results

3.1. Initial conditions

We start with a solid core of $0.6 M_{\oplus}$ located at 8 AU which will eventually lead after ~ 1 Myr to a giant planet now located around 5.5 AU but still migrating inward.

To allow an easy comparison with P96, we chose an initial disc surface density profile given by a power law $\Sigma \propto r^{-2}$, where r is the distance to the star, the constant being chosen to yield $\Sigma = 525 \text{ g/cm}^2$ at 5.2 AU. The viscosity parameter α is set to 2×10^{-3} which yields a typical evolution time of the disc of 4 Myr. The gas-to-dust ratio is equal to 70. Our initial disk therefore corresponds closely to case J2 of P96 for which they found a formation time of about 50 Myr. The numerical parameters are f_1 (reduction of type I migration) equal to $1/30$ and f_{Λ} , the numerical factor in the expression of the momentum transfer between the planet and the disc, set to 0.05. This latter choice gives a transition from type I to type II migration when the reduction of Σ due to momentum transfer is around 30%. We have checked that our conclusions remain valid if f_{Λ} is set to 0 (no gap formation).

3.2. Formation timescales

Figure 1 shows the mass of heavy elements and the mass of H/He accreted by the planet as a function of time. Note that the mass of heavy elements does not correspond to the core mass since some fraction of the planetesimals are being destroyed while traversing the envelope and never reach the core.

As in P96, the formation timescale is essentially determined by the time necessary to reach the runaway accretion phase which occurs shortly after the crossover mass (mass of core equals mass of envelope), M_{cross} , has been reached. In the case where migration and disk evolution have been switched off, this occurs after ~ 31 Myr, compared to 48 Myr in P96. This difference provides a measure for the sensitivity of the results to differences in physical and numerical approximations used in both approaches. In particular, we use different EOS and, more importantly, opacity laws (which has been shown to have a huge influence on formation timescale, see model J6 of P96). To properly derive the effect of migration and disk evolution,

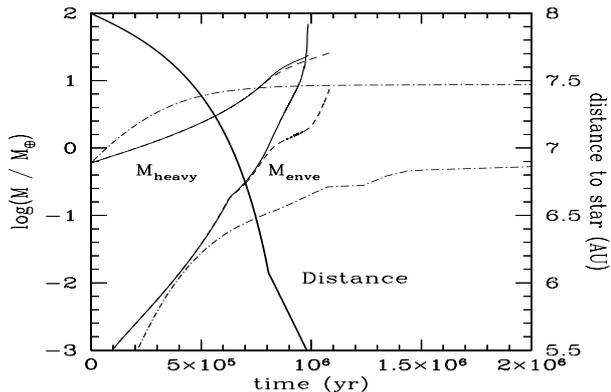


Fig. 1. Total mass of heavy elements (core+envelope) and mass of the envelope (H/He) as a function of time, for three models. Solid lines: migrating case, without gap formation (case 1); dashed lines: migrating case, with gap formation (case 2); and dot-dashed lines: non migrating case, without disk evolution nor gap formation (case 3). The heavy line gives the distance to the central star as a function of time (case 1). The kink at 0.8 Myr is the transition from type I to type II migration.

we will compare the formation timescales obtained with our own value (~ 30 Myr).

Allowing for migration and disc evolution, we obtain a formation time of about ~ 1 Myr, i.e. thirty times faster than in our identical model in which migration and disc evolution has been switched off. This is also an order of magnitude faster than the preferred model (J1, Σ normalized to 700 g/cm^2) of P96 even though their initial disc was significantly more massive than ours and not viscously evolving. The main reason for this speed-up is that owing to migration the feeding zone is not as severely depleted as in P96. In their models, it is this depletion which was responsible for the long time needed by the core to reach critical mass and start runaway gas accretion. In our models, the moving planet always encounters new planetesimals and thus its feeding zone is never emptied. To illustrate this important point, we show in Fig. 2 the initial and final disc profiles (for both the gaseous and the solid component).

We note that the crossover mass obtained in our calculation ($\sim 22 M_{\oplus}$) is significantly larger¹ than the one obtained by P96 (case J1 and J2, respectively $\sim 16 M_{\oplus}$ and $\sim 10.5 M_{\oplus}$). This is to be expected since the crossover mass is a growing function of the solid accretion rate. Migration, besides preventing the depletion of the feeding zone, also causes higher accretion rates (and then higher crossover masses) than the corresponding no-migrating case. However, we note that this crossover mass is significantly lower than the one obtained by P96 in their model J3 (Σ normalized to 1050 g/cm^2 , $M_{\text{cross}} \sim 29 M_{\oplus}$), which started with a disk twice as massive as ours in order to obtain formation timescales comparable to ours.

4. Summary and discussion

We have calculated the formation of giant planets up to runaway gas accretion and studied the effect of migration and gap

¹ However, the final mass of heavy elements is still compatible with the one derived by Guillot (1999).

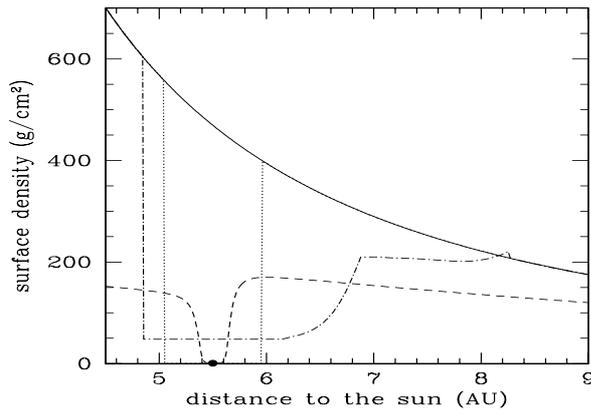


Fig. 2. Solid and gas surface densities for two of our simulations. Solid line: initial gas surface density; dotted line: solid surface density for case 3 after 1.2 Myr; dashed line: gas surface density at the end of case 2; dot-dashed line: solid surface density for the same model, at the same time. The solid surface densities are multiplied by 70. The dot gives the position of the planet.

formation on the resulting formation timescale. Our main result is that phase 2 described in P96 is suppressed, and this leads to a formation time around 1 Myr for the initial conditions chosen here. This is roughly an order of magnitude faster than the favored model of P96 even though our initial disc had less mass than the one used by P96.

We have performed many tests and convinced ourselves that this speed-up is robust against changes in various parameters. For example, in a calculation in which the reduction of type I migration (f_1) is set to 0.1, an embryo starting at 15 AU undergoes runaway accretion in less than 3 Myr. The assumed size of the planetesimals plays a critical role as already noted by P96. For example, assuming planetesimals of 10 km instead of 100 km leads to runaway accretion after only 0.3 Myr! As already mentioned in Sect. 2.3.1, since the effect of ablation is negligible in our calculations, mass loss of planetesimals occurs very deep in the envelope. The switch from sinking to no-sinking approximation (see P96) has then a small effect. In the migrating case (without gap formation) we obtain a formation timescale of ~ 1.2 Myr using the sinking approximation, compared to ~ 1 Myr in the no-sinking case.

Thus, migration, besides explaining the presence of giant planets at short distances to their stars, also plays an important role in the formation process itself. By ensuring that the feeding

zone is never depleted, migration suppresses almost entirely the protracted phase 2 therefore shortening enormously the formation time. This of course, does not preclude other effects such as reduction of opacity or formation of vortices prior to planet formation to further reduce this timescale. The formation of giant planets through the core-accretion scenario can therefore proceed over timescales in good agreement with disk lifetimes, and *without having to consider disks significantly more massive than the minimum mass solar nebula*.

Finally, we point out that the formation of giant planets appears only possible if the currently available type I migration rates are reduced by at least a factor of 10. This suggests that their might still be a serious problem in our understanding of this type of migration.

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