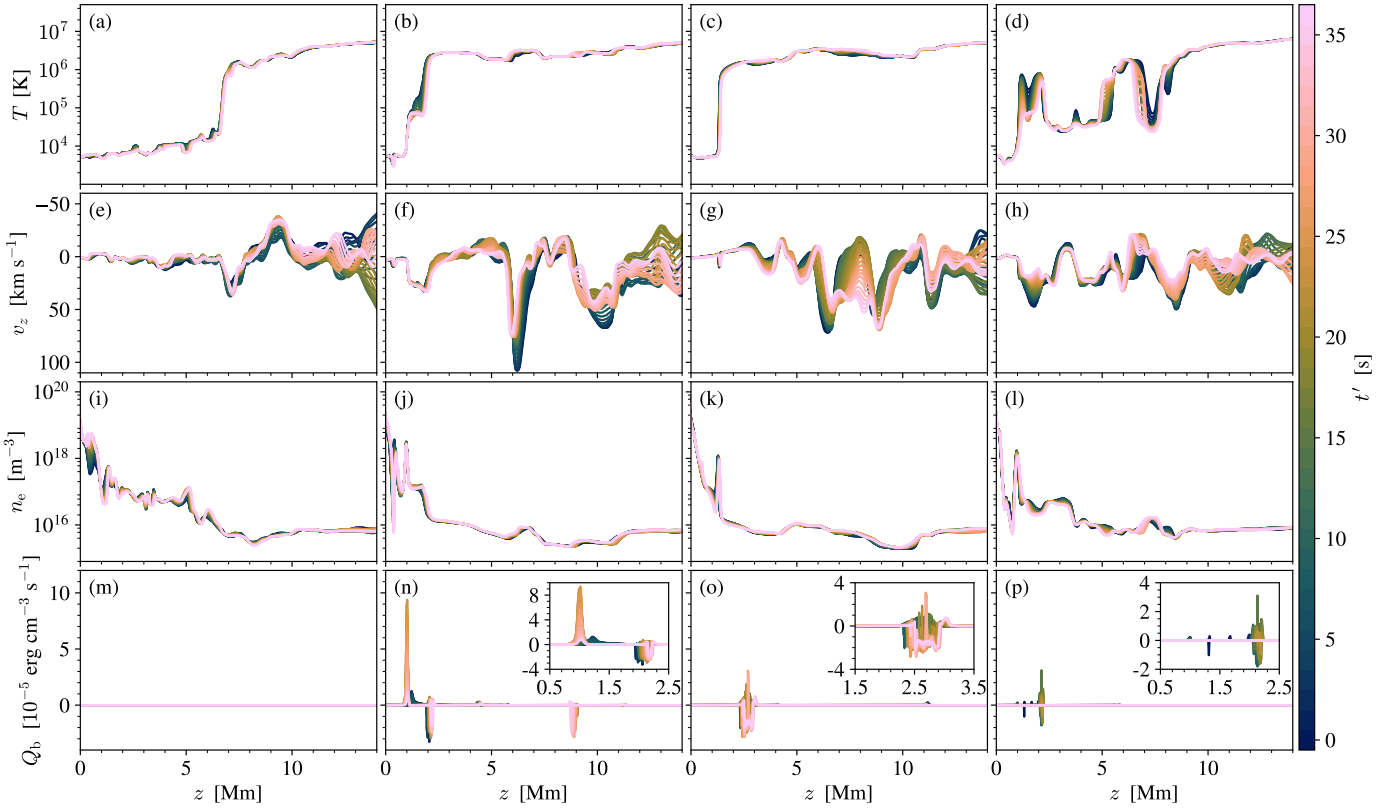
L1
L2
L3
L4
(a)
(b)
(c)
(d)
(e)
(f)
(g)
(h)
(i)
(j)
(k)
(l)
(m)
(n)
(o)
(p)
T [K]
v_z [km s^{-1}]
n_e [m^{-3}]
Q_b [10^{-5} erg cm^{-3} s^{-1}]
z [Mm]
t' [s]