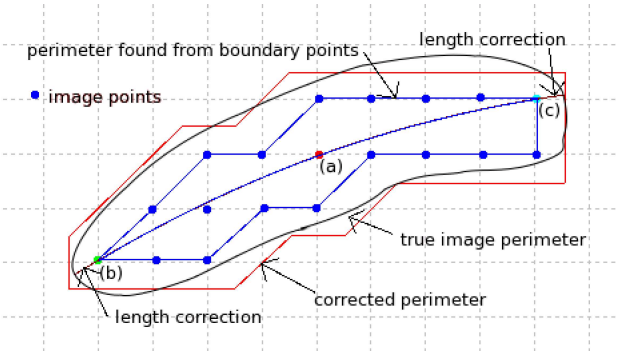
perimeter found from boundary points
length correction
image points
(c)
(a)
true image perimeter
(b)
corrected perimeter
length correction