

Feasibility of spectro-polarimetric characterization of exoplanetary atmospheres with direct observing instruments

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ABSTRACT

Context. Spectro-polarimetry of reflected light from exoplanets is anticipated to be a powerful method for probing atmospheric composition and structure.

Aims. We aim to evaluate the feasibility of the search for a spectro-polarimetric feature of water vapor using a high-contrast polarimetric instrument on a 30–40 m-class ground-based telescope.

Methods. Three types of errors are considered: (a) errors from the difference between efficiencies for two orthogonally polarized states; (b) errors caused by speckle noises; and (c) errors caused by photon noise from scattered starlight. Using the analytically derived error formulas, we estimate the number of planets for which feasible spectro-polarimetric detection of water vapor is possible.

Results. Our calculations show that effective spectro-polarimetric searches for water vapor are possible for 5 to 14 known planets. Spectro-polarimetric characterization of exoplanetary atmospheres is feasible with an extremely large telescope and a direct observing spectro-polarimeter.

Key words. planetary systems – techniques: polarimetric – instrumentation: polarimeters

1. Introduction

Spectro-polarimetric observations of visible or near-infrared reflected light from exoplanets can be a powerful tool for probing their atmospheres. At molecular absorption wavelengths, the polarization degree of planetary reflected light increases owing to the decrease in intensity of the multiply scattered component as compared with that of the continuum wavelengths. Stam et al. (2004) and Stam (2008) calculated polarization degree spectra for Jupiter-like and Earth-like planets, respectively, and derived enhanced features due to absorption by atmospheric molecules such as CH₄, H₂O, and O₂. In fact, Sterzik et al. (2012) and Miles-Páez et al. (2014) clearly detected H₂O (at wavelengths 0.72, 0.82, 0.93, and 1.12 μm) and O₂ (0.69, 0.76, and 1.25 μm) features on the polarization spectra of lunar Earthshine. Hence, spectro-polarimetry for exoplanets can be used for the detection of these atmospheric molecules.

Spectro-polarimetry facilitates not only the detection of atmospheric molecules, but also further characterization of the atmosphere. Stam et al. (2004) and Stam (2008) showed that the polarization of planets is sensitive to the structure of the atmosphere. Stam et al. (2004) simulated three different model atmospheres of Jupiter-like planets: (1) an atmosphere that contains only gaseous molecules (“clear atmosphere”); (2) an atmosphere with a tropospheric cloud layer (“low cloud atmosphere”); and (3) an atmosphere with a tropospheric cloud layer and a stratospheric haze layer (“high haze atmosphere”). The resulting differences between the polarization spectra from the models were significant in overall wavelength-dependence and strength of the molecular features, whereas the differences in the intensity

spectra were less clear. Similarly, Stam (2008) pointed out that the degree of polarization at the continuum wavelengths near a molecular feature is more sensitive to the altitude of the cloud’s top compared with intensity. Therefore, spectro-polarimetry provides information that cannot be obtained solely by intensity spectroscopy.

In addition to these scientific benefits, polarimetry has some technical advantages. Because polarimetry is a relative measurement, the degree (and position angle) of polarization is not affected by isotropic transmittance between celestial objects and observers. This advantage will be especially effective for ground-based detection of H₂O, O₂, and other components common with the Earth’s atmosphere, if the telluric transmittance is isotropic.

The degree of polarization P of a planet is derived by the equation:

$$P(\lambda) = \frac{I_0^p(\lambda) - I_{90}^p(\lambda)}{I_0^p(\lambda) + I_{90}^p(\lambda)}, \quad (1)$$

where I_0^p and I_{90}^p represent planetary intensities of light oscillating perpendicular and parallel to the scattering plane (the plane which includes the central star, the planet, and the observer), respectively, and λ is the wavelength. If the instrumental reference plane is aligned to the scattering plane (using a half-wave plate), we have Stokes parameters $U = 0$ and $Q = P$, because scattering or reflected light is polarized perpendicular or parallel to the scattering plane. We take I_0^p and I_{90}^p as the values that are not altered by any absorption. When observations are conducted at the ground, intensities are affected by telluric transmittance.

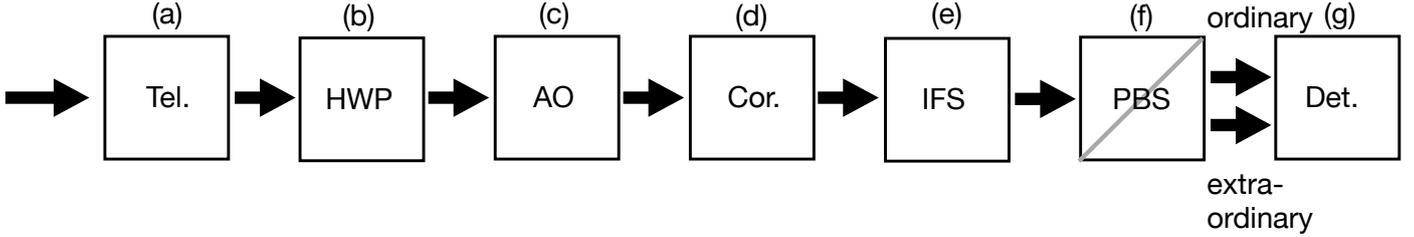


Fig. 1. Schematic illustration of the hypothetical observational system considered in this paper. It consists of **a**) a telescope; **b**) a half-wave plate; **c**) extreme adaptive optics; **d**) a coronagraph or a nulling interferometer; **e**) an integral field spectrograph; **f**) a polarizing beam splitter; and **g**) a detector.

Previously, it was believed that telluric transmittance was isotropic, and thus did not affect the polarization state of light from an astronomical object. However, [Bailey et al. \(2008\)](#) found that dust in the telluric atmosphere can produce polarization up to $\sim 5 \times 10^{-5}$. In addition, the polarization state is affected by interstellar transmittance, instrumental transmittance, and any offset error in the intensities. Therefore, we should express measured intensity values (I^P) as

$$\begin{pmatrix} I_{0}^P(\lambda) \\ I_{90}^P(\lambda) \end{pmatrix} = \begin{pmatrix} r_0(\lambda) \cdot I_0^p(\lambda) \\ r_{90}(\lambda) \cdot I_{90}^p(\lambda) \end{pmatrix} + \begin{pmatrix} \epsilon_0(\lambda) \\ \epsilon_{90}(\lambda) \end{pmatrix}, \quad (2)$$

$$r_\chi(\lambda) = \mathcal{S}_\chi(\lambda) \cdot \mathcal{T}_\chi(\lambda) \cdot k_\chi(\lambda) \quad (\chi = 0^\circ, 90^\circ), \quad (3)$$

where r_χ is the total efficiency from the object to the detector for ordinary ($\chi = 0^\circ$) or extraordinary ($\chi = 90^\circ$) components. It is the product of interstellar transmittance (\mathcal{S}_χ), telluric transmittance (\mathcal{T}_χ), and instrumental throughput including detector efficiency (k_χ). ϵ_χ is any offset error in the measurement of intensity values. In this paper, we examine how r_χ and ϵ_χ affect the measured degree of polarization.

In the 2020s, 30–40 m-class ground-based telescopes such as the Thirty-Meter Telescope (TMT), the European Extremely Large Telescope (E-ELT), and the Giant *Magellan* Telescope (GMT) will begin operation. Direct spectro-polarimetry or narrow-band imaging polarimetry for exoplanets is anticipated to be realized by a combination of high-contrast and polarimetric instruments on these extremely large telescopes (ELTs). Polarimetric differential imaging (PDI) is one of the highly effective techniques used to enhance the contrast range of an instrument and facilitate the detection of reflected light from planets around stars. PDI allows not only the detection of planets but also the measurement of polarization. PDI is widely utilized for currently operating instruments, such as HiCIAO (e.g., [Tamura et al. 2006](#); [Hashimoto et al. 2011](#); [Tanii et al. 2012](#)) on the Subaru telescope, and the SPHERE-ZIMPOL (e.g., [Thalmann et al. 2008, 2015](#)) and NACO (e.g., [Lenzen et al. 2003](#); [Rousset et al. 2003](#); [Garufi et al. 2013](#)) on the Very Large Telescopes (VLTs). A high-contrast direct-imaging polarimeter for exoplanets, EPICS-EPOL, is designed based on the ZIMPOL and is proposed for the E-ELT ([Kasper et al. 2010](#); [Keller et al. 2010](#)). Furthermore, a concept of the spectro-polarimetric option for EPICS-EPOL has also been studied ([Rodenhuis et al. 2012](#)). A spectro-polarimeter based on their concept will enable an effective suppression of the residual speckles by combining PDI with simultaneous spectral differential imaging (SSDI) or chromatic speckle suppression ([Marois et al. 2000](#); [Sparks & Ford 2002](#)). Therefore, at this point, it is important to assess the feasibility of polarimetry using a high-contrast spectro-polarimeter with SSDI and PDI techniques.

In this paper, we evaluate the feasibility of spectro-polarimetric characterization of exoplanetary atmospheres by

taking into account the errors expected in high-contrast instruments. As shown [Fig. 1](#), we consider a hypothetical spectro-polarimeter based on the concept proposed by [Rodenhuis et al. \(2012\)](#). The instrument shall be equipped with an integral field spectrograph (IFS) and a polarizing beam splitter (PBS) to obtain a polarization degree spectrum of a planet. Although the EPIS-EPOL is a visible light instrument, we assume that our instrument works in the near-infrared because we focus on the detection of the strongest spectro-polarimetric feature of H_2O at 1.12 μm on a visible-to-near-infrared spectrum ([Miles-Páez et al. 2014](#)). We assume that our instrument has a medium wavelength resolution R of a few thousand. Although our target spectral feature is relatively broad ($\Delta\lambda \cong 0.05 \mu\text{m}$, [Miles-Páez et al. 2014](#)), we follow the setting adopted by [Barman et al. \(2011\)](#) and [Konopacky et al. \(2013\)](#), who detected CH_4 and H_2O in exoplanet atmospheres by using the SSDI method for $R \sim 4000$ data.

We focus on H_2O vapor, which is a fundamental component in planetary atmospheres. H_2O plays a major role in meteorology and habitability of Earth and other Solar System planets. Detection of H_2O vapor has already been reported for several hot-Jupiters based on transit spectroscopy (e.g., [Barman 2007](#); [Tinetti et al. 2007](#); [McCullough et al. 2014](#)). However, transit spectroscopy is only possible for close-in planets. Direct observations can investigate planets in different orbital areas such as those near the habitable zone and the snow line. In addition, successful spectro-polarimetric searches for a H_2O feature will provide information on the structure of planetary atmospheres, such as cloud/haze height. Note that the framework we construct for H_2O detectability evaluation can easily be applied to other atmospheric species.

We discuss the detectability of the H_2O spectro-polarimetric feature with $\Delta P \equiv P(\lambda_{\text{abs}}) - P(\lambda_{\text{cnt}}) = 10\%$ and $P(\lambda_{\text{cnt}}) = 10\%$, where λ_{abs} and λ_{cnt} represent absorption and its nearby continuum wavelengths, respectively ($\lambda_{\text{abs}} = 1.12 \mu\text{m}$). These values are based on lunar Earthshine observations by [Miles-Páez et al. \(2014\)](#) with an approximate correction of depolarization at the lunar surface (Earth pol. \cong Earthshine pol. $\times 3$, [Dollfus 1957](#)). Although our target exoplanets include gas-giants, the setting above is justified for the following reasons; (1) H_2O vapor can be abundant if a planet is located within the snow line; and (2) as long as scattering of the atmosphere has a significant contribution to the total planetary intensity (i.e., clouds or hazes are not too high in altitude), a polarization degree spectrum of the planet is expected to have enhancement features at molecular absorption wavelengths ([Stam et al. 2004](#); [Stam 2008](#)).

This paper is organized as follows. In [Sect. 2](#), we formulate different types of errors in polarization degrees. Based on the derived equations, requirements for detection of a spectro-polarimetric feature are formulated and evaluated in [Sect. 3](#). Then, we examine the feasibility of spectro-polarimetric

searches for H₂O vapor in Sect. 4. After discussions on unconsidered error factors and remaining future works in Sect. 5, we summarize and conclude this paper in Sect. 6.

2. Formulation of errors

We consider three types of errors: (a) errors arising from the difference between the efficiencies (throughputs) of two orthogonally polarized states, b_p^{eff} ; (b) errors caused by speckle noises, σ_p^{spec} ; and (c) errors arising from photon noise, σ_p^{phot} . (a) and (b) are systematic biases, whereas (c) is a random error. Each type of error is formulated below by expanding Eq. (1). Note that, in this section, we do not write out wavelength dependence in functions so as to avoid complicating the equations.

2.1. Different efficiencies

We analyze the effect of the difference between r_0 and r_{90} . By substituting I^p in Eq. (2) into I^p in Eq. (1), the total error in the polarization degree is written as

$$\mathcal{E}_p \cong b_p^{\text{eff}} + \frac{(\epsilon_0 - \epsilon_{90}) - (P + b_p^{\text{eff}})(\epsilon_0 + \epsilon_{90})}{2\bar{r}\bar{I}^p}, \quad (4)$$

where

$$\begin{aligned} b_p^{\text{eff}} &\cong -\frac{1}{2} \left(\frac{r_{90}}{r_0} - 1 \right) (1 - P^2) \\ &\cong \left(\frac{\delta\mathcal{S}}{\bar{\mathcal{S}}} + \frac{\delta\mathcal{T}}{\bar{\mathcal{T}}} + \frac{\delta k}{\bar{k}} \right) (1 - P^2). \end{aligned} \quad (5)$$

The derivation of the equations is given in Appendix A, where $|\epsilon_\chi| \ll r_\chi I_\chi^p$ and $|r_{90}/r_0 - 1| \ll 1$ are assumed in the approximations. b_p^{eff} is the bias caused by different efficiencies as it is caused by r_{90}/r_0 . The barred values (e.g., \bar{r} , \bar{I}^p) satisfy $\bar{X} = (X_0 + X_{90})/2$ and δX (e.g., $\delta\mathcal{S}$, $\delta\mathcal{T}$) is defined by $\delta X = (X_0 - X_{90})/2$. The terms $\delta\mathcal{S}/\bar{\mathcal{S}}$, $\delta\mathcal{T}/\bar{\mathcal{T}}$, and $\delta k/\bar{k}$ are the polarization degrees through interstellar, telluric, and instrumental (including telescope) transmission, respectively. The difference of total efficiencies, $r_{90}/r_0 - 1$, can be written as the sum of the three individual polarization terms.

Keller (1996) analyzed the effect of nonlinearity in detector responses. Following his formulation, this effect is implemented into b_p^{eff} as

$$b_p^{\text{eff}} \cong \left(\frac{\delta\mathcal{S}}{\bar{\mathcal{S}}} + \frac{\delta\mathcal{T}}{\bar{\mathcal{T}}} + \frac{\delta k}{\bar{k}} \right) (1 - P^2) (1 + LI^p), \quad (6)$$

where LI^p is the nonlinearity term and has a typical value of ~ 0.01 (Keller 1996).

The second term in Eq. (4) is an error in P caused by offset errors in intensity measurement. It can be either systematic or random: it is systematic if ϵ_χ is systematic (e.g., due to speckle noises) and random if ϵ_χ is random (e.g., due to photon noise). Each type of error is analyzed below.

2.2. Speckle noises

In high-contrast instruments, stellar intensity is reduced with a coronagraph. Even with an extreme AO system, a certain roughness of wavefront cannot be corrected, and hence, the speckle noises are generated on an image plane. The speckle noises disturb the detection and measurement of planetary photons. In this

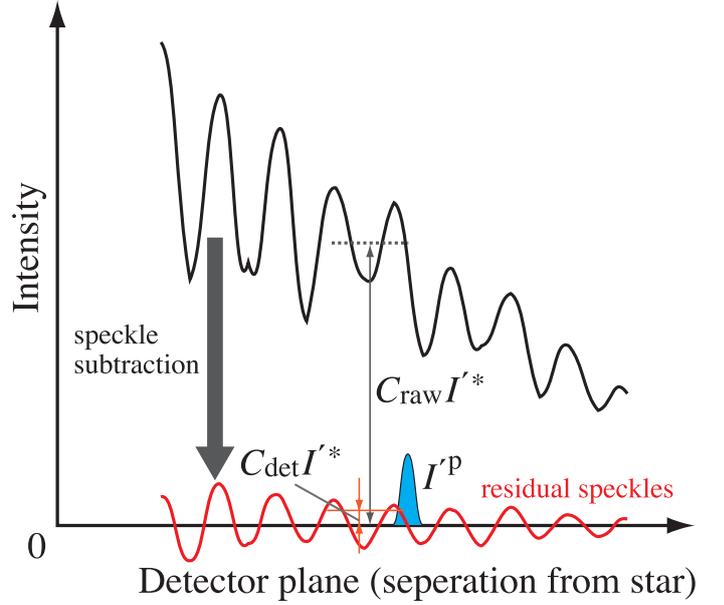


Fig. 2. Schematic illustration of an image profile before (upper line) and after (lower line) the speckle subtraction procedures. In the situation assumed for this paper, the speckle subtraction procedures include the SSDI but not the PDI at this stage. The PDI is conducted further on.

section, we examine the systematic bias in the planetary polarization degree due to the speckle noises.

We examine the second term of Eq. (4). In this paper, we consider a case where the PDI technique is applied after the SSDI procedure. The typical strength of ϵ_χ (speckle noises) after the SSDI but before PDI is $C_{\text{det}} I_\chi^*$ ($= C_{\text{det}} r_\chi I_\chi^*$), where C_{det} is the detection contrast of the instrument achieved with the SSDI but without the PDI. It describes the ratio of the strength of speckles to the non-coronagraphic stellar intensity, I_χ^* (see Fig. 2 for a schematic explanation and Appendix C for a more rigid description). Thus, we express

$$\sigma_{\epsilon_0 + \epsilon_{90}} \cong 2C_{\text{det}} \bar{r} \bar{I}^*, \quad (7)$$

$$\sigma_{\epsilon_0 - \epsilon_{90}} \cong g \cdot 2C_{\text{det}} \bar{r} \bar{I}^*, \quad (8)$$

where $\sigma_{\epsilon_0 + \epsilon_{90}}$ and $\sigma_{\epsilon_0 - \epsilon_{90}}$ represent the standard deviations of $(\epsilon_0 + \epsilon_{90})$ and $(\epsilon_0 - \epsilon_{90})$, respectively. Hence, $(\epsilon_0 + \epsilon_{90})$ and $(\epsilon_0 - \epsilon_{90})$ are typically within $\pm \sigma_{\epsilon_0 + \epsilon_{90}}$ and $\pm \sigma_{\epsilon_0 - \epsilon_{90}}$, respectively.

If both of the ordinary and extraordinary components of speckle noises have the same pattern and intensity, then we have $\epsilon_0 - \epsilon_{90} = 0$. However, it is not true due to, for example, different throughputs and wavefront errors for orthogonal polarized states; and polarization aberrations (deviation of the point-spread functions; Breckinridge & Oppenheimer 2004; Breckinridge et al. 2015). Besides, it is not known yet how well the PDI after SSDI works because a spectro-polarimeter based on the combination of an IFS and a PBS has not been realized. Thus, we introduce a parameter, g , which expresses how well the PDI suppresses the speckle noise. The detection contrast improves from C_{det} to gC_{det} by applying the PDI. We consider the best and worst cases with regard to g . In the best case, g is determined only by the difference in the throughputs, that is, $g = \delta r/\bar{r} \cong \delta k/\bar{k} \cong 0.05$. In the worst case, PDI does not work at all, that is, $g = 1.0$.

A typical value of the error caused by the speckle noise (σ_p^{spec}) is derived from the second term of Eq. (4) using Eqs. (7)–(8). If the spatial patterns of $(\epsilon_0 - \epsilon_{90})$ and $(\epsilon_0 + \epsilon_{90})$ are similar,

we have

$$\sigma_P^{\text{spec}} \cong \left| g - (P + b_P^{\text{eff}}) \right| \frac{C_{\text{det}}}{C_{\text{p/s}}}, \quad (9)$$

where $C_{\text{p/s}} = \bar{I}^{\text{p}}/\bar{I}^*$ is the intensity contrast of a planet to its host star. Contrarily, if $(\epsilon_0 - \epsilon_{90})$ and $(\epsilon_0 + \epsilon_{90})$ are not correlated, we should express

$$\sigma_P^{\text{spec}} \cong \sqrt{g^2 + (P + b_P^{\text{eff}})^2} \frac{C_{\text{det}}}{C_{\text{p/s}}}. \quad (10)$$

Because the highly correlated components between ϵ_0 and ϵ_{90} will largely disappear in $(\epsilon_0 - \epsilon_{90})$, we expect that Eq. (10) is the case.

σ_P^{spec} is a function of $C_{\text{det}}/C_{\text{p/s}}$. It is understandable that σ_P^{spec} is smaller when C_{det} is better (smaller) and $C_{\text{p/s}}$ (the planetary brightness relative to the star) is greater. When $g \gg P + b_P^{\text{eff}}$, we have $\sigma_P^{\text{spec}} \cong gC_{\text{det}}/C_{\text{p/s}}$. This means that we have a smaller σ_P^{spec} if we have a better (smaller) g , as expected. On the other hand, when $g \ll P + b_P^{\text{eff}}$, we have $\sigma_P^{\text{spec}} \cong (P + b_P^{\text{eff}})C_{\text{det}}/C_{\text{p/s}}$. This indicates that, even if the PDI were perfect ($g = 0$), P would suffer from an error caused by the speckles, because we need to use not only a differential ($I'_0 - I'_{90}$) image but also a sum ($I'_0 + I'_{90}$) image to derive P .

It may be puzzling that we have a larger error when the planet is more polarized. This is a result of the fact that the change of a P value due to virtually unpolarized speckle noises is greater when the planet is more polarized. Hence, most high-contrast polarimetry data is expressed in terms of polarized intensity, not degree of polarization. However, for ground-based spectro-polarimetric detection of H₂O (and other components common to Earth's atmosphere, e.g., O₂), avoidance of deriving the degree of polarization (i.e., dividing by the sum data) may pose a problem because one must cancel out telluric features using a standard star spectrum, which will be observed at a different time and sky position from the target. Therefore, we continue to study the errors in degree of polarization, rather than polarized intensity.

As we assume the scaling factor at the head of Eq. (10) ranges from the order of 10^{-1} to unity, $C_{\text{det}}/C_{\text{p/s}}$ should be less than the order of 10^{-1} to 10^{-2} so as to achieve a σ_P^{spec} of a few percent.

2.3. Photon noise

If ϵ_0 and ϵ_{90} in Eq. (2) are caused by photon noise and are thus random, the second term of Eq. (4) represents a random error (σ_P^{phot}) in P . We consider scattered starlight remaining after a coronagraph as the dominating source of the photon noise. As the intensity of scattered starlight is $C_{\text{raw}}\bar{r}\bar{I}^*$, we have

$$\sigma_{\epsilon_0 + \epsilon_{90}} \cong \sigma_{\epsilon_0 - \epsilon_{90}} \cong \sqrt{2C_{\text{raw}}\bar{r}\bar{I}^*}. \quad (11)$$

Hence,

$$\begin{aligned} \sigma_P^{\text{phot}} &\cong \frac{\sqrt{2\left(1 + (P + b_P^{\text{eff}})^2\right)C_{\text{raw}}\bar{r}\bar{I}^*}}{2\bar{r}\bar{I}^{\text{p}}} \cong \frac{\sqrt{2C_{\text{raw}}\bar{r}\bar{I}^*}}{2\bar{r}\bar{I}^{\text{p}}} \\ &= \frac{1}{\sqrt{2}\bar{r}\bar{I}^*} \frac{\sqrt{C_{\text{raw}}}}{C_{\text{p/s}}}, \end{aligned} \quad (12)$$

where \bar{I}^* is expressed in photon numbers. Naturally, the error from photon noise is smaller when the host star is brighter (\bar{I}^* is greater), the planet is brighter ($C_{\text{p/s}}$ is greater), and the instrument raw contrast is better (C_{raw} is less).

2.4. Summary of error formulations

In summary, the following types of errors in P are formulated:

- Error from different efficiencies

$$b_P^{\text{eff}} \cong \left(\frac{\delta\mathcal{S}}{\bar{\mathcal{S}}} + \frac{\delta\mathcal{T}}{\bar{\mathcal{T}}} + \frac{\delta k}{\bar{k}} \right) (1 - P^2) (1 + LI^{\text{p}}). \quad (13)$$

- Error from speckle noises

$$\sigma_P^{\text{spec}} \cong \sqrt{g^2 + (P + b_P^{\text{eff}})^2} \frac{C_{\text{det}}}{C_{\text{p/s}}}. \quad (14)$$

- Error from photon noise

$$\sigma_P^{\text{phot}} \cong \frac{1}{\sqrt{2}\bar{r}\bar{I}^*} \frac{\sqrt{C_{\text{raw}}}}{C_{\text{p/s}}}. \quad (15)$$

3. Requirements for detecting a spectro-polarimetric feature

In this section, requirements for detecting a spectro-polarimetric feature are formulated based on the derived equations for b_P^{eff} , σ_P^{spec} , and σ_P^{phot} (Eqs. (13)–(15)). Then, we calculate these errors to obtain the requirements of the instruments.

3.1. Different efficiencies

A b_P^{eff} spectrum has a spurious feature at the absorption wavelength λ_{abs} , as described later. Therefore, the absolute strength of the spurious feature must be significantly smaller than that of the real feature on a P spectrum for its detection. In other expressions, the following requirement should be satisfied:

$$|\Delta b_P^{\text{eff}}| \equiv |b_P^{\text{eff}}(\lambda_{\text{abs}}) - b_P^{\text{eff}}(\lambda_{\text{cnt}})| < w\Delta P, \quad (16)$$

where $\Delta P (\equiv P(\lambda_{\text{abs}}) - P(\lambda_{\text{cnt}}))$ is the polarization degree of the feature and w is a coefficient determined by the detection definition. w is set to 1/3 throughout the paper.

We verify that the b_P^{eff} spectrum has a feature at λ_{abs} by examining the three factors in Eq. (13). The following properties are found:

- The first factor, $(\delta\mathcal{S}/\bar{\mathcal{S}} + \delta\mathcal{T}/\bar{\mathcal{T}} + \delta k/\bar{k})$, is presumably featureless. The reasons are given in the following paragraph.
- The second factor, $(1 - P^2)$, has a feature if the P spectrum has a real feature. If P does not have a feature, neither does $(1 - P^2)$, which is quite evident.
- The third factor, $(1 + LI^{\text{p}})$, has a feature, even if I^{p} (and thus P) does not have a feature. This is because the detector nonlinearity term, LI^{p} , is proportional to $I^{\text{p}} (= \bar{\mathcal{S}}\bar{\mathcal{T}}\bar{k}\bar{I}^{\text{p}})$ and telluric transmittance, $\bar{\mathcal{T}}$, always has an H₂O absorption feature at λ_{abs} .

At the end, the spectrum of b_P^{eff} will have a spurious feature at λ_{abs} . Therefore, the requirement Eq. (16) must be satisfied.

We describe the reasons why $(\delta\mathcal{S}/\bar{\mathcal{S}} + \delta\mathcal{T}/\bar{\mathcal{T}} + \delta k/\bar{k})$ is presumed to be featureless by looking at each term separately. Although \mathcal{S} may have a weak feature at λ_{abs} , interstellar polarization $\delta\mathcal{S}/\bar{\mathcal{S}}$ does not have a feature at λ_{abs} because the polarization is caused by aligned dust particles and is not due to H₂O molecules (see P spectra of polarized standard stars, which are polarized through interstellar transmission, e.g., Fossati et al. 2007). \mathcal{T} has a strong feature at λ_{abs} . However, similar to the

Table 1. Input values to the calculations.

Parameter	Description	Values	References, notes
– Planet –			
$P(\lambda_{\text{cnt}})$	pol. deg. at continuum	0.1	Miles-Páez et al. (2014)
ΔP	pol. enhancement at feature (H ₂ O)	0.1	Miles-Páez et al. (2014)
λ_{abs}	absorption wavelength (H ₂ O)	1.12 μm	Miles-Páez et al. (2014)
$\Delta\lambda$	wavelength width of feature (H ₂ O)	0.05 μm	Miles-Páez et al. (2014)
$^\dagger p(\lambda_{\text{cnt}})$	geometric albedo	0.25	Montañés-Rodríguez et al. (2005)
$^\dagger \mu$	abs. strength, $[p(\lambda_{\text{cnt}}) - p(\lambda_{\text{abs}})]/p(\lambda_{\text{cnt}})$	0.5	Turnbull et al. (2006)
$^\dagger R_p$	planet radius	var	Exoplanet.eu [‡] or estimated from mass*
$^\dagger a_p$	orbital distance	var	Exoplanet.eu [‡]
$^\dagger \alpha$	phase angle	90°	
– Host star –			
m^*	stellar magnitude in <i>J</i> band (Fig. 4) (Table 2 and Fig. 6)	0, 5, 10 mag var	SIMBAD**
$^\dagger d$	distance from Earth	var	Exoplanet.eu [‡] or SIMBAD**
– Interstellar, telluric –			
$\delta S/\bar{S}$	interstellar polarization	0.01	
$\delta\mathcal{T}/\bar{\mathcal{T}}$	pol. through telluric transmission	5.0×10^{-5}	Bailey et al. (2008)
$\mathcal{T}(\lambda_{\text{abs}})$	telluric transmittance at λ_{abs}	0.7	Alt. ~3000 m. Based on GEMINI-S data [§] .
$\mathcal{T}(\lambda_{\text{cnt}})$	telluric transmittance at λ_{cnt}	0.99	Same as $\mathcal{T}(\lambda_{\text{abs}})$.
– Observation, instrument –			
Δt	integration time	15 h	
D	diameter of the telescope mirror	39 m	E-ELT
\bar{k}	averaged efficiency: $(k_0 + k_{90})/2$	0.1	EPOL goal, Keller et al. (2010)
$\delta k/\bar{k}$	instrumental (inc. telescope) pol.	0.05	E-ELT, de Juan Ovelar et al. (2012)
$LI^{\text{P}}(\lambda_{\text{cnt}})$	detector nonlinearity term	0.01	Keller (1996)
$^\dagger C_{\text{raw}}$	inst. raw contrast	(see Fig. 6)	EPICS, Fig. 3 of Kasper et al. (2010)
$^\dagger C_{\text{det}}$	inst. detection contrast before PDI (1σ)	(see Fig. 6)	EPICS-IFS, Fig. 4 of Kasper et al. (2010)
w	detection criteria definition	1/3	

Notes. ^(†) Not used in the calculations for Figs. 3, 4, but used for Table 2 and Fig. 6. ^(‡) The Extrasolar Planets Encyclopaedia, <http://exoplanet.eu/>, Schneider et al. (2011). ^(*) Using the mass-radius relations in Weiss et al. (2013) and Weiss & Marcy (2014). See text for details. ^(**) <http://simbad.u-strasbg.fr/simbad/>, Wenger et al. (2000). ^(§) <http://www.gemini.edu/sciops/telescopes-and-sites/observing-condition-constraints/ir-transmission-spectra>, Lord (1992).

case of $\delta S/\bar{S}$, telluric polarization $\delta\mathcal{T}/\bar{\mathcal{T}}$ should be featureless at λ_{abs} because the polarization is produced by dust particles (Bailey et al. 2008). Since k is determined by optical elements, k and $\delta k/\bar{k}$ do not have a feature at λ_{abs} . Thus, we regard the spectrum of $(\delta S/\bar{S} + \delta\mathcal{T}/\bar{\mathcal{T}} + \delta k/\bar{k})$ as featureless.

The value of $|\Delta b_p^{\text{eff}}|$ is calculated using Eq. (13) and the values listed in Table 1. As a result, we obtain $|\Delta b_p^{\text{eff}}| \cong 2.2 \times 10^{-3}$, which satisfies the requirement of Eq. (16).

Here we address the $\delta S/\bar{S}$, $\delta\mathcal{T}/\bar{\mathcal{T}}$, and $\delta k/\bar{k}$ values, which are used for the calculation. All of them are wavelength-dependent. However, in order to simplify the calculation, we treat $\delta S/\bar{S}$, $\delta\mathcal{T}/\bar{\mathcal{T}}$, and $\delta k/\bar{k}$ as constants within a minimum wavelength range necessary to detect a feature, that is, the range between $\lambda_{\text{abs}} \pm \Delta\lambda$ ($\Delta\lambda$ is the FWHM of the feature, $\sim 0.05 \mu\text{m}$). This assumption is allowed because they are expected to be featureless, as described above.

The interstellar polarization ($\delta S/\bar{S}$) is set to be 1% as a safe assumption. Note that most strongly polarized standard stars, which are polarized through a relatively long (a few hundred parsec) interstellar path, have a polarization degree of one to a few percent (Whittet et al. 1992). As direct observation of exoplanets

is limited to relatively nearby systems (within ~ 30 pc), we expect that the interstellar polarization for many of the targets is likely to be lower than the assumed value. As for polarization through telluric transmission ($\delta\mathcal{T}/\bar{\mathcal{T}}$), we take a value 5.0×10^{-5} , measured by Bailey et al. (2008). We assume instrumental (including telescope) polarization ($\delta k/\bar{k}$) to be 5%, based on modeling for the E-ELT by de Juan Ovelar et al. (2012). We do not know the signatures (position angles of polarization) of $\delta S/\bar{S}$, $\delta\mathcal{T}/\bar{\mathcal{T}}$, and $\delta k/\bar{k}$, but assume all of them to be positive so as to maximize the value of their sum.

For the purpose of understanding how $|\Delta b_p^{\text{eff}}|$ is determined, it is written as

$$\begin{aligned}
 |\Delta b_p^{\text{eff}}| &\cong |\delta S/\bar{S} + \delta\mathcal{T}/\bar{\mathcal{T}} + \delta k/\bar{k}| \\
 &\quad \times \left| (1 - P(\lambda_{\text{cnt}})^2) (\Delta[LI^{\text{P}}]) - (1 + LI^{\text{P}}(\lambda_{\text{cnt}})) \Delta[P^2] \right| \\
 &\cong |\delta S/\bar{S} + \delta\mathcal{T}/\bar{\mathcal{T}} + \delta k/\bar{k}| \times |\Delta[LI^{\text{P}}] - \Delta[P^2]| \\
 &\cong |0.01 + 5.0 \times 10^{-5} + 0.05| \times |-0.0065 - 0.03|, \quad (17)
 \end{aligned}$$

where $\Delta[X]$ represents $X(\lambda_{\text{abs}}) - X(\lambda_{\text{cnt}})$. It is seen that the contribution from $\delta\mathcal{T}/\bar{\mathcal{T}}$ is negligible. We also find that the ratio of contributions from the LI^{P} and P is approximately 1:5.

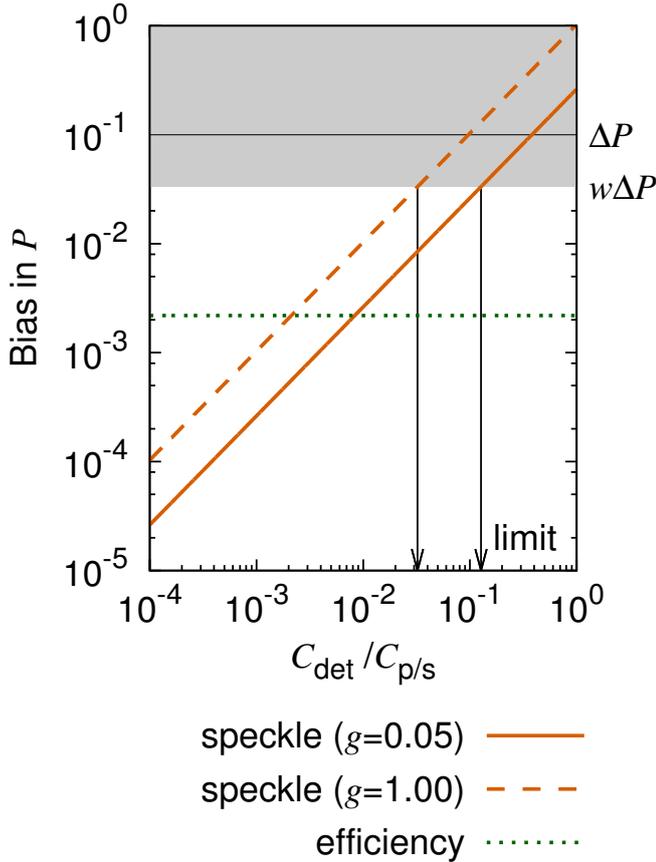


Fig. 3. Bias in P with respect to $C_{\text{det}}/C_{\text{p/s}}(\lambda_{\text{abs}})$. The speckle error $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ for $g = 0.05$ (solid line) and $g = 1.0$ (dashed line) are plotted. The efficiency error $|\Delta b_P^{\text{eff}}|$ (dotted line) is also shown. The shaded areas show where detection is difficult because the bias is larger than $w\Delta P$. The arrows point to the maximum limit of $C_{\text{det}}/C_{\text{p/s}}(\lambda_{\text{abs}})$ for the feature detection. w is set to one third.

3.2. Speckle noises

Speckles move outward from the host star on an image plane as the wavelength increases (see Fig. 23 in Sparks & Ford 2002), whereas the position of a planet image is independent of the wavelength. The SSDI technique removes the speckles using this property; however, some residuals will remain. Because the speckles “cross” a planet on a space of the separation (θ) and the wavelength (λ); see Fig. 2 in Rodenhuis et al. 2012), they will appear as spurious features on the I^{P} and P spectra. It is difficult to distinguish the spurious speckle features from the real molecular feature based on their spectral widths (see Appendix B). Therefore, it must be guaranteed that the strength of the speckle features on the P spectrum is sufficiently small compared to that of the real feature, ΔP .

Unlike the efficiency error, b_P^{eff} , we only know the standard deviation of the speckle error, σ_P^{spec} . Thus, we need to define the detection requirement differently: both $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ and $\sigma_P^{\text{spec}}(\lambda_{\text{cnt}})$ must be significantly smaller than ΔP . Owing to a greater P and a smaller $C_{\text{p/s}}$ at λ_{abs} than those at λ_{cnt} , it is expected that $\sigma_P^{\text{spec}}(\lambda_{\text{abs}}) > \sigma_P^{\text{spec}}(\lambda_{\text{cnt}})$, assuming Eq. (16) is satisfied (see Eq. (14)). Hence, the requirement regarding b_P^{spec} is expressed as

$$\sigma_P^{\text{spec}}(\lambda_{\text{abs}}) < w\Delta P. \quad (18)$$

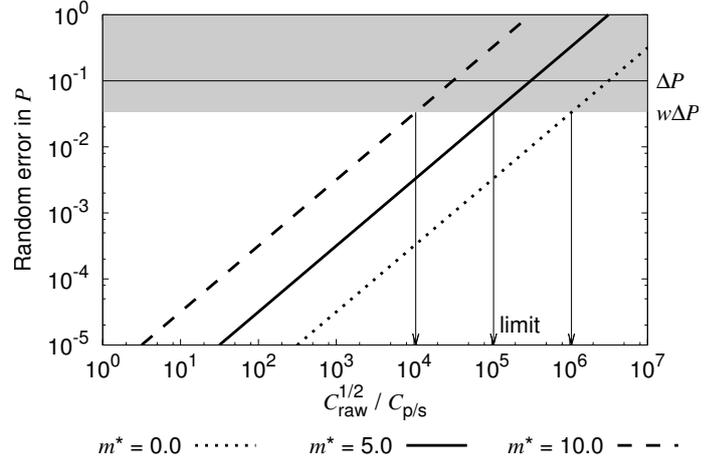


Fig. 4. $\sigma_P^{\text{phot}}(\lambda_{\text{abs}})$ with respect to $\sqrt{C_{\text{raw}}}/C_{\text{p/s}}(\lambda_{\text{abs}})$ for different stellar magnitudes: $m^* = 0.0$ (dotted line), 5.0 (solid line), 10.0 (dashed line). Magnitude m^* determines \bar{I}_χ^* in Eq. (15). The shaded area shows where detection is difficult because σ_P^{phot} is larger than $w\Delta P$. The arrows point to the maximum limit of $\sqrt{C_{\text{raw}}}/C_{\text{p/s}}(\lambda_{\text{abs}})$ for detection. w is set to one third.

Using Eq. (14), the values of $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ are calculated as a function of $C_{\text{det}}/C_{\text{p/s}}(\lambda_{\text{abs}})$. As described, we consider two cases with regard to g : $g = 0.05$ as the best case and $g = 1.0$ as the worst. All the other input values are given in Table 1.

Figure 3 displays $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ together with $|\Delta b_P^{\text{eff}}|$. As shown in Eq. (14), $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ is linearly correlated to $C_{\text{det}}/C_{\text{p/s}}(\lambda_{\text{abs}})$. For the best case ($g = 0.05$), C_{det} should be better than $\sim 1.3 \times 10^{-1} C_{\text{p/s}}(\lambda_{\text{abs}})$, which means that a contrast performance (before PDI) to achieve ~ 8 -sigma detection of the planet signal is required. For the worst case ($g = 1.0$), C_{det} should be better than $\sim 3.2 \times 10^{-2} C_{\text{p/s}}(\lambda_{\text{abs}})$, meaning a requirement of ~ 30 -sigma detection performance. Naturally, the requirement for C_{det} is less strict for the case of a better g .

The detectability is limited by the speckle error $\sigma_P^{\text{spec}}(\lambda_{\text{abs}})$ rather than the efficiency error $|\Delta b_P^{\text{eff}}|$ because $|\Delta b_P^{\text{eff}}|$ is small enough compared to ΔP . Thus, hereafter, the requirement pertaining to the efficiency error (Eq. (16)) is neglected in the evaluation of the detectability, though b_P^{eff} in Eq. (14) is still taken into account.

3.3. photon noise

The error due to photon noise σ_P^{phot} should be smaller than ΔP both at λ_{cnt} and λ_{abs} . Because of the smaller $\bar{r}\bar{I}^*$ and $C_{\text{p/s}}$ at λ_{abs} than at λ_{cnt} , we have $\sigma_P^{\text{phot}}(\lambda_{\text{abs}}) > \sigma_P^{\text{phot}}(\lambda_{\text{cnt}})$. Thus, the requirement regarding the photon noise is written as

$$\sigma_P^{\text{phot}}(\lambda_{\text{abs}}) < w\Delta P. \quad (19)$$

Using Eq. (15), the values of $\sigma_P^{\text{phot}}(\lambda_{\text{abs}})$ are calculated as a function of $\sqrt{C_{\text{raw}}}/C_{\text{p/s}}(\lambda_{\text{abs}})$ for stellar magnitudes $m^* = 0.0$, 5.0 , and 10.0 (Fig. 4). Telescope diameter $D = 39$ m (E-ELT) and total integration time $\Delta t = 15$ h (5 h \times 3 nights) are taken to derive the stellar photon counts $2\bar{r}\bar{I}^*$. The other settings are summarized in Table 1.

As seen in Fig. 4, for a host star of magnitude $m^* = 5.0$, $\sqrt{C_{\text{raw}}}/C_{\text{p/s}}(\lambda_{\text{abs}})$ should be smaller than $\sim 1 \times 10^5$. In other words, C_{raw} should be smaller than $\sim 1 \times 10^{10} (C_{\text{p/s}}(\lambda_{\text{abs}}))^2$. As might be

expected, the requirement for C_{raw} is less strict if the host star is brighter.

4. Evaluation of feasibility

4.1. Expected number of observable planets

We discuss the feasibility of spectro-polarimetry through estimating the number of planets for which a H_2O feature with $P(\lambda_{\text{cnt}}) = 10\%$ and $\Delta P = 10\%$ is detectable. The detectability is estimated according to Eqs. (18) and (19) by calculating $\sigma_p^{\text{spec}}(\lambda_{\text{abs}})$ and $\sigma_p^{\text{phot}}(\lambda_{\text{abs}})$ for the 2041 discovered planets listed in the Exoplanet.eu (the Extrasolar Planets Encyclopaedia, Schneider et al. 2011) database as of January 7, 2016. Assuming we use the E-ELT at Cerro Armazones, Chile, we exclude objects with declination $> +35^\circ$.

In Eq. (15) C_{raw} is taken from the values delivered by the AO system (called XAO) for EPICS, a planned direct observing instrument for exoplanets (Fig. 3 in Kasper et al. 2010). We choose EPICS-IFS as the reference of C_{det} in Eq. (14) (Fig. 4 in Kasper et al. 2010), because: (1) it is actually being studied for the E-ELT; (2) it covers the $\lambda_{\text{abs}} (= 1.12 \mu\text{m})$; and (3) its C_{det} can be applied directly to our formulae because the values without the PDI procedure are provided in Kasper et al. (2010). Note that EPICS-IFS itself will not have a spectro-polarimetry capability. We consider a hypothetical spectro-polarimeter with a contrast performance (before PDI) comparable to that of EPICS-IFS. The C_{det} values of EPICS-IFS are converted from 5-sigma to 1-sigma values to fit our formulation because we use an external parameter w to define the criteria of the detection.

In Eqs. (14) and (15), $C_{p/s}$ for each planet is calculated by

$$C_{p/s}(\lambda) = p(\lambda) \Phi_\alpha \left[\frac{R_p}{a_p} \right]^2 = p(\lambda) \Phi_\alpha \left[\frac{R_p}{d \tan(\theta_p)} \right]^2, \quad (20)$$

$$\Phi_\alpha = [\sin(\alpha) + (\pi - \alpha) \cos(\alpha)] / \pi, \quad (21)$$

where $p(\lambda)$ is the geometric albedo of a planet at wavelength λ , Φ_α is the phase law at phase angle α for a Lambert sphere, R_p is the planet radius, a_p is the distance from the host star to the planet, and d is the distance to the star from an observer (Traub & Oppenheimer 2010). $p(\lambda)$ and α are fixed for all the planets (Table 1). R_p , a_p (assumed to be close to the semi-major axis), and d is obtained primarily from the Exoplanet.eu database. If d is not available, we transform it from the parallax data in the SIMBAD database (Wenger et al. 2000). If R_p is not found in the Exoplanet.eu database, we predict it based on the empirical mass-radius relations studied by Weiss et al. (2013) and Weiss & Marcy (2014), where the planet mass (M_p) is acquired from the Exoplanet.eu. Different relations are applicable, depending on the different ranges of the planet mass (M_p): (1) $M_p > 150 M_{\text{Earth}}$; (2) $10 M_{\text{Earth}} < M_p \leq 150 M_{\text{Earth}}$ (Weiss et al. 2013); (3) $4 M_{\text{Earth}} < M_p \leq 10 M_{\text{Earth}}$, and (4) $M_p < 4 M_{\text{Earth}}$ (Weiss & Marcy 2014). Weiss et al. (2013) show that the radius is weakly (exponents -0.03 or 0.094) correlated with the incident stellar flux on the planet for the M_p ranges of (1) and (2). The time-averaged incident flux is calculated using the stellar effective temperature, the stellar radius, the semi-major axis, and the orbital eccentricity, which are retrieved primarily from the Exoplanet.eu database. If the eccentricity is not provided in the database, it is assumed to be zero. If either the stellar temperature or radius is not in the database, we use the mean flux in Weiss et al. (2013; $8.6 \times 10^8 \text{ erg s}^{-1} \text{ cm}^{-2}$).

The SIMBAD database (Wenger et al. 2000) is used for the reference of the J -band magnitudes (m^*) of the host stars, which

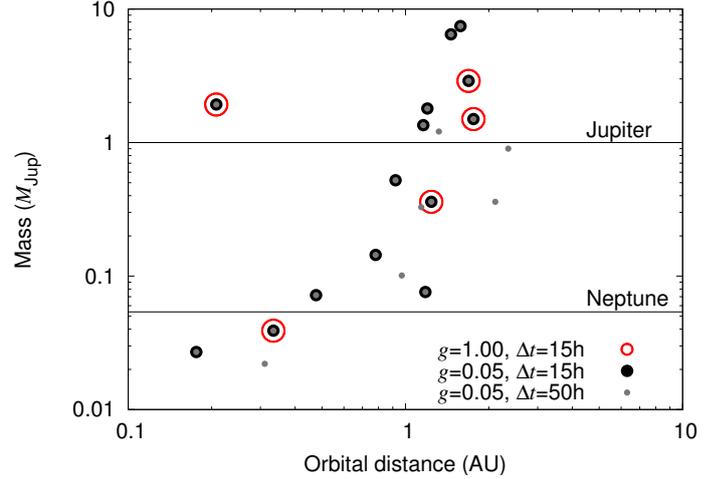


Fig. 5. Mass and orbital distances of the observable planets. The open circles are planets observable with a setting of $g = 1.0$ and $\Delta t = 15$ h. The filled larger circles are those with a setting of $g = 0.05$ and $\Delta t = 15$ h. The filled smaller circles are those with a setting of $g = 0.05$ and $\Delta t = 50$ h.

determine $\bar{I}_\lambda^*(\lambda_{\text{abs}})$ in Eq. (15). All the other fixed input values to the calculations are shown in Table 1.

Table 2 lists the planets for which we predict the spectro-polarimetric detection of the H_2O feature is possible with the setting $g = 0.05$. We have extracted 14 planets, of which 11 are estimated to be located within the snow line. The snow line distance is calculated according to Eq. (17) in Ida & Lin (2005). Among the 14 observable planets with $g = 0.05$, five planets are observable even with $g = 1.0$. Figure 5 shows the mass and orbital distances of the observable planets. The mass of the planets range from $7.5 M_{\text{Jup}}$ (HD 60532 c) to $0.027 M_{\text{Jup}} \cong 0.5 M_{\text{Nep}}$ (GJ 682 c).

In order to illustrate our results graphically, we transform the expressions for the detection requirements (Eqs. (18) and (19)) into suitable forms:

$$\frac{1}{w} \sqrt{g^2 + (P(\lambda_{\text{abs}}) + b_p^{\text{eff}}(\lambda_{\text{abs}}))^2} C_{\text{det}} < \Delta P C_{p/s}(\lambda_{\text{abs}}), \quad (22)$$

$$\frac{1}{w} \frac{1}{\sqrt{2F(\lambda_{\text{abs}}) \bar{I}_\lambda^*(\lambda_{\text{abs}})}} \sqrt{C_{\text{raw}}} < \Delta P C_{p/s}(\lambda_{\text{abs}}). \quad (23)$$

The right-hand side of the inequations above is interpreted as the contrast of the spectro-polarimetric feature signals to the host star signals. The left hand side of Eqs. (22) and (23) are contrast performances for the feature detection, constrained by the speckle noises and the photon noise, respectively.

In Fig. 6, we plot the (i) speckle-limited contrast (the left-hand side of Eq. (22)); (ii) photon-limited contrast (the left-hand side of Eq. (23)); and (iii) spectro-polarimetric feature contrast ($\Delta P C_{p/s}$) against the separation from the star. When both lines for (i) and (ii) are below (iii) in the figure, the feature is detectable. Four different cases are shown: (a) a “typical” planet with averaged properties of the observable planets with $g = 1.0$; (b) same as (a) except for $g = 0.05$. (c) Gliese 876 b with $g = 1.0$; and (d) Gliese 876 b with $g = 0.05$. Except for (a), detectability is determined by the photon-limited contrast for a certain θ range. Thus, the detectability can be improved by obtaining more photons (e.g., with a longer Δt or a better \bar{k}). In fact, if we extend

Table 2. List of planets for which spectro-polarimetric detection of H₂O vapor is possible with $g = 0.05$.

Planet	$m^*(J)$ (mag)	d (pc)	Sp. type	M_p (M_{Jup})	R_p^\dagger (10^4 km)	θ_p ($''$)	a_p (AU)	SL ‡	σ_P^{phot} (%)	$\frac{\Delta P}{\sigma_P^{\text{phot}}}$	σ_P^{spec} (%)	$\frac{\Delta P}{\sigma_P^{\text{spec}}}$
55 Cnc f	4.6	12.3	K0IV-V	1.4E-01	5.6 (2)	0.06	0.78	in	1.9	5	1.3	8
61 Vir d	3.3	8.5	G5V	7.2E-02	3.8 (2)	0.06	0.48	in	1.0	10	1.6	6
Aldebaran b	-2.1	20.4	K5III	6.5E+00	7.3 (1)	0.07	1.46	in	0.2	62	1.6	6
GJ 682 c	6.5	5.1	M3.5V	2.7E-02	2.3 (3)	0.04	0.18	in	2.9	4	2.3	4
§ Gliese 876 b	5.9	4.7	M4V	1.9E+00	4.1 (1)	0.04	0.21	in	0.7	15	0.6	18
§ Gliese 876 e	5.9	4.7	M4V	3.9E-02	3.0 (2)	0.07	0.33	out	2.0	5	0.5	19
§ HD 113538 b	6.4	15.8	K9V	3.6E-01	9.9 (2)	0.08	1.24	out	2.9	3	0.5	20
§ HD 176051 b	3.9	15.0		1.5E+00	8.5 (1)	0.12	1.76	?	1.7	6	0.8	13
HD 192310 c	4.1	8.8	K3V	7.6E-02	4.2 (2)	0.13	1.18	in	3.2	3	1.0	10
HD 27442 b	2.6	18.1	K2IVa	1.4E+00	6.0 (1)	0.06	1.16	in	1.4	7	2.3	4
HD 60532 c	3.7	25.7	F6IV-V	7.5E+00	8.0 (1)	0.06	1.58	in	2.6	4	3.0	3
§ HD 62509 b	-0.5	10.3	K0IIIb	2.9E+00	5.7 (1)	0.16	1.69	in	0.4	28	0.8	12
α Ari b	0.1	20.2	K2III	1.8E+00	6.7 (1)	0.06	1.20	in	0.4	24	2.7	4
μ Ara d	4.2	15.3	G3IV-V	5.2E-01	5.1 (1)	0.06	0.92	in	2.8	4	2.7	4
Average	3.5	13.2		1.8E+00	5.7	0.08	1.01		1.7	6	1.6	6
Summary	Total: 14		F:G:K:M = 1:2:7:3					in:out = 11:2				

Notes. § Planets that are also observable with $g = 1.0$. † The radii of all the listed planets are predicted from the mass. The figures in the parentheses represent the methods to estimate R_p : (1) adopts the mass-radius relation for $M_p > 150 M_{\text{Earth}}$ ($0.47 M_{\text{Jup}}$); (2) $10 M_{\text{Earth}}$ ($0.031 M_{\text{Jup}}$) $< M_p \leq 150 M_{\text{Earth}}$; and (3) $4 M_{\text{Earth}}$ ($0.013 M_{\text{Jup}}$) $< M_p \leq 10 M_{\text{Earth}}$. See text for details. ‡ This column describes whether the planet is located inside or outside the snow line. The snow line distance is estimated by Eq. (17) in [Ida & Lin \(2005\)](#).

Δt to 50 h (with $g = 0.05$), the number of observable planets increases to 20 (Fig. 5).

Note that we have extracted observable planets from the already known planets. Further, observable planets are not necessarily limited to those in Table 2, given that transit and radial velocity detection of exoplanets is biased toward edge-on systems, whereas direct observations can also find those in face-on systems.

4.2. Notes on some of the observable planets

Among the listed observable planets, Aldebaran b orbits the brightest star ($m^*(J) = -2.1$ mag). The existence of a planetary companion with a mass of $6.47 \pm 0.53 M_{\text{Jup}}$ is considered to be the most plausible explanation for the observed radial velocity (RV) variations with a 629-day period ([Hatzes et al. 2015](#)). Owing to the extreme brightness of the host star, σ_P^{phot} for the planet will be suppressed to a very low level ($\sim 0.2\%$). Aldebaran b, if it truly exists, may be one of the first targets for the spectro-polarimetry.

Gliese 876 (=GJ 876) is currently known to host four planets. Discoveries of planets “b” and “e” were made based on RV observations by [Delfosse et al. \(1998\)](#) and [Marcy et al. \(1998\)](#); and [Rivera et al. \(2010\)](#); respectively. It is expected that both of the planets can be observable even with $g = 1.0$. The contrast plot for Gliese 876 b is shown in Figs. 6c and d for $g = 1.0$ and 0.05, respectively. The orbital distance of the snow line in the system is evaluated to be 0.30 AU based on the mass of the host star ($0.334 M_{\odot}$). Fortunately, the orbital distance of planet “b” ($a_p = 0.21$ AU) is estimated to be within the snow line, whereas that of planet “e” (0.33 AU) is predicted to be beyond the line. Therefore, this system may be an optimal target to investigate the existence of H₂O vapor on planets inside and outside the snow line.

5. Discussions

5.1. Unconsidered factors

In this paper, we explore the feasibility of spectro-polarimetric detection of H₂O vapor on exoplanets by evaluating the P errors, which arise mainly from the efficiency differences between polarization states, speckle noises, and photon noise. In this section, some unconsidered factors are discussed.

Influences from the circumstellar disks were not discussed. [Min et al. \(2012\)](#) pointed out that the central resolution element on a disk image can be polarized because of scattering from the innermost regions of the disk. This makes the central star appear to have an intrinsic polarization. However, the polarization degree was calculated to be less than 0.1% for a spatial element obtained through 30–40 m telescopes ([Min et al. 2012](#)). As we have assumed much greater interstellar and instrumental polarization (several percent, Table 1), consideration of this effect will not change the result of our feasibility estimates.

As another influence from the disks, we consider exo-zodiacal light around a planet image. For low-spatial-resolution images, exo-zodiacal light may obscure a planet image. Simulations by [Cash et al. \(2008\)](#) showed that intensity of an Earth twin in a solar system twin at 10 pc was comparable to that of the surrounding exo-zodiacal light when observed through a 4.0 m diffraction-limited telescope (see their Fig. 1). However, as spatial resolution improves, a planetary image sharpens. When the same system is viewed through a 30–40 m telescope, intensity of the exo-zodiacal light per a spatial resolution element is approximately 50–100 times fainter than that of the Earth twin. Hence, we expect that this effect will not interfere with detection of a spectro-polarimetric feature with $\Delta P = 10\%$.

[Keller \(1996\)](#) mentioned the interference fringes due to multiple reflections between the retarder surfaces. Fringes on intensity spectra were observed at a level of 1×10^{-5} , which may lead

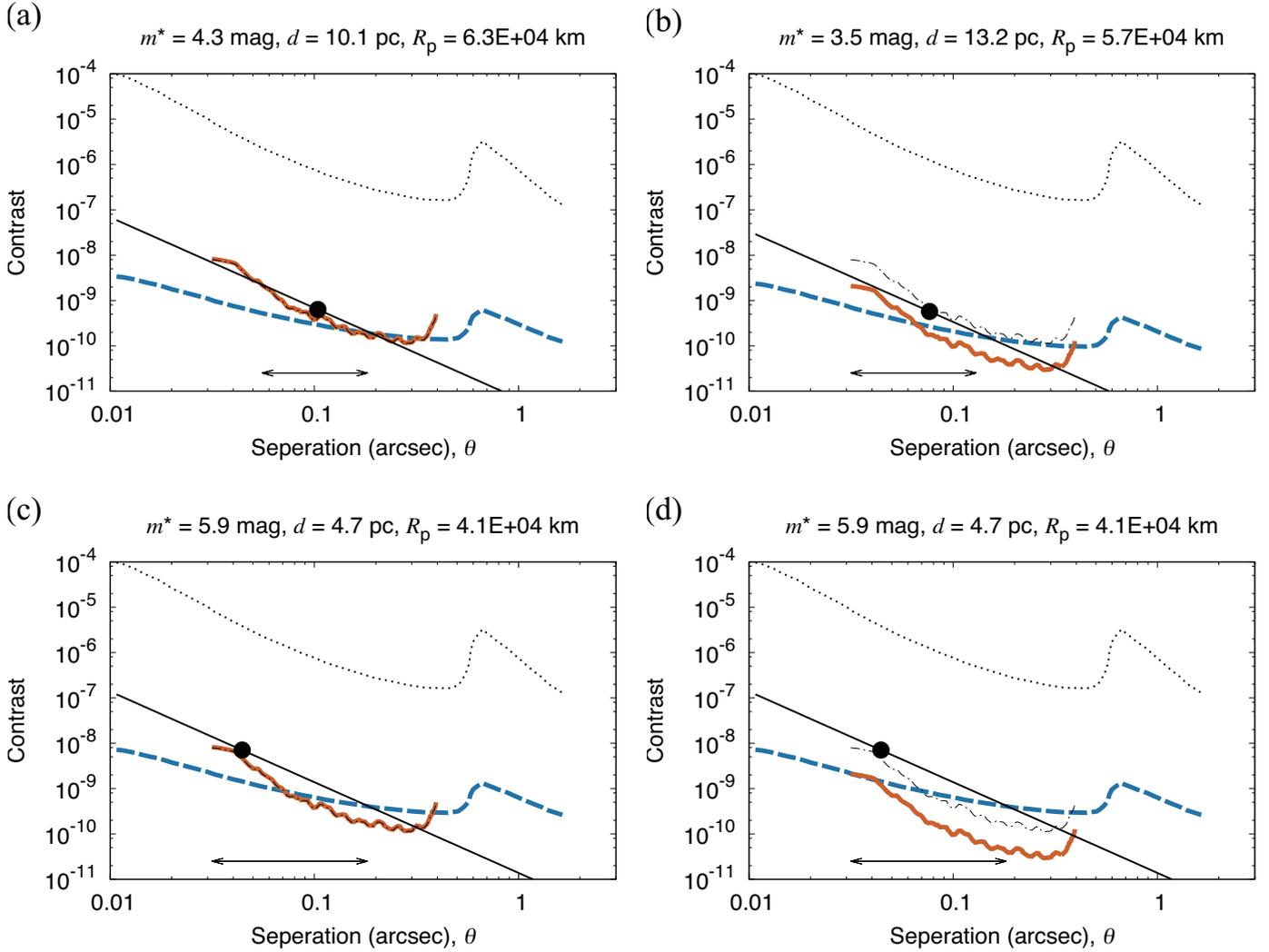


Fig. 6. Comparison of contrasts. Contrast performance limited by the speckle noises (bold solid lines) and by the photon noise (dashed lines) is compared with $\Delta P C_{p/s}$ (filled circles), that is, contrast of the polarized feature signal. **a)** a “typical” planet with averaged properties of the observable planets with $g = 1.0$. **b)** same as **a)** except for $g = 0.05$. **c)** Gliese 876 b with $g = 1.0$. **d)** Gliese 876 b with $g = 0.05$. The thin solid line in each panel is $\Delta P C_{p/s}(\theta)$ for a planet with the same radius. The polarization feature is detectable in the ranges of θ designated by the arrows. 3-sigma C_{det} (dashed-dotted lines) and C_{raw} (dotted lines) are also plotted for the reference.

to fringes on P spectra at a few times 10^{-5} . There are instrumental approaches and a data reduction method called the autoregressive model to reduce the fringes (Keller 1996). Although these approaches may not be perfect, we expect that the fringes will not pose a serious problem as long as the EPICS-IFS-like C_{det} is achieved as we assume, because the degree of the fringe errors is expected to be much smaller than ΔP (=10%).

5.2. Future works

Sophisticated data reduction techniques may suppress the systematic bias more efficiently. We have adopted Eq. (1) to derive P , which is the simplest way. For a dual beam polarimeter, however, there are two other approaches: the “difference” and “ratio” methods (Keller 1996; Bagnulo et al. 2009). These methods can be applied by obtaining two sets of ordinary and extraordinary images while switching the polarization states (rotating the position angle of polarization by 90°) with a half-wave plate or a ferroelectric liquid crystal. It is anticipated that better g will be achieved using these techniques. Evaluation of their effects is desirable but beyond the scope of this work.

Obviously, laboratory and on-sky experiments are required to confirm and refine our estimates. In particular, determination and examination of g is important. In this paper, we have parameterized g as the combination of many uncertain factors including difference between transmittances for orthogonally polarized states, polarization aberrations, and wavefront aberrations. Knowledge of the dependence of g on these factors will lead to minimization of g and enhancement of detection contrast through a combination of the SSDI and PDI techniques.

Despite the remaining future works, this study has provided a basic framework to evaluate the feasibility of spectro-polarimetric detection of atmospheric components and presented the instrumental requirements with regards to C_{raw} , C_{det} , g , and \bar{k} .

6. Summary and concluding remarks

Motivated by the scientific and technical benefits of spectro-polarimetry for the reflected light from exoplanets, the feasibility of the spectro-polarimetric search for H_2O vapor has been investigated. We formulated three types of errors in the measurement of the polarization degree: (a) b_p^{eff} , errors from different

efficiencies (throughputs from the light source to the detector) between ordinary and extraordinary light paths; (b) σ_p^{spec} , errors caused by speckle noises; and (c) σ_p^{phot} , errors caused by photon noise from the scattered starlight. Based on the derived equations, we have calculated the requirements for instrumental contrasts to detect the enhanced feature of H₂O at $\lambda_{\text{abs}} = 1.12 \mu\text{m}$ with $P(\lambda_{\text{cnt}}) = 10\%$ and $\Delta P = 10\%$. Furthermore, the number of observable planets was estimated, assuming availability of the E-ELT and a spectro-polarimeter with an EPICS-IFS-like contrast. The results show that 5 to 14 known planets are observable. Therefore, we remark that spectro-polarimetric characterization of exoplanetary atmospheres is feasible in principle at the coming age of ELTs. Since we have conducted simple analytical formulations, the framework we have developed will be easily adopted for feasibility evaluations with other settings, such as those using an instrument with a different contrast or a search for other molecular species.

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Appendix A: Derivation of Eqs. (4) and (5)

By substituting I'_χ in Eq. (2) into I_χ in Eq. (1), the polarization degree with errors is written as

$$\begin{aligned}
 P' &= \frac{I'_0 - I'_{90}}{I'_0 + I'_{90}} \\
 &= \frac{(r_0 I_0^p + \epsilon_0) - (r_{90} I_{90}^p + \epsilon_{90})}{(r_0 I_0^p + \epsilon_0) + (r_{90} I_{90}^p + \epsilon_{90})} \\
 &= \frac{(r_0 I_0^p - r_{90} I_{90}^p) + (\epsilon_0 - \epsilon_{90})}{(r_0 I_0^p + r_{90} I_{90}^p) + (\epsilon_0 + \epsilon_{90})} \\
 &= \frac{[rI^p]_- + \epsilon_-}{[rI^p]_+ + \epsilon_+} \\
 &= \left(\frac{[rI^p]_-}{[rI^p]_+} + \frac{\epsilon_-}{[rI^p]_+} \right) \left(1 + \frac{\epsilon_+}{[rI^p]_+} \right)^{-1} \\
 &\cong \left(\frac{[rI^p]_-}{[rI^p]_+} + \frac{\epsilon_-}{[rI^p]_+} \right) \left(1 - \frac{\epsilon_+}{[rI^p]_+} \right) \\
 &= \frac{[rI^p]_-}{[rI^p]_+} + \frac{\epsilon_-}{[rI^p]_+} - \frac{[rI^p]_-}{[rI^p]_+} \frac{\epsilon_+}{[rI^p]_+} - \frac{\epsilon_- \epsilon_+}{([rI^p]_+)^2} \\
 &\cong \frac{[rI^p]_-}{[rI^p]_+} + \frac{\epsilon_-}{[rI^p]_+} - \frac{[rI^p]_-}{[rI^p]_+} \frac{\epsilon_+}{[rI^p]_+}, \tag{A.1}
 \end{aligned}$$

where $|\epsilon_\chi| \ll r_\chi I_\chi^p$ is assumed in the approximations and the following replacements are used:

$$[rI^p]_+ \equiv r_0 I_0^p + r_{90} I_{90}^p \cong 2\bar{r} \bar{I}^p, \tag{A.2}$$

$$[rI^p]_- \equiv r_0 I_0^p - r_{90} I_{90}^p, \tag{A.3}$$

$$\epsilon_+ \equiv \epsilon_0 + \epsilon_{90}, \tag{A.4}$$

$$\epsilon_- \equiv \epsilon_0 - \epsilon_{90}. \tag{A.5}$$

We introduce the following parameters:

$$\rho \equiv r_{90}/r_0 - 1, \tag{A.6}$$

$$l \equiv I_{90}^p/I_0^p. \tag{A.7}$$

With them, we have

$$\begin{aligned}
 \frac{[rI^p]_-}{[rI^p]_+} &= \frac{1 - \frac{r_{90} I_{90}^p}{r_0 I_0^p}}{1 + \frac{r_{90} I_{90}^p}{r_0 I_0^p}} \\
 &= \frac{1 - (1 + \rho)l}{1 + (1 + \rho)l} \\
 &= (1 - l - \rho l)(1 + l + \rho l)^{-1} \\
 &= (1 - l - \rho l)(1 + l)^{-1} \left(1 + \frac{\rho l}{1 + l} \right)^{-1} \\
 &\cong (1 - l - \rho l)(1 + l)^{-1} \left(1 - \frac{\rho l}{1 + l} \right) \\
 &= (1 + l)^{-2} (1 - l - \rho l)(1 + l - \rho l) \\
 &= (1 + l)^{-2} [(1 - l)(1 + l) - 2\rho l + \rho^2 l^2] \\
 &\cong (1 + l)^{-2} [(1 - l)(1 + l) - 2\rho l] \\
 &= \frac{1 - l}{1 + l} - \frac{2\rho l}{(1 + l)^2} \\
 &= P - \frac{\rho(1 - P^2)}{2} \\
 &= P - \frac{1}{2} \left(\frac{r_{90}}{r_0} - 1 \right) (1 - P^2), \tag{A.8}
 \end{aligned}$$

where $\rho \ll 1$ is assumed in the approximations. In the last transformation,

$$P = \frac{1 - l}{1 + l}, \tag{A.9}$$

$$1 - P^2 = \frac{4l}{(1 + l)^2}, \tag{A.10}$$

are used. By substituting Eq. (A.8) into Eq. (A.1), we obtain

$$P' \cong P + b_P^{\text{eff}} + \frac{(\epsilon_0 - \epsilon_{90}) - (P + b_P^{\text{eff}})(\epsilon_0 + \epsilon_{90})}{2\bar{r}\bar{I}^p}, \tag{A.11}$$

where

$$b_P^{\text{eff}} \equiv -\frac{1}{2} \left(\frac{r_{90}}{r_0} - 1 \right) (1 - P^2). \tag{A.12}$$

The underlined part is the error in P , that is, \mathcal{E}_p . Since $r_\chi = \mathcal{S}_\chi \mathcal{T}_\chi k_\chi$, we have

$$\begin{aligned}
 \frac{r_{90}}{r_0} &= \frac{\mathcal{S}_{90} \mathcal{T}_{90} k_{90}}{\mathcal{S}_0 \mathcal{T}_0 k_0} \\
 &\cong \left(1 - \frac{2\delta\mathcal{S}}{\bar{\mathcal{S}}} \right) \left(1 - \frac{2\delta\mathcal{T}}{\bar{\mathcal{T}}} \right) \left(1 - \frac{2\delta k}{\bar{k}} \right) \\
 &\cong 1 - 2 \left(\frac{\delta\mathcal{S}}{\bar{\mathcal{S}}} + \frac{\delta\mathcal{T}}{\bar{\mathcal{T}}} + \frac{\delta k}{\bar{k}} \right). \tag{A.13}
 \end{aligned}$$

Thus, we can also write b_P^{eff} as

$$b_P^{\text{eff}} = \left(\frac{\delta\mathcal{S}}{\bar{\mathcal{S}}} + \frac{\delta\mathcal{T}}{\bar{\mathcal{T}}} + \frac{\delta k}{\bar{k}} \right) (1 - P^2). \tag{A.14}$$

Appendix B: Width of the spectral speckle features

The FWHM of a spectral speckle feature, which overlays the real feature on I^p and P spectra at λ_{abs} is

$$\Delta\lambda^{\text{spec}} = \frac{\Delta\theta}{\theta_p} \lambda_{\text{abs}}, \tag{B.1}$$

where $\Delta\theta$ is the FWHM of a point source image and θ_p is the separation of the planet from the star. Equation (B.1) shows that the width of the spectral speckle features becomes narrower as the planet is more distant from the star. In the case of the E-ELT (aperture diameter $D = 39$ m), we have $\Delta\theta \cong \lambda_{\text{abs}}/D \cong 0.006''$. When θ_p is taken as the inner working angle (IWA) of the EPICS-IFS, $0.03''$ (Kasper et al. 2010) for example, we have $\Delta\lambda^{\text{spec}} \cong 0.22 \mu\text{m}$, which is wide enough to be distinguished from the real feature with a FWHM ($\Delta\lambda$) of $\sim 0.05 \mu\text{m}$ (Miles-Páez et al. 2014). However, when θ_p is $0.1''$, $\Delta\lambda^{\text{spec}}$ is $\sim 0.07 \mu\text{m}$, which is comparable with $\Delta\lambda$. As long as the spectro-polarimeter has a minimum wavelength resolution to detect the real feature, we should perceive that, except for a planet near the IWA, the spurious spectral features by the speckles cannot be distinguished from the real feature based on the feature widths. Therefore, it must be guaranteed that the strength of the speckle features on the P spectrum is small enough compared to that of the real feature (ΔP).

Appendix C: Raw contrast and detection contrast

In this appendix, the raw contrast (C_{raw}) and the detection contrast (C_{det}) of a high-contrast instrument are explained and formulated using wavefront ripples of the electric field.

The intensity (equivalent to the number of photons per unit area per unit time) of speckle noises for an (extra)ordinary component varies with position (separation from the star θ and position angle ψ) and time t . Speckle noises arise from ripples of the electromagnetic wavefront. Extreme AO corrects the ripples to the extent $\phi \sim \frac{2\pi}{10}$ (or $\frac{\lambda}{10}$ in a length scale) or more, but cannot perfectly remove them. ϕ can be separated into random (ϕ_{rand}) and quasi-static (ϕ_{qst}) components. ϕ_{rand} is mainly caused by atmospheric turbulence and varies randomly on short time-scales of a few to ten milliseconds. ϕ_{qst} comes from optical imperfections of the instrument and evolves on time-scales of minutes to hours. ϕ_{qst} can be divided into two components: one from a telescope to a coronagraph (including the coronagraph; ϕ_{qst1}) and the other after the coronagraph (ϕ_{qst2} ; see Fig. 1).

We examine the stellar electric field immediately after the coronagraph, E_c . Here, we take a shearing interferometric nuller as a coronagraph for a simple analytical discussion, but the discussion below can be applied to other types of coronagraphs. In the nuller, incident light is separated into two rays $E_1 = Ae^{i\phi_1}$ and $E_2 = Ae^{i(\phi_2+\pi)}$, where A is a constant, and ϕ_1 and ϕ_2 are the phase perturbations, which are assumed to be small ($|\phi_1|, |\phi_2| \ll 1$). E_c can be written as

$$\begin{aligned} E_c &= E_1 + E_2 = Ae^{i\phi_1} - Ae^{i\phi_2} \\ &= Ae^{i\phi_1} (1 - e^{i(\phi_2-\phi_1)}) = Ae^{i\phi_1} (1 - e^{i\Delta\phi}) \\ &\cong A(1 + i\phi_1)(-i\Delta\phi) = A(-i\Delta\phi + \phi_1\Delta\phi) = A\phi_c, \end{aligned} \quad (\text{C.1})$$

where $\Delta\phi \equiv \phi_2 - \phi_1$. As for ϕ_c , we find

$$\phi_c \equiv -i\Delta\phi + \phi_1\Delta\phi \cong -i\Delta\phi = -i(\Delta\phi_{\text{rand}} + \Delta\phi_{\text{qst1}}), \quad (\text{C.2})$$

where we split $\Delta\phi$ into random ($\Delta\phi_{\text{rand}}$) and quasi-static ($\Delta\phi_{\text{ast1}}$) components. When the static perturbation ϕ_{qst2} is added to E_c , it becomes

$$\begin{aligned} E'_c &= E_c e^{i\phi_{\text{qst2}}} \cong A\phi_c(1 + i\phi_{\text{qst2}}) = A(\phi_c + i\phi_c\phi_{\text{qst2}}) \\ &\cong A\phi_c = -iA(\Delta\phi_{\text{rand}} + \Delta\phi_{\text{qst1}}). \end{aligned} \quad (\text{C.3})$$

Thus, ϕ_{qst2} is negligible. The electric field at the following image plane is

$$\begin{aligned} E_d &= \text{FT}(E'_c) = i\text{FT}(A) * \text{FT}(\Delta\phi_{\text{rand}} + \Delta\phi_{\text{qst1}}) \\ &= i\text{FT}(A) * [\text{FT}(\Delta\phi_{\text{rand}}) + \text{FT}(\Delta\phi_{\text{qst1}})], \end{aligned} \quad (\text{C.4})$$

where FT() represents the Fourier transform.

For an incident field $Ae^{i\phi}$, the ratio of speckle intensity to stellar intensity, or contrast C , is given by

$$C = \left(\frac{\pi h}{\lambda}\right)^2, \quad (\text{C.5})$$

where the peaks and valleys of the wavefront ripple have values (length) $\pm h$ (Traub & Oppenheimer 2010, Eq. (121)). The phase perturbation is described as

$$\phi(x) = a' \cos(2\pi x/x_0 + \alpha') + ib' \cos(2\pi x/x_0 + \beta'), \quad (\text{C.6})$$

where x is a position at the pupil plane and x_0 is a typical spatial period of the ripples. a' , α' , b' , and β' are constants with units of radians. a' is related to h by

$$a' = 2\pi h/\lambda. \quad (\text{C.7})$$

See Eqs. (108), (109) and the related text in Traub & Oppenheimer (2010) for more details.

In the case being studied, the raw contrast is

$$C_{\text{raw}} = \left(\frac{\pi \sqrt{h_{\text{rand}}^2 + h_{\text{qst1}}^2}}{\lambda}\right)^2 = \left(\frac{\pi h_{\text{rand}}}{\lambda}\right)^2 + \left(\frac{\pi h_{\text{qst1}}}{\lambda}\right)^2, \quad (\text{C.8})$$

where h_{rand} and h_{qst1} are h for $\Delta\phi_{\text{rand}}$ and $\Delta\phi_{\text{qst1}}$, respectively. As h_{qst1} can be suppressed greatly by a deformable mirror in the AO, it is safe to assume $h_{\text{rand}} \gg h_{\text{qst1}}$ in their typical values. Thus, we find

$$C_{\text{raw}} \cong \left(\frac{\pi h_{\text{rand}}}{\lambda}\right)^2. \quad (\text{C.9})$$

C_{raw} is a ratio of instantaneous intensities or photon rates. When we integrate photons on a detector for a certain duration Δt , the effective h_{rand} ($h_{\text{rand,e}}$) will be

$$h_{\text{rand,e}} = h_{\text{rand}} \sqrt{\frac{t_0}{\Delta t}}, \quad (\text{C.10})$$

where t_0 is a typical time-scale of $\Delta\phi_{\text{rand}}$, which is a few to ten milliseconds. With a sufficient Δt , $h_{\text{rand,e}}$ is much smaller than h_{qst1} (if $h_{\text{rand}} \sim 10^{-4}\lambda$ and $h_{\text{qst1}} \sim 10^{-6}\lambda$, then $h_{\text{rand,e}} < h_{\text{qst1}}$ for $\Delta t > 100$ s). The detection contrast C_{det} is defined as the contrast achieved with a sufficient Δt , which is

$$C_{\text{det}} = \left(\frac{\pi h_{\text{qst1}}}{\lambda}\right)^2. \quad (\text{C.11})$$

According to experiments by Trauger & Traub (2007), it is possible to reach $C_{\text{det}} = 10^{-10}$ in space. In this paper, C_{det} is referred from the values for a ground-based instrument EPICS-IFS Kasper et al. (2010; see our Fig. 6).